NAME: MAC-ETELI GOLDEN

MATRIC NUMBER: 16/ENG05/021

DEPARTMENT: MECHATRONICS

```
oc = cost + tsint
             4 = Sint - toost
     \frac{dx}{dt} = -\sin t + t\cos t + \sin t = t\cos t
            = cost +tsint - cost = tsint
    \frac{dy}{dz} = \frac{dy}{dz} \times \frac{dt}{dz} - \frac{\cancel{t} \cdot sint}{\cancel{t} \cdot cost} = tant
   \frac{d^2y}{dx^2} = \sec^2 t
                [ 1 + (dy/dx)2 73/2
                                                           [1+(\tan t)^2]^{\frac{3}{2}}
                        (d2y/dx2)
      h = 2 - RSin\theta
           K= y + R & 030
      tan o = dy

\Theta = \tan^{-1} \left[ \frac{dy}{dx} \right]

     from eqn () x = cost + t sint
from eqn (2) y = sint - t cost
     from question (*) R = [1 + (tant)^2]^{3/2}
                                            Sec2t
So h = (\cos t + t \sin t) - ((1 + (\tan t)^2)^{3/2}) \sin(\tan^{-1}(\tan t))
      x = (\sin t - t \cos t) + ((1 + (\tan t)^2)^{3/2}) \cos (\tan^{-1} (\tan t))
```