

YAMUBU HEEMAT OHUNENE

17/ENG02/080

COMPUTER ENGINEERING

ENG 381

ASSIGNMENT

→ The dynamic model of a body in motion performing damped force vibration is as in the equation:

$$\frac{d^2x}{dt^2} + 5\frac{dx}{dt} + 6x = \cos t$$

Given that $x=0$, $t=0$ and $\frac{dx}{dt} = 0$

→ Using the auxiliary equation method, the solution of the model in form of an expression having x as a function of t .

Solu

$$\frac{d^2x}{dt^2} + 5\frac{dx}{dt} + 6x = \cos t$$

$$m^2 + 5m + 6 = 0$$

Auxiliary equation

$$m^2 + 3m + 2m + 6 = 0$$

$$(m+2)(m+3) = 0$$

$$m = -2 \text{ or } -3$$

Complementary Function

$$y = Ae^{2t} + Be^{-3t}$$

Particular Integral

$$x = C \cos t$$

$$= C \cos t + D \sin t$$

$$\frac{dx}{dt} = -C \sin t + D \cos t$$

$$\frac{d^2x}{dt^2} = -C \cos t - D \sin t$$

Put

$$= -C \cos t - D \sin t - 5C \sin t + 5D \cos t + 6C \cos t + 6D \sin t = \cos t$$

Coefficients of $\cos t$

$$= -C \cos t + 6C \cos t + 5D \cos t = 1$$

$$= 5C + 5D = 1 \dots \textcircled{1}$$

coefficients of $\sin t$

$$-D \sin t + 6D \sin t - 5C \sin t = 0$$

$$5D - 5C = 0 \dots \textcircled{2}$$

$$5C + 5D = 1$$

from eqn $\textcircled{2}$

$$5D - 5C = 0$$

$$D = C \dots \textcircled{3}$$

Put eqn $\textcircled{3}$ in $\textcircled{1}$

$$5C + 5(C) = 1$$

$$10C = 1$$

$$C = 0.1$$

$$D = 0.1$$

P.I

$$x = 0.1 \cos t + 0.1 \sin t$$

General solution

$$x = A e^{-2t} + B e^{-3t} + 0.1 \cos t + 0.1 \sin t$$

When $t=0$, $x=0.1$

$$0.1 = A + B + 0.1$$

$$A + B = 0$$

When $t=0$, $\frac{dx}{dt} = 0$

$$\frac{dx}{dt} = -2A e^{-2t} - 3B e^{-3t} - 0.1 \sin t + 0.1 \cos t$$

$$0 = -2A - 3B + 0.1$$

$$-0.1 = -2A - 3B$$

from

$$A + B = 0$$

$$B = -A$$

$$-0.1 = -2A - 3(-A)$$

$$-0.1 = A$$

$$A = -0.1$$

$$B = 0.1$$

Particular Function

$$x = 0.1e^{-2t} + 0.1e^{-3t} + 0.1\cos t + 0.1\sin t.$$

→ Using MATLAB

Command window

clear

clc

close all

Syms t

$$x = (1/10 * \exp(-2*t)) - (1/10 * \exp(-3*t)) + (1/10 * (\sin t)) + (\cos t)$$

$$t = 0:0.001:15$$

$$x_t = \text{subs}(x, t)$$

$$x_t_n = \text{double}(x_t)$$

plot(t, x, t_n)

xlabel('t')

ylabel('x')

grid on

grid minor

grid right

→ At steady state $k \sin(t+a)$

$$x_{ss} = x_t \rightarrow \infty = 0.1\cos t + 0.1\sin t$$

$$= 0.1\cos t + 0.1\sin t = k \sin(t+a)$$

$$x_{ss} = k \sin t \cos a + k \cos t \sin a$$

$$0.1 = k \sin a$$

$$0.1 = k \cos a$$

$$k^2 \sin^2 a + k^2 \cos^2 a = \frac{1}{100} + \frac{1}{100}$$

$$k^2 (\sin^2 a + \cos^2 a) = 2/100$$

$$k^2 = \frac{2}{100}$$

$$k = \frac{\sqrt{2}}{10}$$

Divide both equations

$$\frac{k \sin a}{k \cos a} = \frac{0.1}{0.1} = 1$$

$$\tan a = 1$$

$$a = \tan^{-1}(1)$$

$$a = 45 \text{ or } \pi/4 \text{ radian}$$

Steady state

$$x_{ss} = \frac{\sqrt{2}}{10} \sin\left(t + \frac{\pi}{4}\right)$$

