

19/ENG05/054

MECHATRONICS ENGINEERING

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$$(1) \quad x = t^2, \quad y = -5t^2 + 6, \quad z = t + 7$$

$$\therefore \mathbf{r} = t^2 \mathbf{i} + (-5t^2 + 6) \mathbf{j} + (t + 7) \mathbf{k}$$

$$\mathbf{v} = \frac{d\mathbf{r}}{dt} = 2t \mathbf{i} + (-10t + 1) \mathbf{j} + \mathbf{k}$$

$$\mathbf{a} = \frac{d\mathbf{v}}{dt} = 2 \mathbf{i} - 10 \mathbf{j}$$

$$(2) \quad \mathbf{P} = \mathbf{i} - 9\mathbf{j} - 4\mathbf{k}, \quad \mathbf{Q} = 8\mathbf{i} - 3\mathbf{j} + 6\mathbf{k}, \quad \mathbf{R} = \mathbf{i} - 4\mathbf{j} - 3\mathbf{k}$$

$$\begin{aligned} \mathbf{P} \times \mathbf{Q} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & -9 & -4 \\ 8 & -3 & 6 \end{vmatrix} = \begin{vmatrix} -9 & -4 \\ -3 & 6 \end{vmatrix} \mathbf{i} - \begin{vmatrix} 1 & -4 \\ 8 & 6 \end{vmatrix} \mathbf{j} + \begin{vmatrix} 1 & -9 \\ 8 & -3 \end{vmatrix} \mathbf{k} \\ &= (-54 - 12) \mathbf{i} - (6 + 32) \mathbf{j} + (-3 + 72) \mathbf{k} \\ &= -66 \mathbf{i} - 38 \mathbf{j} + 69 \mathbf{k} \end{aligned}$$

$$\begin{aligned} \mathbf{R} \times \mathbf{P} &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & -4 & -3 \\ 1 & -9 & -4 \end{vmatrix} = \begin{vmatrix} -4 & -3 \\ -9 & -4 \end{vmatrix} \mathbf{i} - \begin{vmatrix} 1 & -3 \\ 1 & -4 \end{vmatrix} \mathbf{j} + \begin{vmatrix} 1 & -4 \\ 1 & -9 \end{vmatrix} \mathbf{k} \\ &= (16 - 27) \mathbf{i} - (-4 + 3) \mathbf{j} + (-9 + 4) \mathbf{k} \\ &= -11 \mathbf{i} + \mathbf{j} - 5 \mathbf{k} \end{aligned}$$

$$(\mathbf{P} \times \mathbf{Q}) \cdot (\mathbf{R} \times \mathbf{P}) = (-66 \times -11) + (-38 \times 1) + (69 \times -5) = 343$$

$$(3) \quad \int \mathbf{F} = \int 5 \cos 7t \mathbf{i} - \int 2e^{3t} \mathbf{j} - \int t^3 \mathbf{k}$$

$$= \frac{5}{7} \sin 7t \mathbf{i} - \frac{2}{3} e^{3t} \mathbf{j} - t^4 \mathbf{k}$$