Name: Chikere Chibu-udom Matric Number: 19/ENG05/024 Department: Mechatronics Enineering Date of Submission: 25/04/2020 Course: MAT102 Department: Mechatronics Engineering

$$\pi = t^2$$
,  $y = -5t^2 + t$ ,  $2 = t + 7$   
 $Y = \pi i + y + 7 K$   
 $Y = t^2 + (-5t^2 + t) + (t + 7) K$ 

L

$$\frac{\text{velocity} = dr}{dt} = 2t_i + (-10t)j + (1)k$$

$$= 2ti - 10tj + K$$
  

$$\frac{d^{2}r}{dr^{2}} = 2i - 10j r$$

$$\begin{array}{c} If P = i - 9j - 4k \\ Q = 8i - 3j + 6k \\ R = i - 4j - 3k \\ find (P \times Q) \cdot (R \times P) \\ (P \times Q) = 1 \quad i \end{array}$$

$$\frac{(P \times Q)}{(P \times Q)} = \begin{bmatrix} i & j & K \\ 1 & -9 & -4 \\ 8 & -3 & 6 \end{bmatrix}$$

$$= i((-9 \times 6) - (-3 \times -4)) - j((1 \times 6) - (-4 \times 8))$$

$$= -66i - 38j + 75K$$

$$(R \times P) = \begin{bmatrix} i & j & K \\ j & K \end{bmatrix}$$

$$=i(\underbrace{((x-4)-(-3x-9))}_{j}((x-4)-(-3x))+k((x-9)-(-9x))$$
  
= -11i +j -5K  
-(PxQ) · (RxP) = (-66i - 38j + 75k) · (-11i + j - 5k)

) + K ((1x-3)-(-

= 313

3 F= 5 cos 7 ti - 203ti - 4t3 K dto =-5 sm7ti-2ej-t4K