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Mechatronics Engineering

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ENG 281

$$1. P = \frac{E^2}{R}$$

$$E = 200 \text{ volts}$$

$$R = 8 \text{ ohms}$$

$$\delta E = -5 \text{ volts}$$

$$\delta R = 0.2 \text{ ohms}$$

Recall:

$$P = f(E, R)$$

$$\delta P = \frac{\delta P}{\delta E} \cdot \delta E + \frac{\delta P}{\delta R} \cdot \delta R$$

$$\frac{\delta P}{\delta E} = \frac{2E}{R} \quad , \quad \frac{\delta P}{\delta R} = -E^2 R^{-2} = \frac{-E^2}{R^2}$$

$$\frac{\delta P}{\delta R} = \frac{-200^2}{8^2} = \frac{-40000}{64} = -625$$

$$\therefore \delta P = \frac{2E}{R} \times \delta E + \left[\frac{-E^2}{R^2} \times \delta R \right]$$

$$\delta P = \left[\frac{2 \times 200}{8} \times -5 \right] + \left[\frac{-625 \times 0.2}{1} \right]$$

$$= [50 \times -5] + [-625 \times 0.2]$$

$$\delta P = -375 \text{ watts}$$

$$2. y = \frac{xw d^4}{t^3}$$

$$\frac{\delta y}{\delta w} = \frac{K d^4}{t^3}$$

$$\frac{\delta y}{\delta d} = \frac{4K w d^3}{t^3}$$

$$\frac{\delta y}{\delta t} = \frac{-3K w d^4}{t^4}$$

$$\delta y = \frac{\delta y}{\delta w} \cdot \delta w + \frac{\delta y}{\delta d} \cdot \delta d + \frac{\delta y}{\delta t} \cdot \delta t$$

$$= \left[\frac{K d^4}{t^3} \times \frac{3w}{100} \right] + \left[\frac{4K w d^3}{t^3} \times \frac{2.5d}{100} \right] + \left[\frac{-3K w d^4}{t^4} \times \frac{4t}{100} \right]$$

$$S_y = \left[\frac{k_w d^4}{t^3} \times \frac{3}{100} \right] + \left[\frac{k_w d^4}{t^3} \times \frac{(4 \times 2.5)}{100} \right] + \left[\frac{k_w d^4}{t^3} \times \frac{(4 \times 3)}{100} \right]$$

$$S_y = \frac{k_w d^4}{t^3} \left[\frac{3}{100} + \frac{10}{100} - \frac{12}{100} \right]$$

$$= \frac{k_w d^4}{t^3} \left[\frac{1}{100} \right]$$

where $y = \frac{k_w d^4}{t^3}$

$\therefore S_y = 1\%$ of y .