

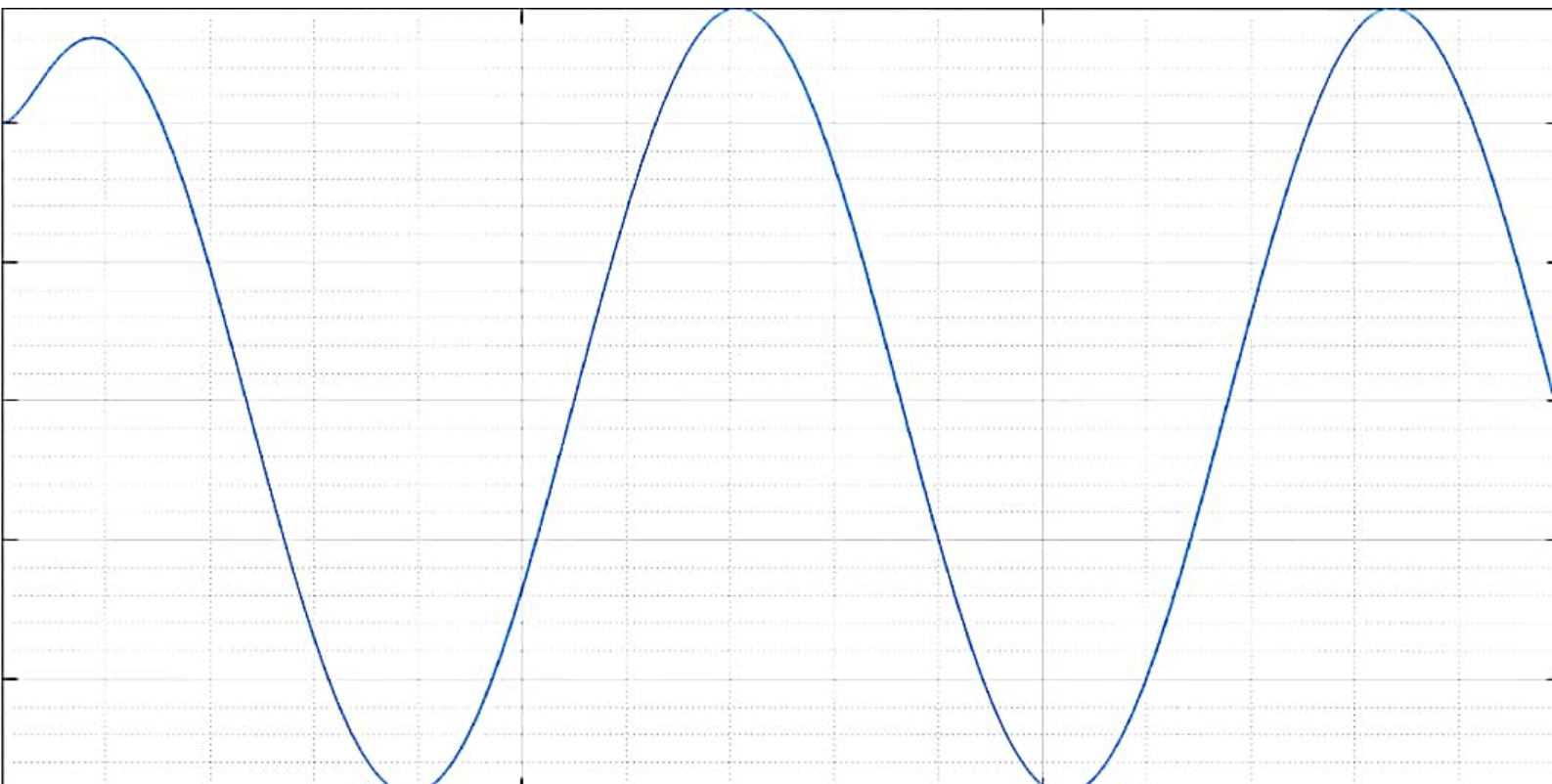
ts ▸ MATLAB
Editor - C:\Users\OCHENI VICTOR\Documents\MATLAB\mid.m
mid.m × +

```
commandwindow  
clear  
clc  
close all  
syms t  
x = (0.1)*(-exp(-2*t)+exp(-3*t)+cos(1*t)+sin(1*t))  
ts=[0:0.01:15]  
xs= subs(x,ts)  
figure(1)  
plot(ts,xs)  
xlabel('Time(seconds)')  
ylabel('Vibrations')  
grid on  
grid minor  
axis tight
```

Command Window

14.9400 14.9500 14.9600 14.9700 14.9800 14.9900 15.0000

```
xs =  
[ 1/10, cos(1/100)/10 - exp(-1/50)/10 + exp(-3/100)/10 + sin(1/100)/10, cos(1/50)/10 - exp(-1/25)/10 + exp(-3/50)/10 + sin(1/50)/10, ...  
...  
>>  
< || >
```



VICTOR OCHIENI

16/ENUGU/087

ELECTRICAL ELECTRONICS

ENG 381

$$\frac{d^2x}{dt^2} + 5\frac{dx}{dt} + 6x = \cos t$$

Using the Auxiliary Equation method to obtain the solution of the model.

1. Find the complementary function CF.

$$\frac{d^2x}{dt^2} + 5\frac{dx}{dt} + 6x = 0$$

$$\text{Assume } \frac{d^2x}{dt^2} = k^2x$$

$$\frac{dx}{dt} = kx$$

$$k^2 + 5k + 6 = 0$$

$$k^2 + 2k + 3k + 6 = 0$$

$$k(k+2) + 3(k+2) = 0$$

$$(k+2)(k+3) = 0$$

$$k+2=0 \quad \text{or} \quad k+3=0$$

$$k_1 = -2 \quad \text{and} \quad k_2 = -3$$

Therefore $x = A e^{k_1 t} + B e^{k_2 t}$

$$x = A e^{-2t} + B e^{-3t}$$

2. For the particular Integral

$$f(t) = \cos t$$

$$x = C \cos t + D \sin t$$

$$\therefore \frac{dx}{dt} = -C \sin t + D \cos t$$

$$\frac{d^2x}{dt^2} = -C \cos t - D \sin t$$

Substituting into the original eqn.

$$-C \cos t - D \sin t + 5[-C \sin t + D \cos t] + 6[C \cos t + D \sin t] = \cos t$$

$$-C \cos t - D \sin t - 5C \sin t + 5D \cos t + 6C \cos t + 6D \sin t = \cos t - 5C \sin t - 5C \sin t + 6D \sin t$$
$$= \cos t$$

$$50 \cos t + 5c \cos t + 50 \sin t - 5c \sin t = e \cos t$$

$$\cos t [50 + 5c] + \sin t [50 - 5c] = e \cos t$$

Equating coefficients

$$50 + 5c = 1$$

$$50 - 5c = 0$$

$$5c - [-5c] = 1 - 0$$

$$5c + 5c = 1$$

$$10c = 1$$

$$c = 1/10$$

$$c = 1/10$$

Sub into eqn (ii)

$$50 + 5 \left[\frac{1}{10} \right] = 1$$

$$\frac{50 + 1}{2} = 1$$

$$\frac{50 + 1}{2} = 1$$

$$\frac{50 + 1}{2} = 1$$

$$\frac{50 + 1}{2} = 1$$

$$100 + 1 = 2$$

$$101 = 2$$

Particular integrals

$$x = \frac{e \cos t}{10} + \frac{\sin t}{10}$$

Complete general solution = CF + PI

$$\text{Solution of the model is } x = A e^{-2t} + B e^{-3t} + \frac{e \cos t}{10} + \frac{\sin t}{10}$$

$$\text{at } t=0, x=0 \text{ and } \frac{dx}{dt} = 0$$

$$0 = A e^{-2(0)} + B e^{-3(0)} + \frac{e \cos(0)}{10} + \frac{\sin(0)}{10}$$

$$0 = A + B + \frac{e}{10} + 0$$

$$A + B = -\frac{e}{10} = -1 \Rightarrow A + B = -1$$

$$X = Ae^{-2t} + Be^{-3t} + \frac{\cos t}{10} + \frac{\sin t}{10}$$

$$\frac{dx}{dt} = -2Ae^{-2t} - 3Be^{-3t} - \frac{\sin t}{10} + \frac{\cos t}{10}$$

$$0 = -2Ae^{-2(0)} - 3Be^{-3(0)} - \frac{\sin(0)}{10} + \frac{\cos(0)}{10}$$

$$= -2A - 3B - 0 + \frac{1}{10}$$

$$2A + 3B = \frac{1}{10} \quad \dots \text{(iv)}$$

$$A + B = 0 \quad \dots \text{(iii)}$$

$$2A + 3B = \frac{1}{10} \quad \dots \text{(v)}$$

From eqn (iii), $A + B = 0$

$$A = -B$$

Sub. eqn (v) into (iv)

$$2(-B) + 3B = \frac{1}{10}$$

$$-2B + 3B = \frac{1}{10}$$

$$B = \frac{1}{10}$$

Sub B into eqn (iii)

$$A + \left[\frac{1}{10} \right] = 0$$

$$A = -\frac{1}{10}$$

The particular solution for the model is

$$x = -\frac{e^{-2t}}{10} + \frac{e^{-3t}}{10} + \frac{\cos t}{10} + \frac{\sin t}{10}$$

$$x = \frac{1}{10} \left[-e^{-2t} + e^{-3t} + \cos t + \sin t \right]$$

111 Write a steady-state solution of the system in form of $x = k \sin(t + \phi)$

From the equation

$$x = Ae^{-2x} + Be^{-3x} + \frac{1}{10} (\sin t + \cos t)$$

The equation has a changing or transient part and a steady part

The transient part denoted as e^{kt} and $k_2 t$

The steady part denoted $\frac{1}{10} (\sin t + \cos t)$

In trigonometric identities

$$A \sin \omega t + B \cos \omega t = C \sin(t + \theta)$$

$$\text{where } \theta = \tan^{-1}(A/B)$$

$$C = (A^2 + B^2)^{1/2}$$

steady part becomes

$$\frac{1}{10} \sin t + \frac{1}{10} \cos t = k \sin(t + \phi)$$

where

$$k = ((0-1)^2 + 0-1^2)^{1/2} = \frac{\sqrt{2}}{10}$$

$$\phi = \tan^{-1}\left(\frac{0-1}{-0-1}\right)$$

$$\phi = -45^\circ$$

$$k \sin(t + \phi) = \frac{\sqrt{2}}{10} \sin(t - 45^\circ)$$

$\frac{\sqrt{2}}{10} \sin(t - 45^\circ)$ is the steady state equation.