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Civil Engineering

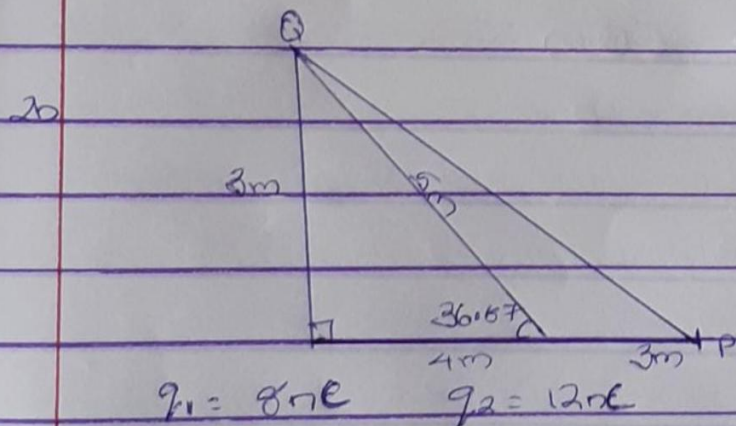
19/ENG103/017

Phy 102

Section A

2a Electric field refers to the region of space in which an electric field intensity charge will experience an electric force.

Electric field intensity refers to the force per unit charge at a point



$$E_1 = \frac{kq_1}{r^2} = \frac{(9 \times 10^9) \times (8 \times 10^{-9})}{3^2} \Rightarrow 1.47 \text{ N/C}$$

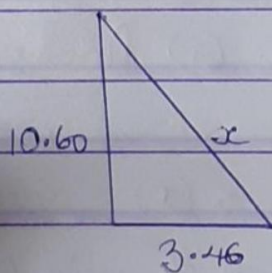
$$E_2 = \frac{kq_2}{r^2} = \frac{(9 \times 10^9) \times (12 \times 10^{-9})}{4^2} \Rightarrow 2.20 \text{ N/C}$$

$\therefore$  The net electric field at a point P  $\Rightarrow 3.67 \text{ N/C}$

$$E_1 = \frac{(9 \times 10^9) \times (8 \times 10^{-9})}{3^2} \Rightarrow 8.0$$

$$E_2 = \frac{(9 \times 10^9) \times (12 \times 10^{-9})}{5^2} \Rightarrow 4.32$$

$x$	$y$
$8 \times \cos(90)$	$8 \times \sin(90)$
$= 0$	$= 8$
$4.32 \times \cos(36.87)$	$4.32 \times \sin(36.87)$
$= 3.46$	$2.60$
$3.46$	$10.60$



$$r = \sqrt{(10.60)^2 + (3.46)^2}$$

3a) Volume Charge density

$$\rho = \frac{dq}{dV} \rightarrow dq = \rho dV$$

ii) Surface Charge density

$$\sigma = \frac{dq}{dA} \rightarrow dq = \sigma dA$$

iii) Linear Charge density

$$\lambda = \frac{dq}{dl} \rightarrow dq = \lambda dl$$

$$3b \quad dW = F \cdot dl \quad \dots (1)$$

$$F = -q_0 E \quad \dots (2)$$

Substituting equation (2) in (1)

$$dW = -q_0 E dl \quad \dots (3)$$

Then total work done in moving the test charge from A to B is

$$W(A \rightarrow B)_{q_0} = -q_0 \int_A^B E dl \quad \dots (4)$$

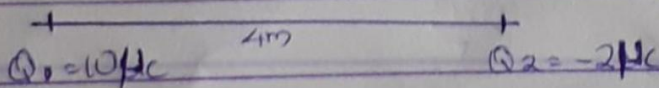
From the definition of electric potential difference it follows that

$$V_B - V_A = \frac{W(A \rightarrow B)_{q_0}}{q_0} \quad \dots (5)$$

Putting equation (4) in (5)

$$V_B - V_A = - \int_A^B E dl \quad \dots (6)$$

C



$$Q_1 = 10 \mu C \quad Q_2 = -2 \mu C$$
$$V = \frac{1}{4\pi\epsilon_0} \left[ \frac{Q_1}{r_1} + \frac{Q_2}{r_2} \right]$$
$$\frac{0}{9 \times 10^9} = \frac{10 \times 10^{-6}}{r_1} - \frac{2 \times 10^{-6}}{r_2}$$

$$2r = 10r_2 \quad ; \quad r_1 = 5r_2$$

A) Magnetic flux refers to the strength of a magnetic field represented by lines of force. It is usually represented by the symbol  $\Phi$

Given:  $q = 1.6 \times 10^{-19} \text{ C}$ ,  $r = 1.04 \times 10^{-7} \text{ m}$ ,  $B = 3.5 \times 10^{-1} \text{ Weber/m}^2$   
 $m = 9.11 \times 10^{-31} \text{ kg}$

Cyclotron frequency = Angular speed ( $\omega$ )

$$\omega = \frac{qB}{m} = \frac{1.60 \times 10^{-19} \text{ C} \times 3.5 \times 10^{-1}}{9.11 \times 10^{-31} \text{ kg}}$$
$$= 6.14 \times 10^{10} \text{ rad/s}$$

$\therefore$  The cyclotron frequency is  $6.14 \times 10^{10} \text{ rad/s}$

AC  $F_B = qvB \sin \theta$  where  $\theta = 90^\circ$

$$\therefore F_B = qvB$$
$$F_B = qvB = \frac{mv^2}{r}$$

Since the proton moves in a circular orbit, therefore

$$mv^2 = qBr$$

$$v = \frac{qBr}{mv} = \frac{1.6 \times 10^{-19} \times (3.5 \times 10^{-1}) \times (1.04 \times 10^{-7} \text{ m})}{9.11 \times 10^{-31}}$$

$$\therefore v = 8.06 \times 10^3 \text{ m/s}$$

From  $v = \frac{qBr}{mv}$ , we have that

$$\frac{v}{r} = \frac{qB}{m}$$

Since  $\frac{v}{r} = \omega$  (Angular Speed)

$$\omega = \frac{qB}{mp} \Rightarrow 1.60 \times 10^{-19} \times (3.5 \times 10^{-1})$$

$$9.01 \times 10^{-21}$$

$$\therefore \omega = 6.04 \times 10^{10} \text{ rad/s}$$

Hence Angular Speed = Cyclotron frequency

5a) Biot-Savart law states that the magnetic intensity  $dH$  at a point  $A$  due to currents ( $I$ ) flowing through a small element  $dl$  is

i) Directly proportional to current ( $I$ )

ii) Directly proportional to the sine of angle  $\theta$  between the direction of current and the line joining the element  $dl$  from  $A$

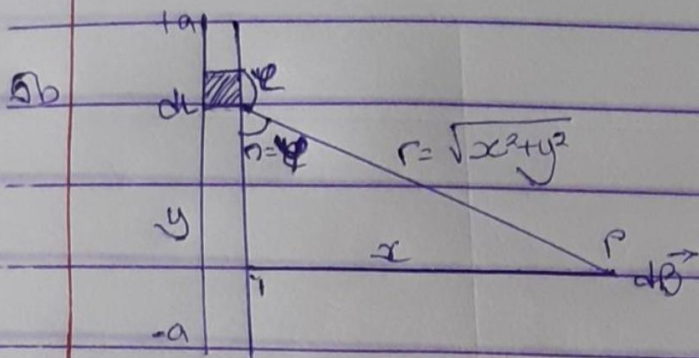
iii) Directly proportional to the length of the element ( $dl$ )

iv) Inversely proportional to the square of the distance  $r$  of point  $A$  from the element  $dl$ .

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I dl}{r^2} \times \hat{r}$$

Where  $\mu_0$  is a constant called permeability of free space

$\hat{r}$  is the unit vector directed from  $dl$  towards  $A$



Applying the Biot-Savart Law

$$B = \frac{\mu_0 I}{4\pi} \int_{-a}^a \frac{dl \sin \theta}{r^2}$$

$$\sin(\pi - \theta) = \sin \theta$$

$$\therefore B = \frac{\mu_0 I}{4\pi} \int_{-a}^a \frac{dl \sin(\pi - \theta)}{r^2}$$

$$\text{But } \sin(\pi - \theta) = \frac{x}{\sqrt{x^2 + y^2}} = \frac{x}{(x^2 + y^2)^{1/2}}$$

Then using special integrals

$$\int \frac{dy}{(x^2 + y^2)^{3/2}} = \frac{y}{x^2 (x^2 + y^2)^{1/2}}$$

$$\therefore B = \frac{\mu_0 I}{4\pi} \left[ \frac{y}{x^2 (x^2 + y^2)^{1/2}} \right]_{-a}^a$$

$$B = \frac{\mu_0 I}{2\pi x} \left( \frac{a}{(x^2 + a^2)^{1/2}} \right)$$

When the length  $2a$  of the conductor is very great in comparison to its distance  $x$  from point  $P$ , we consider it infinitely long. That is when  $a$  is much larger than  $x$

$$\therefore B = \frac{\mu_0 I}{2\pi x} \quad \text{since } (x^2 + a^2)^{1/2} \approx a, \text{ as } a \rightarrow \infty$$

In a physical situation, we have axial symmetry about the  $y$ -axis. Thus, at all points in a circle of radius  $r$ , around the conductor, the magnitude of  $B$  is  $B = \frac{\mu_0 I}{2\pi r}$