

Maths

1. Velocity = $\frac{dr}{dt}$

Since we are dealing with position vectors

let $P(x, y, z)$ be any point on the curve

and $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ be the position vector of P relative to O as

the origin

Substituting x, y, z in \vec{r}

$$\text{we have } \vec{r} = (t)\hat{i} + (6t^2 + 4t)\hat{j} + (t-6)\hat{k}$$

So velocity vector \vec{v}

will be differential of \vec{r} in respect to t

$$\text{Vector } \vec{v} = \frac{d\vec{r}}{dt} = 14t^2\hat{i} + (2 \times (6t^{2-1} + 4t^{-1}))\hat{j} + 1t^{-1}$$

$$\vec{v} = \frac{d\vec{r}}{dt} = 14t\hat{i} + (12t - 4)\hat{j} + \hat{k}$$

2. $A = 1\hat{i} + 2\hat{j} - 4\hat{k}$

$B = 2\hat{i} + 3\hat{j} - \hat{k}$

$C = 4\hat{j} + 3\hat{k}$

$A \times B \times C$

$$1\hat{i} + 2\hat{j} - 4\hat{k} \times [(2\hat{i} - 3\hat{j} + \hat{k}) \times (4\hat{j} - 3\hat{k})]$$

$$1\hat{i} + 2\hat{j} - 4\hat{k} \times [2\hat{i} - 12\hat{j} - 3\hat{k}]$$

$$2\hat{i} - 24\hat{j} + 12\hat{k}$$

3. $R = 4\sin 3t\hat{i} + 4e^{2t}\hat{j} + 7e^3\hat{k}$

$$\int R dt = \frac{-4}{3} \cos 3t \hat{i} + \frac{4}{3} e^{2t} \hat{j} + \frac{7t^4}{4} \hat{k}$$

$$\begin{aligned}
 4 \quad A &= 7i + 2j + k \\
 B &= 2i + 3j + 4k \\
 C &= i + j + k \\
 (A+C) &= (B-A) \\
 [(7i+2j+k) + (i+j+k)] &= [(2i+3j+4k) - (7i+2j+k)] \\
 [8i+3j+2k] &= [-5i-j+3k] \\
 (8i+3j) \times (-5i-j+3k) &= 40i - 3j
 \end{aligned}$$

$$\begin{aligned}
 5 \quad x &= t \quad y = t^2 \quad z = t^3 \\
 r &= xi + yj + zk \\
 r &= ti + t^2j + t^3k \\
 \frac{dr}{dt} &= i + 2tj + 3t^2k \\
 \text{At } t=1 \quad \frac{dr}{dt} &= i + 2(1)j + 3(1^2)k \\
 \frac{dr}{dt} &= i + 2j + 3k \\
 \left| \frac{dr}{dt} \right| &= \sqrt{1^2 + 2^2 + 3^2} \\
 &= \sqrt{14} \\
 T &= \frac{\frac{dr}{dt}}{\left| \frac{dr}{dt} \right|} = \frac{i + 2j + 3k}{\sqrt{14}}
 \end{aligned}$$