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COMPUTER ENGINEERING

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$$\textcircled{1} P = \frac{E^2}{R}$$

$$E = 200\text{V}, R = 8\Omega, \Delta E = -5\text{V}, \Delta R = 0.2\Omega$$

$$\Delta P = \frac{dP}{dE} \cdot \Delta E + \frac{dP}{dR} \cdot \Delta R$$

$$\frac{dP}{dE} = \frac{2E}{R} \quad \frac{dP}{dR} = \frac{-E^2}{R^2}$$

$$\Delta P = \frac{2(200)(-5)}{8} + \frac{-(200)^2 \cdot (0.2)}{8^2}$$

$$\Delta P = -250 - 125$$

$$\Delta P = -375\text{W}$$

Change in P is -375W

$$\textcircled{2} y = \frac{Kwd^4}{t^3}$$

$$\Delta W = \frac{3}{100} w$$

$$\Delta d = \frac{2.5}{100} d$$

$$\Delta t = \frac{4}{100} t$$

$$\frac{dy}{dw} = \frac{Kd^4}{t^3}$$

$$\frac{dy}{dd} = \frac{4Kwd^3}{t^3}$$

$$\frac{dy}{dt} = \frac{-3Kwd^4}{t^4}$$

$$\Delta y = \frac{dy}{dw} \cdot \Delta W + \frac{dy}{dd} \cdot \Delta d + \frac{dy}{dt} \cdot \Delta t$$

$$\Delta y = \frac{Kd^4}{t^3} \cdot \frac{3}{100} w + \frac{4Kwd^3}{t^3} \cdot \frac{2.5}{100} d - \frac{3Kwd^4}{t^4} \cdot \frac{4}{100}$$

$$\Delta y = \frac{Kwd^4}{t^3} \cdot \frac{3}{100} + \frac{Kwd^4}{t^3} \cdot \frac{(2.5) \cdot 4}{100} - \frac{Kwd^4}{t^3} \cdot \frac{12}{100}$$

$$\Delta y = \frac{Kwd^4}{t^3} \left(\frac{3}{100} + \frac{10}{100} - \frac{12}{100} \right)$$

$$\Delta y = \frac{k w d^4}{t^3} \left(\frac{1}{100} \right)$$

$$y = \frac{k w d^4}{t^3}$$

$$\therefore \Delta y = \frac{1}{100} y = 1\% y$$

Change in $y = \pm 1\%$