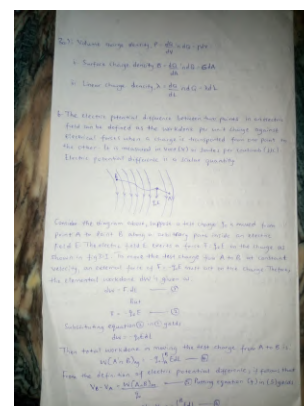
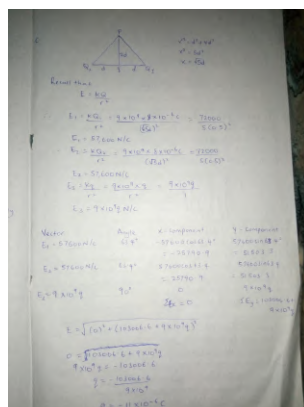
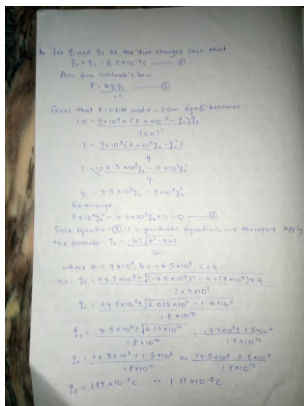
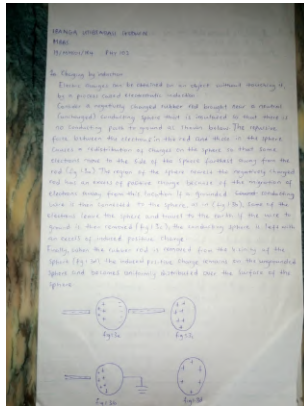


# Ibanga Utibeabasi Godwin

19/MHS01/184



4. Magnetic flux is defined as the strength of the magnetic field which can be represented by the eq.  $\Phi = \int \vec{B} \cdot d\vec{A}$

b. For a wire loop  
 $r = 1.5 \times 10^{-2} \text{ m}$   
 $B = 3.5 \times 10^{-2} \text{ Tesla}$

$\Phi = \int \vec{B} \cdot d\vec{A}$   
 $\Phi = B \cdot A$   
 $\Phi = 3.5 \times 10^{-2} \cdot \pi (1.5 \times 10^{-2})^2$   
 $\Phi = 2.47 \times 10^{-4} \text{ Weber}$


c. For wire loop parameter: the mass of electron  $m = 9.1 \times 10^{-31} \text{ kg}$   
 radius of wire  $r = 1.5 \times 10^{-2} \text{ m}$   
 Magnetic field of  $3.5 \times 10^{-2} \text{ Tesla}$

Recall that angular speed is given as  $\omega = \frac{v}{r}$   
 Substituting we have  $\omega = \frac{v}{r} = \frac{3.5 \times 10^{-2} \cdot \pi (1.5 \times 10^{-2})^2}{9.1 \times 10^{-31}}$   
 $\omega = 2.2 \times 10^{11} \text{ rad/s}$

Since cyclotron frequency is equal to angular speed, the cyclotron frequency is equal to  $2.2 \times 10^{11} \text{ rad/s}$ , having a unit as  $\text{rad/s}$  which is equal to the unit of frequency dimensionally.

5. We know that the flux through the magnetic field is directly proportional to the probability of the electron to tunnel through the energy barrier, the tunneling current is directly proportional to the square of the tunneling probability.

Magnetic field is a straight current carrying conductor.



Applying the Biot-Savart law and the magnitude of the field  $B$

$$B = \frac{\mu_0}{4\pi} \int \frac{I \times d\vec{l} \times \hat{r}}{r^2}$$

For a straight wire of length  $L$  and current  $I$ , the magnetic field at a distance  $r$  is

$$B = \frac{\mu_0 I}{4\pi r} \left( \frac{L}{r} \right) = \frac{\mu_0 I L}{4\pi r^2}$$

Substituting  $B$  into the tunneling probability equation

$$I = \frac{e n A v_d}{L} = \frac{e n A v_d}{L} \cdot \frac{4\pi r^2 B}{\mu_0}$$

Hence  $I \propto \frac{1}{r^2}$

Using special integrals

$$\int \frac{1}{(a^2 + x^2)^2} dx = \frac{x}{2(a^2 + x^2)} + \frac{1}{2a^2} \arctan\left(\frac{x}{a}\right)$$

Equation (1) can be used to solve for  $I$

$$I = \frac{e n A v_d}{L} \cdot \frac{4\pi r^2}{\mu_0} \int \frac{1}{(a^2 + x^2)^2} dx$$

$$I = \frac{e n A v_d}{L} \cdot \frac{4\pi r^2}{\mu_0} \left[ \frac{x}{2(a^2 + x^2)} + \frac{1}{2a^2} \arctan\left(\frac{x}{a}\right) \right]$$

When the length  $L$  of the conductor is very great in comparison to the distance  $r$  from point  $P$  we consider it infinitely long. That is,  $L \gg r$ , then  $a = r$ .

$$I = \frac{e n A v_d}{L} \cdot \frac{4\pi r^2}{\mu_0} \left[ \frac{x}{2(r^2 + x^2)} + \frac{1}{2r^2} \arctan\left(\frac{x}{r}\right) \right]$$

In a physical situation, we have a long cylindrical wire of radius  $r$ , then we will have a current  $I$  flowing through it. In this case, the magnetic field  $B$  is

$$B = \frac{\mu_0 I}{2\pi r}$$