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Assignment

The dynamic model of a body in motion performing damped force vibrations is as in Equation ①

$$\frac{d^2x}{dt^2} + \frac{5dx}{dt} + 6x = \cos t \quad ①$$

Given that when $t=0$, $x=0.1$ and $\frac{dx}{dt}=0$.

i) using the auxiliary equation method, obtain the solution of the model in form of an expression having x as a function of t .

ii) Write a MATLAB program to plot the relationship b/w x and t for 0cts is units using a step size of 0.01 units, and

iii) write the steady-state solution of the system in form of $x = K \sin(\omega t + \phi)$

Solution

$$① \frac{d^2x}{dt^2} + \frac{5dx}{dt} + 6x = \cos t$$

$$\text{let } x = A e^{kt}$$

$$x' = \frac{dx}{dt} = KAe^{kt} \quad \text{initial condition?}$$

$$x'' = \frac{d^2x}{dt^2} = K^2 A e^{kt} \quad \text{initial condition?} = [2.3] \text{ initial condition?}$$

$$\text{let R.H.S} = 0$$

$$K^2 x + 5Kx + 6x = 0 \quad (\text{initial condition?})$$

$$K^2 + 5K + 6 = 0 \quad (\text{by using factorization method})$$

$$K^2 + 3K + 2K + 6 = 0$$

$$K(K+3) + 2(K+3) = 0$$

$$(K+2)(K+3) = 0$$

$$K_1 = -2 \quad \text{and} \quad K_2 = -3$$

for Real & distinct roots

$$x = Ae^{k_1 t} + Be^{k_2 t}$$

$$x = Ae^{-2t} + Be^{-3t}$$

from R.H.S

$$x = \text{Cost}$$

General form of the function, $x = C\text{Cost} + D\text{Sint}$

$$x' = \frac{dx}{dt} = -Csint + Dcost$$

$$\frac{d^2x}{dt^2}$$

$$x'' = \frac{d^2x}{dt^2} = -Ccost - Dsint = -C(cost + Dsint)$$

$$-(Ccose + Dsint) + 5(-Csint + Dcost) + 6(Ccost + Dsint) = Cost$$

$$Cost (-C + 5D + 6C) + Sint (-D - 5C + 6D) = Cost$$

$$Cost (C - C + 5D + 6C) = Cost$$

$$Sint (-D - 5C + 6D) = 0$$

$$-C + 5D + 6C = 1 \quad 5D + 5C = 1 \quad \text{Equation 1}$$

$$-D - 5C + 6D = 0 \quad 5D - 5C = 0 \quad \text{Equation 2}$$

$$\text{Equation 1} - \text{Equation 2} \Rightarrow 10C = 1$$

$$C = \frac{1}{10}$$

$$\text{Sub } C = \frac{1}{10} \text{ into Equation 2}$$

$$5D - 5\left(\frac{1}{10}\right) = 0$$

$$5D = \frac{1}{5}$$

$$D = \frac{1}{10}$$

$$x = \frac{1}{10} \text{Cost} + \frac{1}{10} \text{Sint}$$

Complete General Solution [GGS] = Complementary Function + Particular Integral

$$x = Ae^{-2t} + Be^{-3t} + \frac{1}{10}(\text{Cost} + \text{Sint})$$

(Combination of Complementary function & Particular Integral)

When $t=0$, $x=0.1$ and $x'=0$

$$x' = \frac{dx}{dt} = -2AB^{-2t} - 3BB^{-3t} - \frac{1}{10}Sint + \frac{1}{10}Cost$$

$$x' = -(2AB^{-2t} + 3BB^{-3t} + \frac{1}{10}Sint - \frac{1}{10}Cost)$$

$$0.1 = A + B + 0.1$$

$$0 = -2A - 3B - 0.1$$

$$A + B = 0 \quad \text{---} \quad ① \times 2$$

$$-2A - 3B = -0.1 \quad \text{---} \quad ②$$

$$2A + 2B = 0 \quad \text{---} \quad ③$$

$$\text{equ } ② + ③ \quad -B = -0.1$$

$$B = 0.1$$

Sub $B = 0.1$ into equ ①

$$A + 0.1 = 0$$

$$A = -0.1$$

Complete particular solution & C.P.S \rightarrow

$$x = -\frac{1}{10}e^{-2t} + \frac{1}{10}e^{-3t} + \frac{1}{10}(cost + sint)$$

$$x = -0.1(e^{-2t} - e^{-3t} - cost - sint)$$

② Solution

- Command Window

- clear

-clc

- close all

- syms

$$x = 0.1 \times (\exp(-3*t) - \exp(-2*t)) + (cost) + (int)$$

$$tn = [0.001..15]$$

$$tn = \text{subs}(x, tn)$$

figure 1.

plot(tn, xn)

Axes tight

x label ('time')

y label ('Vibration')

③ Solution

$$x = \frac{1}{10}(e^{-3t} - e^{-2t} + sint + cost)$$

$$\text{at steady state } \frac{dx}{dt} = 0 \quad 1.8$$

$$\frac{dx}{dt} = \frac{1}{10} (-3e^{-3t} - e^{-2t} + \cos t - \sin t)_{t=0}$$

$$10 = 8t - A$$

\therefore the exponential ab results to 0 because it is at steady state

$$0 = \cos t - \sin t$$

$$\cos t = \sin t$$

$$t = 45^\circ$$

$$x = \frac{1}{10} (\cos 45 + \sin 45) = \frac{\sqrt{2}}{10}$$

$$A \cos \omega t + B \sin \omega t = K \cos(\omega t - \theta)$$

$$\text{But; } \cos(\omega t - \theta) = \sin(\omega t - \theta + 90^\circ)$$

$$\text{Where, } K = \sqrt{A^2 + B^2}$$

$$= \sqrt{10^2 + 10^2} = \frac{\sqrt{2}}{10}$$

$$\theta = 0^\circ$$

$$\text{Recall } x = K \sin(\omega t + \theta)$$

$$\frac{\sqrt{2}}{10} = \frac{\sqrt{2}}{10} \sin(45^\circ + 0^\circ)$$

$$\theta = 90 - 45 = 45^\circ$$

Steady state equation

$$x = \frac{\sqrt{2}}{10} \left(\sin 1 + \frac{x}{4} \right)$$

$$(d\omega)^2 + (d\omega)^2 + (d\omega)^2 \sin 0 - (d\omega)^2 \sin 0 \times 10$$