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SECTION A

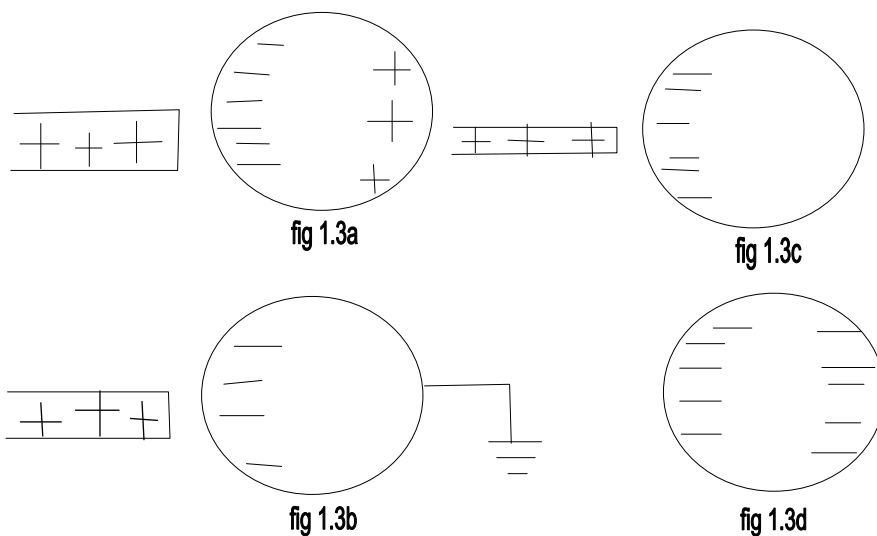
1a. Charging by Induction:

Electric charges can be obtained on an object without touching it, by a process called electrostatic induction.

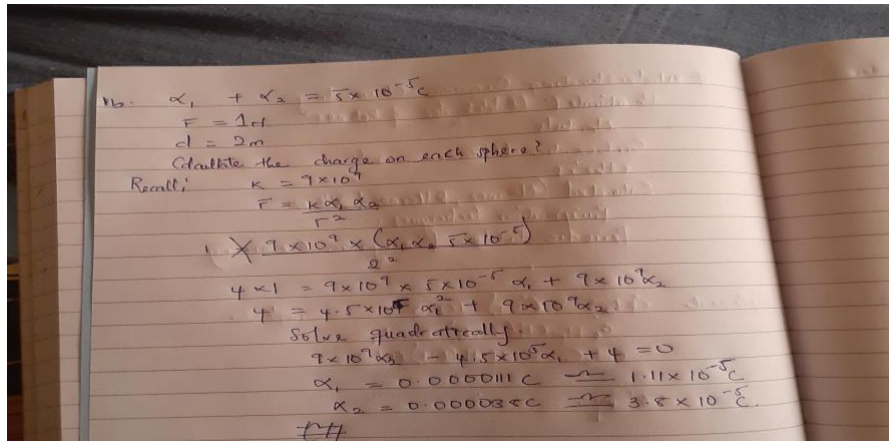
Consider a positively charged rubber rod brought near a neutral (uncharged) conducting sphere that is insulated so that there is no conducting path to ground as shown below. The repulsive force between the protons in the rod and those in the sphere causes a redistribution of charges on the sphere so that some protons move to the side of the sphere farthest away from the rod (fig. 1.3a). The region of the sphere nearest the positively charged rod has an excess of negative charge because of the migration of protons away from this location. If a grounded conducting wire is then connected to the sphere, as in (fig. 1.3b), some of the protons leave the sphere and travel to the earth. If the wire to ground is then removed (fig. 1.3c), the conducting sphere is left with an excess of induced negative charge.

Finally, when the rubber rod is removed from the vicinity of the sphere (fig. 1.3d), the induced negatively charge remains on the ungrounded sphere and becomes uniformly distributed over the surface of the sphere.

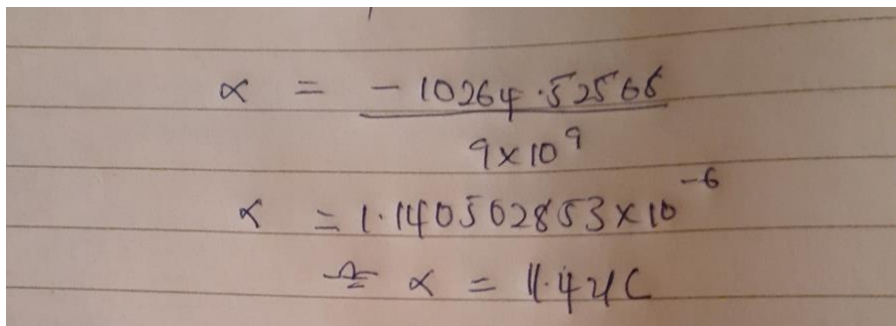
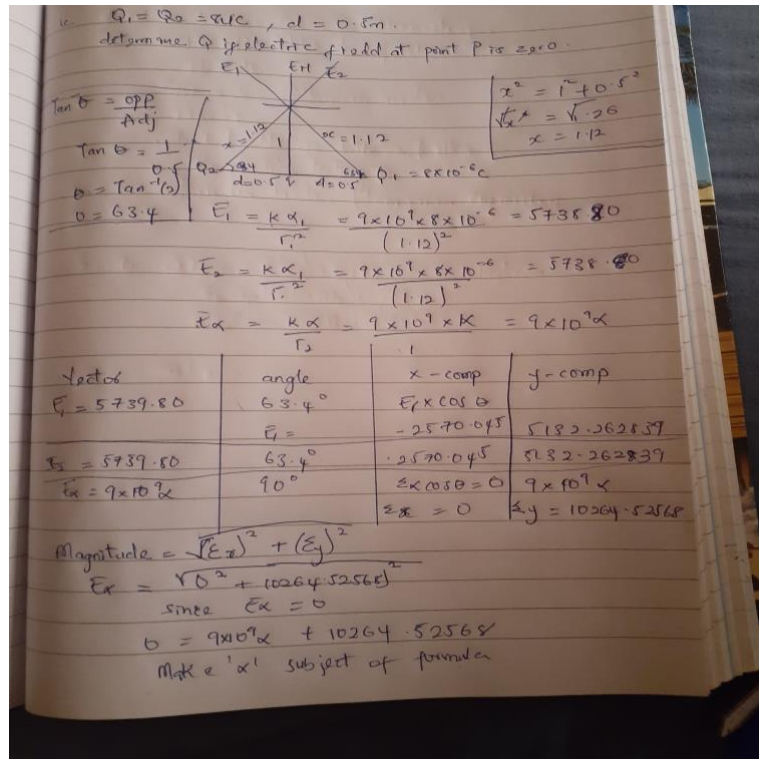
Diagram:



1b.



1c.



2a. Electric field is a region around a charge in which it exerts electrostatic force on another charge. While electric field intensity is the strength of electric field at any point in space, it is a vector quantity with N/C .

3a.

- (i) Volume charge density, $\rho = \frac{dQ}{dV} \rightarrow dQ = \rho dV$
- (ii) Surface charge density, $\sigma = \frac{dQ}{dA} \rightarrow dQ = \sigma dA$
- (iii) Linear charge density, $\lambda = \frac{dQ}{dL} \rightarrow dQ = \lambda dL$

3b. ELECTRIC POTENTIAL DIFFERENCE

The electric potential difference between two points in an electric field can be defined as the work done per unit charge against electrical forces when a charge is transported from one point to the other. It is measured in Volt (v) or Joules per Coulomb (J/C). Electric potential difference is a scalar quantity.

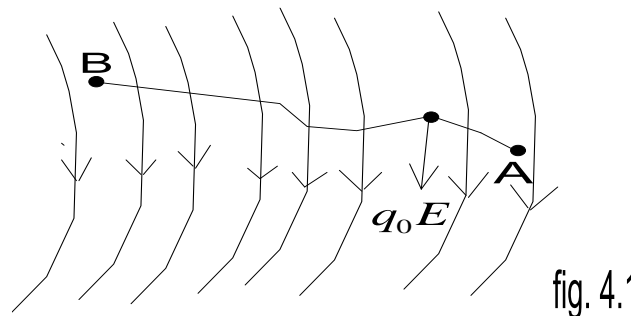


fig. 4.1

Consider the diagram above, suppose a test charge q_0 is moved from point A to point B along an arbitrary path inside an electric field E . The electric field E exerts a force $F = q_0 E$ on the charge as shown in fig 3.1. To move the test charge from A to B at constant velocity, an external force of $F = -q_0 E$ must act on the charge. Therefore, the elemental work done dW is given as:

$$dW = F \cdot dL \quad \dots \quad (1)$$

But

$$F = -q_0 E \quad \dots \quad (2)$$

Substituting equation (2) in (1) yields

$$dW = -q_0 E dL \quad \dots \quad (3)$$

Then total work done in moving the test charge from **A** to **B** is:

$$W(A \rightarrow B)_{Ag} = -q_0 \int_A^B E dL \quad \dots \quad (4)$$

From the definition of electric potential difference, it follows that:

$$V_B - V_A = \frac{W(A \rightarrow B)_{Ag}}{q_0} \quad \dots \quad (5)$$

Putting equation (4) in (5) yields

$$V_B - V_A = - \int_A^B E dL \quad \dots \quad (6)$$

SECTION B.

4a. magnetic flux is defined as the strength of the magnetic field which can be represented by line of forces. It is represented by the symbol Φ . mathematically given as $\Phi = B \cdot dA$

4c. In the question we were given parameters such as

i. mass of the electron = 9.11×10^{-31} kg

ii. A radius of 1.4×10^{-7} m

iii. magnetic field of 3.5×10^{-1} weber/meter square

and you are asked to find the cyclotron frequency which is equal or the same thing as angular speed. it is called cyclotron frequency because it is a frequency of an accelerator called cyclotron

Recall that angular speed is given as $\omega = \frac{v}{r} = \frac{qB}{m}$

Substituting we have $\omega = \frac{v}{r} = \frac{qB}{m} = \frac{1.6 \times 10^{-19} \times 3.5 \times 10^{-10}}{9.11 \times 10^{-31}} = 6.222222222222222 \times 10^7 \text{ T}^{-1}$

$$\frac{qB}{m} = \frac{1.6 \times 10^{-19} \times 3.5 \times 10^{-10}}{9.11 \times 10^{-31}} = 6.222222222222222 \times 10^7 \text{ T}^{-1}$$

4c. SO since cyclotron frequency is equal to angular speed the cyclotron frequency is equal to $= 6.222222222222222 \times 10^7 \text{ T}^{-1}$, having a unit as $1/\text{T}$ which is equal to the unit of frequency dimensionally.

5a. Biot-savart law states that the magnetic field is directly proportional to the product permeability of free space (μ_0), the current (I), the change in length, the radius and inversely proportional to square of radius (r^2). It can be represented mathematically by

$$d\vec{B} = \frac{\mu_0 I d\vec{l} \times \hat{r}}{4\pi r^2}$$

where μ_0 is a constant called Permeability of free space.

$$\mu_0 = 4\pi \times 10^{-7} \text{ T} \cdot \frac{\text{m}}{\text{A}}$$

The unit of \vec{B} is weber\metre square

5b. Magnetic Field of a Straight Current Carrying Conductor

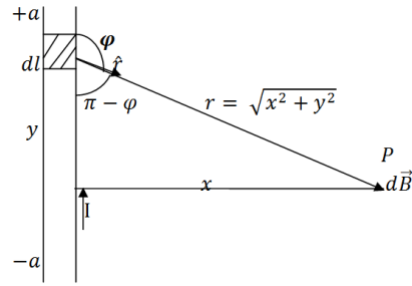


Fig 1: A section of a Straight Current Carrying Conductor

Applying the Biot-Savart law, we find the magnitude of the field $d\vec{B}$

$$B = \frac{\mu_0 I}{4\pi} \int_{-a}^a \frac{dl \sin \phi}{r^2}$$

$$\sin(\pi - \phi) = \sin \theta$$

$$\therefore B = \frac{\mu_0 I}{4\pi} \int_{-a}^a \frac{dl \sin(\pi - \phi)}{r^2}$$

From diagram, $r^2 = x^2 + y^2$ (*Pythagoras theorem*)

$$B = \frac{\mu_0 I}{4\pi} \int_{-a}^a \frac{dl \sin(\pi - \phi)}{x^2 + y^2} \quad \dots \quad (*)$$

$$\text{But } \sin(\pi - \phi) = \frac{x}{\sqrt{x^2 + y^2}} = \frac{x}{(x^2 + y^2)^{1/2}} \quad \dots \quad (**)$$

Substituting (**) into (*), we have

$$B = \frac{\mu_0 I}{4\pi} \int_{-a}^a dl \frac{x}{(x^2 + y^2)(x^2 + y^2)^{1/2}}$$

$$B = \frac{\mu_0 I}{4\pi} \int_{-a}^a dl \frac{x}{(x^2 + y^2)^{3/2}}$$

Recall $dl = dy$

$$B = \frac{\mu_0 I}{4\pi} \int_{-a}^a \frac{x}{(x^2 + y^2)^{3/2}} dy$$

$$B = \frac{\mu_0 I x}{4\pi} \int_{-a}^a \frac{1}{(x^2 + y^2)^{3/2}} dy \quad \dots \quad (***)$$

Using special integrals:

$$\int \frac{dy}{(x^2 + y^2)^{3/2}} = \frac{1}{x^2} \frac{y}{(x^2 + y^2)^{1/2}}$$

Equation (***) therefore becomes

$$B = \frac{\mu_0 I x}{4\pi} \left[\frac{y}{x^2(x^2 + y^2)^{1/2}} \right]_{-a}^a$$

$$= \frac{\mu_0 I x}{4\pi} \left(\frac{2a}{x^2(x^2 + a^2)^{1/2}} \right)$$

$$B = \frac{\mu_0 I}{4\pi x} \left(\frac{2a}{(x^2 + a^2)^{1/2}} \right)$$

When the length $2a$ of the conductor is very great in comparison to its distance x from point P, we consider it infinitely long. That is, when a is much larger than x ,

$$(x^2 + a^2)^{1/2} \cong a, \text{ as } a \rightarrow \infty$$

$$\therefore B = \frac{\mu_0 I}{2\pi x}$$

In a physical situation, we have axial symmetry about the y- axis. Thus, at all points in a circle of radius r , around the conductor, the magnet inside the coil magnetizes the portion of the string nearest the coil. When the

string vibrates at some frequency, its magnetized segment produces a changing

magnetic flux through the coil. The changing flux induces an emf in the coil that is

fed to an amplifier. The output of the amplifier is sent to the loudspeakers, which

produce the sound waves we hear. e of B is

$$B = \frac{\mu_0 I}{2\pi r} \quad \dots \quad (\#)$$

Equation (#) defines the magnitude of the magnetic field of flux density B near a long, straight current carrying conductor.

6. In the application of Faraday's law to electric guitar, the coil in this case known as the pickup coil, is placed near the vibrating guitar string, which is made of a metal that can be magnetized. A permanent magnet inside the coil magnetizes the portion of the string nearest to the coil. When the string vibrates at some frequency, its magnetized portion produces a magnetic flux through the coil. The changing flux induces an emf in the coil that is led to an amplifier. The output of the amplifier is left to the loudspeaker, which produces the sound we hear.

6b.