

Solu

Using MATHECAD

$$A = \begin{bmatrix} 1 & -2 & -1 & 3 \\ 2 & 3 & 0 & 1 \\ 1 & -0 & -4 & -2 \\ 0 & -1 & 3 & 1 \end{bmatrix} \quad C = \begin{pmatrix} 10 \\ 8 \\ 3 \\ -7 \end{pmatrix}$$

$$B = A^{-1}$$

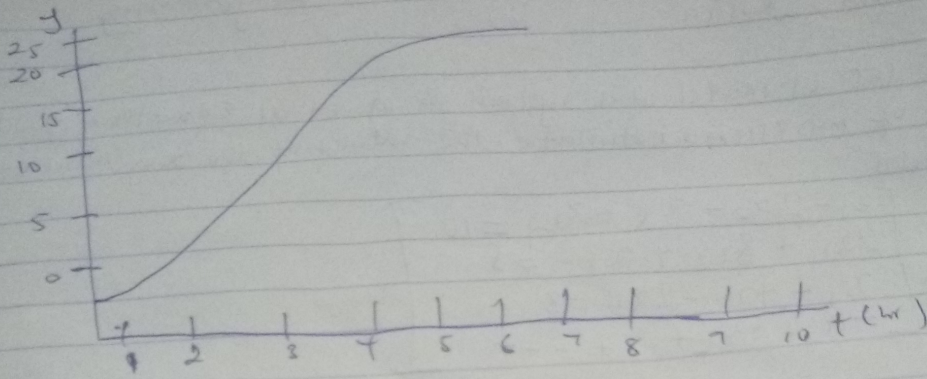
$$B = \begin{bmatrix} 0.627 & 0.242 & 0.493 & 0.667 \\ -0.093 & 0.16 & -0.227 & -0.333 \\ -0.107 & 0.054 & 0.027 & 0.333 \\ 0.227 & -0.054 & -0.307 & -0.333 \end{bmatrix}$$

$$D = B \cdot C$$

$$D = \begin{pmatrix} -1 \\ 2 \\ -3 \\ 4 \end{pmatrix} = \begin{pmatrix} x_1 = -1 \\ x_2 = 2 \\ x_3 = -3 \\ x_4 = 4 \end{pmatrix}$$

| t | y |
|-----|---------|
| 9.0 | 20.6807 |
| 9.1 | 20.8832 |
| 9.2 | 21.0833 |
| 9.3 | 21.2810 |
| 9.4 | 21.4764 |

Scale x-axis same to Unit
y-axis same to Units



The Model equation of a system has been developed to be
 $y = \sin(0.25t) + 2t e^{20-0.5t} - 2 \cos \frac{\pi}{10} t$. with the goal of
 MATLAB, determine its dynamic response in tabular form for
 $0 \leq t \leq 10$ hr with $\Delta t = 0.1$ hr

to present
 the
 with Δt

| t | y | t | y | t | y |
|-----|---------|-----|--------|-----|---------|
| 0 | -1 | 2.0 | 3.0441 | 4.0 | 8.2568 |
| 0.1 | -0.8555 | 2.1 | 3.2887 | 4.1 | 8.5277 |
| 0.2 | -0.7624 | 2.2 | 3.5358 | 4.2 | 8.7982 |
| 0.3 | -0.5413 | 2.3 | 3.7852 | 4.3 | 9.0692 |
| 0.4 | -0.3726 | 2.4 | 4.0367 | 4.4 | 9.3402 |
| 0.5 | -0.1969 | 2.5 | 4.2903 | 4.5 | 9.6112 |
| 0.6 | -0.0146 | 2.6 | 4.5458 | 4.6 | 9.8821 |
| 0.7 | 0.1788 | 2.7 | 4.8030 | 4.7 | 10.1529 |
| 0.8 | 0.3681 | 2.8 | 5.0617 | 4.8 | 10.4234 |
| 0.9 | 0.5677 | 2.9 | 5.3223 | 4.9 | 10.6935 |
| 1.0 | 0.7727 | 3.0 | 5.5841 | 5.0 | 10.9632 |
| 1.1 | 0.9824 | 3.1 | 5.8473 | 5.1 | 11.2325 |
| 1.2 | 1.1966 | 3.2 | 6.1116 | 5.2 | 11.5012 |
| 1.3 | 1.4150 | 3.3 | 6.3770 | 5.3 | 11.7692 |
| 1.4 | 1.6375 | 3.4 | 6.6432 | 5.4 | 12.0365 |
| 1.5 | 1.8637 | 3.5 | 6.9106 | 5.5 | 12.3031 |
| 1.6 | 2.0935 | 3.6 | 7.1787 | 5.6 | 12.5688 |
| 1.7 | 2.3266 | 3.7 | 7.4474 | 5.7 | 12.8335 |
| 1.8 | 2.5628 | 3.8 | 7.7166 | 5.8 | 13.0975 |
| | | 3.9 | 7.9866 | 5.9 | 13.3600 |