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Electrical/electronics

Electrical machines

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1 The power factor of a [synchronous motor](http://www.mytech-info.com/2015/02/principle-of-operation-of-synchronous.html" \t ") is changed with a change in the excitation. When the excitation of the motor is increased, the power factor changes from lagging to unity and then to a leading power factor. This property of the motor is utilized to improve the power factor of the leads, having a low lagging power factor. Normally, when the motor is utilized in this way to improve the factor, the synchronous motor is run without any mechanical load. The excitation is adjusted in such a manner that it works at a leading power factor. The synchronous motor is then referred to a synchronous condenser.

2 That means that the three phase current entering the stator winding has an angle difference with the voltage

The purpose of using synchronous motors is to use it in leading power factor By controlling the field current in the rotor

3 An over-excited **synchronous motor** has a leading **power factor**. This makes it useful for **power factor** correction of industrial loads. Both transformers and induction **motors** draw lagging (magnetising) currents from the line. ... This improves the plant **power factor** and reduces the reactive current required from the grid.

4 A synchronous motor has better power factor as compared to that of an equivalent induction motor. This is mainly because

 A. synchronous motor has no slip

 B. stator supply is not required to produce magnetic field

C. mechanical load on the rotor remains constant

 D. synchronous motor has large airgap

5 **Synchronous motors** are used for the **power factor** correction Now, since the set up of the magnetic flux (which **can** be considered as the reactive **power** component) inside the **motor**is done by the dc excitation provided on the rotor terminals, the **power factor can** also be **controlled** by **controlling** this dc excitation.

6 A **synchronous motor** running on **no**-**load** with leading power factor-will **act** as **synchronous** condenser.

The same **motor when operated** with lagging power factor on **no**-**load** will draw a reactive current from the system depending upon the system voltage.

7 Like an induction **machine**, an under excited **synchronous machine** too will consume reactive **power**; a properly excited **synchronous machine** neither consumes nor produces reactive **power**; An over excited **synchronous machine** can produce reactive **power**.

8 **Efficiency** is higher **than** of an **induction motor** of the same output and voltage rating because there are neither losses related to slip nor the additional losses due to magnetizing current. With **synchronous motors**, there is no difference of speed between air gap rotating magnetic field and rotor.

9 Power factor of induction motor depends on load and speed ,Piwer factor of a synchronous might be fixed ,usually such motors are huge and therefore their reactive power causes huge losses

10 The real power is nothing to do with it. The real power will be proportional to the mechanical load. If the motor is uncoupled it will be (close to) zero, regardless of the reactive situation. If the load is consuming power, the motor will take it from the supply to pass on. If the load is supplying power the converse will apply.

11 This a tough job on your hands. Large synchronous motors have adjustable power factor. They can even have leading power factor. They are often set this way compensate for all the other induction motors. This can effect the efficiency of the motor depending on load. With the system tuned to near unity the entire distribution system benefits. It is a good way to go. There is not just one type of synchronous motor but they most often do better than standard induction motors.

12 Synchronous motor always rotates with synchronous speed, irrespective of the loading conditions. So, the effective output is not reduced, compared to induction motor. So, more efficiency is observed in this case. Also, the operating power factor is constant in synchronous motors. It is also a doubly excited machine, unlike induction motor.

13 **synchronous** machine **have** separate DC excitation which reduces machine's excitation dependency on main supply, hence better **PF**. where as IM **have** no such provisions, hence low **PF** .

14 **Power factor** is a number which in very small length tells us about the efficiency of an **AC machine** like **induction motor**. As we know, in an inductive load current lags the voltage by a certain angle. Higher the lag, lesser will be the **power factor**. ... cosine of the angle between Voltage and Current is called **power factor**.

15 An over-excited **synchronous motor** has a leading **power factor**. This makes it useful for **power factor correction** of industrial loads. Both transformers and **induction motors** draw lagging (magnetising) currents from the line. ... This improves the plant **power factor** and reduces the reactive current required from the grid.