

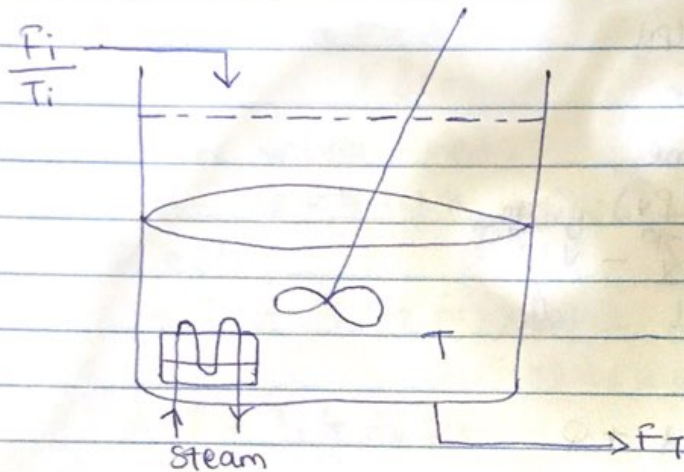
Name: Gaganga Ayibatonye Ebiere

matric no: 1416NG01008

Course: <sup>code</sup> CH0 331

Course: ~~Process~~ Process Dynamics & Control I

### Assignment 1



using energy balance

$$\sum [u + PE + KE]_{t+\Delta t} - \sum [u + PE + KE]_t = \left[ \begin{array}{l} H + PE + KE \\ \text{into the system} \\ \text{due to convection} \end{array} \right]_{At} - \left[ H + PE + KE \right]_{\text{out of system}} + \Phi - W_s$$

where  $W_s$  = shaft work

$PE$  = Potential energy

$KE$  = kinetic energy

$\Phi$  = heat

#### Assumptions

$W_s = 0$  because the tank is steady

$PE = 0$

$KE = 0$  because there is no elevation of the product in the system.

$$[U_{\text{sys}}]_{t+\Delta t} - [U_{\text{sys}}]_t = \dot{H}_{\text{in}} \Delta t - \dot{H}_{\text{out}} \Delta t + \dot{Q} \Delta t$$

Dividing through by  $\Delta t$  and limiting  $t \rightarrow 0$

$$\frac{du}{dt} = \dot{H}_{\text{in}} - \dot{H}_{\text{out}} + \dot{Q}$$

from first Law of thermodynamics

$$H = U + PV$$

$$\therefore U = H - PV$$

where  $H = \text{Enthalpy}$

$P = \text{Pressure}$

$V = \text{volume}$

$$U_{\text{sys}} = H_{\text{sys}} - (PV)_{\text{system}}$$

$$\frac{du}{dt} = \frac{dH}{dt} - P \frac{dV}{dt} - V \frac{dP}{dt}$$

Substitute  $du/dt$

$$\frac{dH}{dt} = \dot{H}_{\text{in}} - \dot{H}_{\text{out}} + \dot{Q}$$

$$H = \dot{m}h$$

$$\dot{m} = \rho \dot{V} \quad \dot{m} = \rho \dot{V}$$

Replacing  $H = \dot{m}h$

$$\frac{d(\dot{m}h)}{dt} = (\dot{m}h)_{\text{in}} - (\dot{m}h)_{\text{out}} + \dot{Q}$$

Replace  $\dot{m} = \rho \dot{V}$  &  $\dot{m} = \rho \dot{V}$

$$\frac{d(\rho \dot{V} h)}{dt} = \rho \dot{V} h_{\text{in}} - \rho \dot{V} h_{\text{out}} + \dot{Q}$$

$$\rho \dot{V} \frac{dh}{dt} = \rho \dot{V} h_{\text{in}} - \rho \dot{V} h_{\text{out}} + \dot{Q}$$

from the question  $Q = \dot{m} \lambda_s$ ,  $h = C_p dT$

Recall  $C_p$  is constant with time.

$$\rho \dot{V} C_p \frac{dT}{dt} = \rho \dot{V} C_p \int_{T_0}^{T_1} dT \Big|_{\text{in}} - \rho \dot{V} C_p \int_{T_0}^T dT \Big|_{\text{out}} + \dot{m} \lambda_s$$

$$\rho \dot{V} C_p \frac{dT}{dt} = \rho \dot{V} C_p [T_1 - T_0]_{\text{in}} - \rho \dot{V} C_p [T - T_0]_{\text{out}} + \dot{m} \lambda_s$$

Divide through by  $F \delta C_p$

$$\frac{\delta u C_p dt}{F \delta C_p dt} = \frac{F \delta C_p (T_1 - T_0)}{F \delta C_p} - \frac{F \delta C_p (T - T_0)}{F \delta C_p} + \frac{\dot{m}_s \lambda_s}{F \delta C_p}$$

$$\frac{dT}{dt} = [T_1 - T_0] - [T - T_0] + \frac{\dot{m}_s \lambda_s}{F \delta C_p}$$

$$\frac{dT}{dt} = T_1 - T + \frac{\dot{m}_s \lambda_s}{F \delta C_p}$$

$$\frac{dT}{dt} + T = T_1 + \frac{\dot{m}_s \lambda_s}{F \delta C_p}$$

Substituting the values where:

$$\delta = 1000 \text{ kg/m}^3, C_p = 4.181 \text{ kJ/kg}^\circ\text{C}, F_i = 0.15 \text{ m}^3/\text{min}, V = 3, \lambda_s = 2258 \text{ kJ/kg}$$

$$\therefore \frac{3}{0.15} \frac{dT}{dt} + T = T_1 + \frac{\dot{m}_s \lambda_s}{0.15 \times 1000 \times 4.181}$$

$$2.0 \frac{dT}{dt} + T = T_1 + \dot{m}_s 3.6$$

Deviation variable = Dynamic model - Steady state models

$$\therefore 2.0 \frac{dT'}{dt} + T' = T_1' + 3.6 \dot{m}_s \rightarrow \text{deviation variable}$$

Transfer function

$$\frac{dT'}{dt} = \delta T(\omega) - T(\omega)$$

$$T = T(\omega)$$

Substitute in the deviation variable

$$2.0 [\delta T'(\omega) - T'(\omega)] + T'(\omega) = T_1'(\omega) + 3.6 \dot{m}_s'(\omega)$$

$$2.0 \delta T'(\omega) + T'(\omega) = T_1'(\omega) + 3.6 \dot{m}_s'(\omega)$$

factorize  $T'(\omega)$

$$T'(\omega) (2.0 + 1) = T_1'(\omega) + 3.6 \dot{m}_s'(\omega)$$

$$T'(\omega) = \frac{T_1'(\omega)}{2.0 + 1} + \frac{3.6}{2.0 + 1} \dot{m}_s'(\omega)$$

$$T'(\omega) [2.0 + 1] = T_1'(\omega) + 3.6 \dot{m}_s'(\omega)$$

making  $T'(s)$  the subject of the formula

$$T'(s) [2.0 + 1] = T_1'(s) + 3.6 \dot{m}'(s)$$

$$T'(s) = \frac{T_1'(s)}{2.0s + 1} + 3.6 \cdot \dot{m}'(s)$$