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16 ENR06/008

MECHANICAL ENGINEERING

ENR 381

1) The dynamic model of a body in motion performing damped forced vibrations is as in eqn (i)

$$\frac{d^2x}{dt^2} + 5\frac{dx}{dt} + 6x = \cos t \quad \text{--- (i)}$$

Given that when  $t=0$ ,  $x=0.1$  and  $\frac{dx}{dt}=0$ .

Using the Auxiliary Equation

(i) using the Auxiliary Eqn method, Obtain the solution of the model in form of an expression having  $x$  as a function of  $t$ .

(ii) Write a MATLAB program to plot the relationship between  $x$  and  $t$  for  $0 \leq t \leq 15$  unit using a step size of 0.01 unit and

(iii) Write the Steady-State solution of the system in form  $x = k \sin(\omega t + \phi)$

Soln

$$\frac{d^2x}{dt^2} + 5\frac{dx}{dt} + 6x = \cos t$$

$$(f); m^2 + 5m + 6 = 0; m^2 + 2m + 3m + 6 = 0$$

$$m(m+2) + 3(m+2) = 0$$

~~m~~

$$(m+3)(m+2) = 0$$

$$m_1 = -3, m_2 = -2$$

$$\therefore x = Ae^{-3t} + Be^{-2t}$$

PI:  $f(t) = \cos t$

$$x = C \cos t + D \sin t$$

$$\frac{dx}{dt} = -[C \sin t + D \cos t]$$

$$\frac{d^2x}{dt^2} = -[C \cos t - D \sin t]$$

$$(-C \cos t - D \sin t) + 5(-C \sin t + D \cos t) + 6(C \cos t + D \sin t) = C \cos t$$

$$-C \cos t - D \sin t - 5C \sin t + 5D \cos t + 6C \cos t + 6D \sin t = C \cos t$$

$$(5D - C + 6C) \cos t + (-5C - D + 6D) \sin t$$

$$= C \cos t + 0$$

Rebalancing

L.H.S  $\neq$  R.H.S

$$5C + 5D = 1 \quad \text{--- (1)}$$

$$-5C + 5D = 0 \quad \text{--- (2)}$$

$$5D = 5C$$

$$D = C$$

Substituting for D in (1)

$$5C + 5C = 1$$

$$10C = 1$$

$$C = \frac{1}{10} = D$$

$$PI \Rightarrow x = \frac{\cos t}{10} + \frac{\sin t}{10}$$

General soln  $\Rightarrow$

$$x = A e^{-3t} + B e^{-2t} + \frac{\cos t}{10} + \frac{\sin t}{10}$$

$$x = A e^{-3t} + B e^{-2t} + \frac{1}{10} (\cos t + \sin t)$$

When  $t = 0$  &  $x = 0.1$

$$0.1 = A + B + \frac{1}{10} (1 + 0)$$

$$A + B = 0 \quad \text{--- (1)}$$

$$\frac{dx}{dt} = -3Ae^{-3t} - 2Be^{-2t} + X_0(-\sin t + \cos t)$$

When  $dx/dt = 0$ ;  $t=0$

$$0 = -3A - 2B + 0.1(-0+1)$$

$$3A + 2B = 0.1 \quad \text{--- (2)}$$

From eqn A

$$A = -B$$

Sub for A in eqn (2)

$$3(-B) + 2B = 0.1$$

$$-B = 0.1$$

$$B = -0.1$$

$$A = 0.1$$

$$A = 0.1$$

$$x = 0.1 \times e^{-3t} - 0.1 \times e^{-2t} + 0.1(\cos t + \sin t)$$

$$x = 0.1(e^{-3t} - e^{-2t} + \cos t + \sin t)$$

$$x = \frac{1}{10} (e^{-3t} - e^{-2t} + \cos t + \sin t)$$

(ii) Matlab codes

1 - Command window

2 - Clear

3 - Clc

4 - Close all

5 - Syms t

6 -  $x = 0.1 \times (\exp(-3 \times t) - \exp(-2 \times t) + \cos(t) + \sin(t))$

7 -  $tn = [0; 0.01; 15]$

8 -  $xn = \text{subs}(x, tn)$

9 - figure (1)

10 - plot (tn, xn)

11 - grid on

12 - grid minor

- 13 - axis tight
- 14 - x label (time)
- 15 - y label ('vibrations')
- 16 - axis tight

$$\text{iii) } x = \frac{1}{10} (e^{-3t} - e^{-3t} + \sin t + \cos t)$$

When at steady state  $\frac{dx}{dt} = 0$  i.e.

Change in  $x$  with time is zero

$$\therefore \frac{dx}{dt} = \frac{1}{10} (-3e^{-3t} - e^{-3t} + \cos t - \sin t)$$

$$0 = \cos t - \sin t$$

$$\cos t = \sin t$$

$$t = 45^\circ$$

$$\therefore x = \frac{1}{10} (\cos 45 + \sin 45) = \frac{\sqrt{2}}{10}$$

~~1~~ b

$$A \cos \omega t + B \sin \omega t = k \cos(\omega t - \theta)$$

$$\text{But; } \cos(\omega t - \theta) = \sin(\omega t - \theta + 90^\circ)$$

$$\text{where } k = \sqrt{A^2 + B^2} = \sqrt{(1/10)^2 + (1/10)^2} = \sqrt{1+1}/(10)^2$$

$$k = \frac{\sqrt{2}}{10}$$

$$\theta = 0^\circ \text{ (since } A \text{ \& } B \text{ in same phase)}$$

Recall that  $x = k \sin(\omega t + \alpha)$

$$\frac{\sqrt{2}}{10} = \frac{\sqrt{2}}{10} \sin(45 + \alpha), \quad 1 = \sin(45 + \alpha)$$

$$45 + \alpha = \sin^{-1}(1)$$

$$\alpha = 90 - 45 = 45^\circ = \frac{\pi}{4}$$

$$\text{The steady state solution} = x = \frac{\sqrt{2}}{10} \sin(t + \frac{\pi}{4})$$