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⇒ Solutions to System response II

Q1) given: $R = 47\Omega$, $C = 20\mu F = 20 \times 10^{-6} F$
 $V_i = 5 \sin(2000t)$

$$\frac{V_o(s)}{V_i} = \frac{1}{Ts + 1} \quad \text{but } T = RC$$

Soln

$$\frac{V_o}{V_i}(j\omega) = \frac{1}{1 + Tj\omega} = \frac{(1 - Tj\omega)}{(1 + Tj\omega)(1 - Tj\omega)}$$

$$\frac{V_o}{V_i}(j\omega) = \frac{1 - Tj\omega}{1 + T^2\omega^2} = \frac{1}{1 + T^2\omega^2} - \frac{jT\omega}{1 + T^2\omega^2}$$

recall: Phase angle, $\phi = \tan^{-1}\left(\frac{B}{A}\right)$

$$\text{but } B = \frac{T\omega}{1 + T^2\omega^2}$$

⇒ recall: $T = RC = 47 \times 20 \times 10^{-6} = 9.4 \times 10^{-4} \text{ sec}$

$$\phi = \frac{9.4 \times 10^{-4} \times 2000}{1 + (9.4 \times 10^{-4})^2 \times (2000)^2} = 0.4146$$

$$A = \frac{1}{1 + T^2\omega^2}$$

$$A = \frac{1}{1 + (9.4 \times 10^{-4})^2 \times (2000)^2} = 0.22053$$

$$\phi = \tan^{-1} \left(\frac{0.4146}{0.22053} \right) = -61.990^\circ \approx \underline{\underline{-62^\circ}}$$

The output voltage is given by

$$\text{mod } \frac{e_o}{e_i} = \sqrt{B^2 + A^2} = \sqrt{(0.4146)^2 + (0.22053)^2}$$

$$\text{mod } \frac{e_o}{e_i} = 0.4696$$

$$\text{Hence : Output Voltage} = 0.4696 \times 5$$

$$= \underline{\underline{2.348}}$$

$$\text{Therefore : } \underline{\underline{2.348 \sin(2000t - 62^\circ)}}$$

Q2) given : $T = 0.4 \text{ sec}$, damping ratio, $\delta = 0.2$

$$e_i = 6 \sin(\omega t), \quad \omega = 2.5 \text{ rad/s}$$

$$\frac{X_o}{X_i}(s) = \frac{1}{T^2 s^2 + 2\delta T s + 1}$$

$$\frac{X_o(j\omega)}{X_i} = \frac{1}{T^2(j\omega)^2 + 2\delta T j\omega + 1} = \frac{1}{(1 - T^2\omega^2) + 2\delta T j\omega}$$

$$\text{where : } A = 1 - T^2\omega^2$$

$$B = 2\delta T\omega$$

Similar to $\frac{X_o}{X_i} = A + jB$

$$\frac{X_o}{X_i} = \frac{1}{(A + jB)} \times \frac{A - jB}{A - jB} = \frac{A - jB}{A^2 + B^2}$$

$$\frac{X_o}{X_i} = \frac{A}{(A^2 + B^2)} - j \frac{B}{(A^2 + B^2)} = C - jD$$

$$\therefore C = \frac{1 - T^2 \omega^2}{(1 - T^2 \omega^2)^2 + (2ST\omega)^2}$$

$$D = \frac{2ST\omega}{(1 - T^2 \omega^2)^2 + (2ST\omega)^2}$$

$$\therefore A = 1 - T^2 \omega^2 = 1 - (0.4)^2 \times (2.5)^2 = 0$$

$$B = 2ST\omega = 2 \times 0.2 \times 2.5 \times 0.4 = 0.4$$

$$\text{but } C = \frac{A}{A^2 + B^2} = \frac{0}{0^2 + 0.4^2} = 0$$

$$D = \frac{B}{A^2 + B^2} = \frac{0.4}{0^2 + 0.4^2} = 2.5$$

Phase angle, $\phi = \tan^{-1} \left(\frac{b}{c} \right)$

$$\phi = \tan^{-1} \left(\frac{2.5}{0} \right) = \tan^{-1} (\infty) = \underline{\underline{90^\circ}}$$

Output amplitude:

$$\text{Mod} \left(\frac{x_o}{x_i} \right) = \sqrt{2.5^2 + 0^2} = 2.5$$

$$\therefore \text{Output amplitude} = 2.5 \times 6 = 15$$

Therefore: $15 \sin(2.5t + 90^\circ)$

Solutions to System response I

Q1) given that: $K_d = 0.03$
 $k = 4 \times 10^3 \text{ N/m}$

recall: $F(t) = kx$ (Spring)

$f(t) = K_d \frac{dx}{dt}$ (damper)

\Rightarrow let q $f(t) = f$

$$\therefore F = kx = K_d \frac{dx}{dt}$$

$$f = K_d \frac{dx}{dt} - Kx$$

$$f = K_d s - Kx$$

$$\frac{f}{x} = \frac{1}{K_d s + K} = \frac{1}{0.03 s + 4 \times 10^3}$$

Comparing with $\frac{\Theta_1}{\Theta_2} = \frac{1}{Ts + 1}$

$$\frac{f}{x} = \frac{\frac{1}{4 \times 10^3}}{\frac{0.03}{4 \times 10^3} s + 1} = \frac{250}{7.5 \times 10^{-6} s + 1}$$

∴ The time constant for the system = 7.5×10^{-6} sec
= 7.5 μs

$$\text{(iii)} \quad \dot{X}_0 = (F/k) (1 - e^{-t/\tau})$$

$$= (1000 \div 4000) (1 - e^{-1})$$

$$X_0 = 0.0158 \text{ m}$$

$$X_0 \approx \underline{0.016 \text{ m}} \quad \text{OK} \quad \underline{\underline{16 \text{ mm}}}$$

Q2 Given: mass = 0.5 kg, $c = 346 \text{ J/kg K}$, $\theta_1 = 20^\circ \text{C}$
 $\theta_2 = 120^\circ \text{C}$, @ $t = 6 \text{ min}$ $\theta = 119^\circ \text{C}$

take: $E_1 = \text{initial energy}$

$E_2 = \text{new energy}$

but $E_1 = mc\Delta\theta = mc(\theta_2 - \theta_1)$

$E_2 = mc\Delta\theta = mc(\theta - \theta_1)$

NOTE: $\theta = \text{new metal Temperature}$

$$G(s) = \frac{F_2}{F_1} = \frac{m\omega(\theta - \theta_1)}{m\omega(\theta_2 - \theta_1)} = \frac{1}{Ts + 1}$$

$$\frac{\theta - \theta_1}{\theta_2 - \theta_1} = \frac{1}{Ts + 1} \quad (\text{Cross multiply})$$

$$\theta - \theta_1 = \frac{\theta_2 - \theta_1}{Ts + 1}$$

$$\Rightarrow \text{assuming } \theta_2 - \theta_1 = kct$$

$$\theta - \theta_1 = \frac{kct}{Ts + 1}$$

$$\theta - \theta_1 = \frac{\frac{kct}{T}}{s + \frac{1}{T}}$$

The Laplace Transform of $kct = \frac{k}{s}$

$$\theta - \theta_1 = \frac{kct \left(\frac{1}{T}\right)}{s + \frac{1}{T}}$$

$$\therefore \theta - \theta_1(s) = \frac{k \left(\frac{1}{T}\right)}{s \left(s + \frac{1}{T}\right)}$$

\Rightarrow recalling ^{similar to} exponential growth

$$\theta - \theta_1(t) = k \left[1 - e^{-t/T} \right]$$

recalling ; $\theta_2 - \theta_1 = kct$

Hence

$$\theta - \theta_1 = (\theta_2 - \theta_1) \left[1 - e^{-t/T} \right]$$

recall $\theta(t) = \theta_1 + (\theta_2 - \theta_1)(1 - e^{-t/\tau})$

$\therefore 119 = 20 + (120 - 20)(1 - e^{-6/\tau})$

$119 = 20 + 100(1 - e^{-6/\tau})$

$0.99 = (1 - e^{-6/\tau})$

$0.99 - 1 = -e^{-6/\tau}$

$\pm 0.01 = \mp e^{-6/\tau}$

$\ln(0.01) = \ln(e^{-6/\tau})$

$-4.605 = -6/\tau$

$\tau = \frac{-6}{-4.605} = 1.304 \text{ minutes}$

$\tau = 1.304 \text{ minutes}$

$\tau = 78.24 \text{ seconds}$

Thermal capacitance, $C = mc$

$C = 0.5 \times 346$

$C = 173 \text{ J/K}$

$\therefore \tau = RC \Rightarrow$

$R = \frac{\tau}{C} = \frac{78.24}{173} = \underline{\underline{0.4522 \text{ K/W}}}$

$$Q3) - \frac{W}{K_m X} = \frac{1}{Ts + 1}$$

$$\text{but } T = \frac{J}{K_3}, \quad K_m = \frac{K_1 K_2}{K_3}$$

Soln

$$W = \frac{K_m X}{Ts + 1}$$

taking the Laplace transform of input step $1 - e^{-t/T}$

$$W(s) = \frac{K_m X}{s} \left(\frac{1}{Ts + 1} \right)$$

$$W(s) = \frac{K_m X}{s} \left(\frac{1/T}{s + 1/T} \right) \quad (*)$$

\Rightarrow eqn (*) being similar to exponential growth

$$\therefore W(t) = K_m X [1 - e^{-t/T}]$$

\Rightarrow The % Change in the output at $t=0$

$$= K_m X [1 - e^{-0/T}] = 0$$

at $t = T$

$$W(t) = K_m X [1 - e^{-T/T}] = 0.6321 K_m X$$

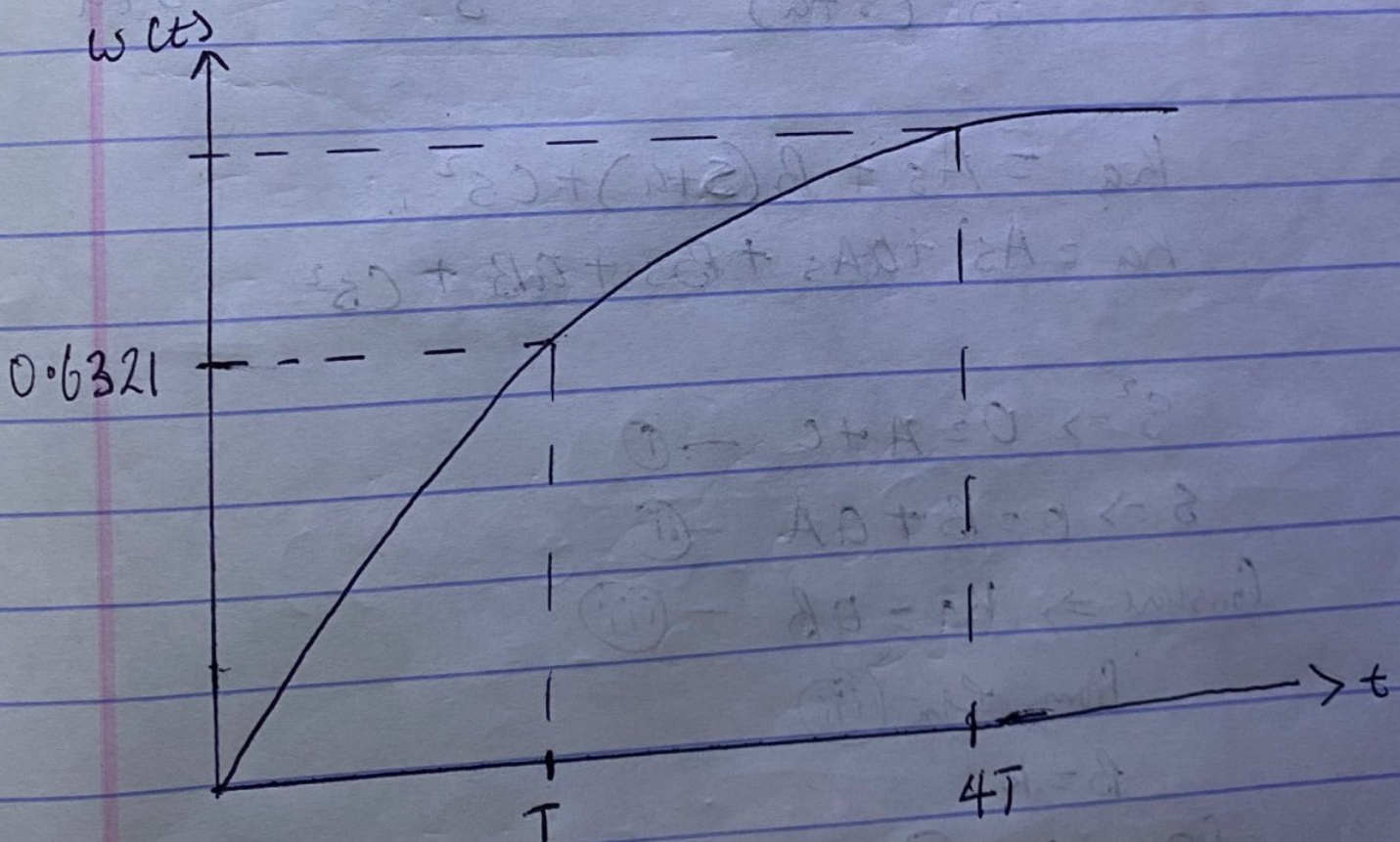
$$\text{at } t = T \\ = K_m \times \left[1 - e^{-\frac{4T}{T}} \right] = 0.98168 K_m$$

Hence for $t = T$

$$\% \text{ change in the output} = [0.6321 - 0] \times 100\% \\ = 63.21\% \approx \underline{\underline{63.2\%}}$$

for $t = 4T$

$$\% \text{ change in the output} = [0.98168 - 0] \times 100\% \\ = 98.168\% \approx \underline{\underline{98\%}}$$



Q4) Given: $G(s) = \frac{1}{3s+1}$

$\Rightarrow M_i (\text{Input}) = \frac{c}{s^2}$

Soln
 $M_o = \frac{C(s)}{s^2(3s+1)} = \frac{c \left(\frac{1}{3}\right)}{s^2\left(s+\frac{1}{3}\right)}$

where : $a = \frac{1}{3}$

$\therefore M_o = \frac{K_a}{s^2(s+a)} = \frac{A s + B}{s^2} + \frac{c}{s+a}$

$K_a = A s + B(s+a) + c s^2$

$K_a = A s^2 + a A s + B s + a B + c s^2$

$s^2 \Rightarrow 0 = A + c \quad \text{--- (i)}$

$s \Rightarrow 0 = B + a A \quad \text{--- (ii)}$

Constant $\Rightarrow K_a = a B \quad \text{--- (iii)}$

from eqn (iii)

$B = K$

from eqn (ii)

$$0 = B + aA \Rightarrow 0 = k + aA$$

$$-\frac{k}{a} = \frac{aA}{a} \Rightarrow A = \underline{\underline{-\frac{k}{a}}}$$

from eqn (i)

$$0 = A + C \Rightarrow 0 = -\frac{k}{a} + C$$

$$\therefore C = \underline{\underline{\frac{k}{a}}}$$

$$\therefore \frac{-\frac{k}{a}s + k}{s^2} + \frac{\frac{k}{a}}{s+a}$$

$$\text{recall: } a = \frac{1}{3}$$

$$k = c$$

$$M_0(s) = \frac{-\frac{k}{a}s + k}{s^2} + \frac{\frac{k}{a}}{s+a}$$

$$M_0(s) = \frac{-\frac{k}{a}s}{s^2} + \frac{k}{s^2} + \frac{\frac{k}{a}}{s+a}$$

$$M_0(s) = \frac{-k/a}{s} + \frac{k}{s^2} + \frac{\frac{k}{a}}{s+a}$$

$$m_0(t) = \frac{-c}{\frac{1}{3}} + ct + \frac{c}{\frac{1}{3}} e^{-\frac{1}{3}t} = -3c + ct + 3ce^{-\frac{1}{3}t}$$

$$m_0(t) = c(-3 + t + 3e^{-\frac{1}{3}t}) = c(t - 3 + 3e^{-\frac{1}{3}t})$$

$$m_0(t) = c(t - 3(1 - e^{-\frac{1}{3}t}))$$

NOTE: At large values of time t , the term $(e^{-\frac{1}{3}t})$ becomes negligibly small and hence

$$m_0(t) = c(t - 3) = ct - 3c$$

the error becomes; $M_e(t) = m_i - m_0$

$$M_e = ct - (ct - 3c) = ct - ct + 3c$$

$$\Rightarrow M_e = 3c$$

recall, $c = 4 \text{ mm/s}$; $T = 3$

\Rightarrow after 2 seconds

$$t = 2, T = 3, c = 4 \text{ mm/s}$$

$$\therefore m_i = ct = 4 \times 10^{-3} \times 2 = 8 \times 10^{-3} \text{ m}$$

$$m_0 = c(t - 3(1 - e^{-\frac{1}{3}t}))$$

$$m_0 = 4 \times 10^{-3} (2 - 3(1 - e^{-\frac{1}{3}(2)}))$$

$$m_0 = 2.161005 \times 10^{-3} \text{ m}$$

Hence, error, $M_e = m_i - m_0$

$$M_e = 8 \times 10^{-3} - 2.161005 \times 10^{-3}$$

$$M_e = 5.839 \times 10^{-3} \text{ mm}$$

∴ Steady state error, $M_e = 3e$
 $= 3 \times 4 \times 10^{-3} = \underline{\underline{12 \text{ mm}}}$

Q5) recall: DC gain is the magnitude of $G(s)$ when $s=0$

i) $G(s) = \frac{2}{0.2s + 0.5}$

Soln

$$G(s) = \frac{\frac{2}{0.5}}{\frac{0.2}{0.5}s + 1} = \frac{4}{0.4s + 1}$$

Hence: DC gain $\neq 4$, time constant = 0.4

ii) $G(s) = \frac{0.2}{0.05s + 0.1}$

Soln

$$G(s) = \frac{\frac{0.2}{0.1}}{\frac{0.05}{0.1}s + 1} = \frac{2}{0.5s + 1}$$

∴ DC gain = 2, time constant, $T = \underline{\underline{0.5}}$

$$\text{iii) } \frac{2}{3s+1} = G(s)$$

Soln

$$G(s) = \frac{\frac{2}{1}}{\frac{3s}{1} + 1} = \frac{2}{3s+1}$$

∴ DC gain = 2, Time Constant, $T = 3$

$$\text{iv) } G(s) = \frac{16}{8s+4}$$

Soln

$$G(s) = \frac{\frac{16}{4}}{\frac{8}{4}s + 1} = \frac{4}{2s+1}$$

∴ DC gain = 4, Time Constant, $T = 2$

$$\text{Q6) } \frac{W}{\Theta}(s) = \frac{K_m}{T_m s + 2}$$

where: $K_m = 15 S^{-1}$, $T_m = 4 \text{ Sec}$

Soln

$$\frac{W}{\Theta}(s) = \frac{15}{4s+2}$$

$$\frac{W(s)}{\Theta} = \frac{\frac{15}{2}}{\frac{4}{2}s + 1} = \frac{7.5}{2s + 1}$$

\therefore DC gain = 7.5 s^{-1} ; Time Constant = 2 seconds