

HABIB AHMAD ANAKI

15/ENGG04/027

MECHATRONICS

1. (i) $\frac{d^2y}{d\theta^2} + 4\frac{dy}{d\theta} + 5y = 6\sin\theta$

$$y'' + 4y' + 5y = 6\sin\theta$$

$$k^2 + 4k + 5 = 0$$

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a} = \frac{-4 \pm \sqrt{4^2 - 4 \times 1 \times 5}}{2 \times 1} = \frac{-4 \pm \sqrt{-4}}{2}$$

$$= \frac{-4 \pm 2i}{2}, -2 \pm i$$

$$k_1 = -2 + i, k_2 = -2 - i$$

$$y = C_1 y_1 + C_2 y_2$$

$$y_p = C_1 \cos 2\theta + C_2 \sin 2\theta$$

$$y_1 = e^{k_1 \theta} = e^{(-2+i)\theta}$$

$$y_2 = e^{k_2 \theta} = e^{(-2-i)\theta}$$

$$y = C_1 e^{(-2+i)\theta} + C_2 e^{(-2-i)\theta}$$

$$y = C_1 e^{-2\theta} e^{i\theta} + C_2 e^{-2\theta} e^{-i\theta}$$

$$y_h = e^{-2\theta} [C_1 e^{i\theta} + C_2 e^{-i\theta}]$$

$$y_h = e^{-2\theta} [A \cos \theta + B \sin \theta]$$

$$y_p = A \cos x + B \sin x$$

$$y_p' = -A \sin x + B \cos x$$

$$y_p'' = -A \cos x - B \sin x$$

$$(-A \cos x - B \sin x) + 4(-A \sin x + B \cos x) + 5(A \cos x + B \sin x) = 6 \sin x + 0 \cos x$$

$$-A \cos x - B \sin x - 4A \sin x + 4B \cos x + 5A \cos x + 5B \sin x = 6 \sin x + 0 \cos x$$

$$(A + 4B + 5A) \cos x + (-B - 4A + 5B) \sin x = 6 \sin x + 0 \cos x$$

$$\cos x: A + 4B + 5A = 0$$

$$\sin x: -B - 4A + 5B = 6$$

$$4B + 4A = 0$$

$$4B - 4A = 6$$

$$A = -B$$

$$4B - 4(-B) = 6$$

$$4B + 4B = 6$$

$$A = -B$$

$$8B = 6$$

$$A = -\frac{3}{4}A$$

$$B = \frac{6}{8} = \frac{3}{4}$$

$$y_p = -\frac{3}{4} \cos \theta + \frac{3}{4} \sin \theta$$

~~$$y = y_0 + y_p = e^{-2\theta} [C_1 e^{1\theta} + C_2 e^{-1\theta}] + [-\frac{3}{4} \cos \theta + \frac{3}{4} \sin \theta]$$~~

$$y = y_0 + y_p = e^{-2\theta} [A \cos \theta + B \sin \theta] + [-\frac{3}{4} \cos \theta + \frac{3}{4} \sin \theta]$$

(iii) At steady state

$$\theta = \infty \quad \frac{dy}{d\theta} = 0$$

$$\frac{dy}{d\theta} = \frac{d(y)}{d\theta}$$

$$u = e^{-2\theta}$$

$$du = -2e^{-2\theta}$$

$$v = A \cos \theta + B \sin \theta$$

$$dv = -A \sin \theta + B \cos \theta$$

$$e^{-2\theta} [-A \sin \theta + B \cos \theta] + [A \cos \theta + B \sin \theta] - 2e^{-2\theta} \frac{d(y)}{d\theta}$$

$$\frac{dy}{d\theta} = e^{-2\theta} [-A \sin \theta + B \cos \theta] + [A \cos \theta + B \sin \theta] - 2e^{-2\theta} + \frac{3}{4} \sin \theta + \frac{3}{4} \cos \theta$$

at steady state

$$\theta = \infty \quad \frac{dy}{d\theta} = 0$$

~~$$\theta \rightarrow \frac{3}{4} \cos$$~~

$$0 = \frac{3}{4} \sin \theta + \frac{3}{4} \cos \theta$$

Divide through by $\cos \theta$

$$0 = \frac{3}{4} \tan \theta + \frac{3}{4}$$

$$\frac{3}{4} \tan \theta = -\frac{3}{4}$$

$$\tan \theta = -1$$

$$\theta = \tan^{-1}(-1)$$

$$\theta = -45^\circ$$

2. $EI \frac{d^3 y}{dx^3} = \frac{w}{2} (L-x)^2$

$$EI \frac{dy}{dx} = 0$$

$$\text{Let } \frac{d^2 y}{dx^2} = k^2$$

$$EI (k^2) = 0$$

$$k^2 = 0 \quad \therefore k = 0$$

$$y = A \cos \theta + B \sin \theta$$

$$y = A$$

$$y = (A + Bx)$$

$$y = A + Bx$$

Particular function

$$y = \frac{w}{2} (L-x)^2$$

$$y = Cx^2 + Dx + E$$

$$\frac{d^2 y}{dx^2} = 2C$$

$$EI(2C) = \frac{w}{2} (L-x)^2$$

$$EI(2C) = \frac{wL^2}{2} - \frac{2Lxw}{2} + \frac{wx^2}{2}$$

Particular function

$$y = \frac{w}{2} (L-x)^2$$

$$y = Cx^2 + Dx + Ex^3$$

$$\frac{dy}{dx} = 2Cx + 3Ex^2$$

$$\frac{d^2 y}{dx^2} = 2C + 6Ex$$

substitute into original equation

$$EI(2C + 6Ex) = \frac{w}{2} (L^2 - 2Lx + x^2)$$

$$2(2CEI + 6DEIx) = w(L^2 - 2Lx + x^2)$$

$$4CEI + 12DEIx + 24EEx^2 = w(L^2 - 2Lx + x^2)$$

Equating Coefficient

$$\Rightarrow w = 24E EI$$

$$E = \frac{w}{24EI} \quad (1)$$

$$\Rightarrow 12DEIx = -2wL$$

$$D = \frac{-2wL}{12EI} = \frac{-wL}{6EI} \quad (2)$$

$$\Rightarrow AC EI = wL^2$$

$$C = \frac{wL^2}{4EI} \quad \text{--- (2)}$$

$$y = \left[\frac{wL^2}{4EI} \right] x^2 - \left[\frac{wL}{6EI} \right] x^3 + \left[\frac{w}{24EI} \right] x^4$$

$$y = \frac{wL^2 x^2}{4EI} - \frac{wL x^3}{6EI} + \frac{w x^4}{24EI}$$

$$y = \frac{6wL^2 x^2 - 4wL x^3 + w x^4}{24EI}$$

$$y_p = \frac{w}{24EI} (6L^2 x^2 - 4L x^3 + x^4)$$

$$y = y_1 + y_2$$

$$y = A + Bx + \frac{w}{24EI} (6L^2 x^2 - 4L x^3 + x^4)$$

when $y=0, x=0, \frac{dy}{dx} = 0$

$$0 = A + B(0) + \frac{w}{24EI} (6L^2(0) - 4L(0) + 0)$$

$$0 = A + \Rightarrow A = 0$$

for B

$$\frac{dy}{dx} = B + \frac{w}{24EI} (6L^2 x - 12L x^2 + 4x^3)$$

$$0 = B + \frac{w}{24EI} (6L^2(0) - 12L(0) + 4(0))$$

$$B = 0$$

$$y = A + Bx + \frac{w}{24EI} (6L^2 x^2 - 4L x^3 + x^4)$$

$$y = 0 + (0)x + \frac{w}{24EI} (6L^2 x^2 - 4L x^3 + x^4)$$

$$y = \frac{w}{24EI} (6L^2 x^2 - 4L x^3 + x^4)$$

$$y = \frac{w}{24EI} (3L^2 x^2)$$

$$y = \frac{wL^2}{8EI} x^2$$

θ	y
0	-0.75
30	-0.27452
60	0.274519
90	0.75
120	1.024519
150	1.024519
180	0.75
210	0.274519
240	-0.27452
270	-0.75

