

19/ENG04/064

300 LEVEL

ELECTRICAL & ELECTRONICS ENGINEERING

ELECTRICAL MACHINES TEST

EEE 326

Question 2

$$V_s = 415 \text{ V}$$

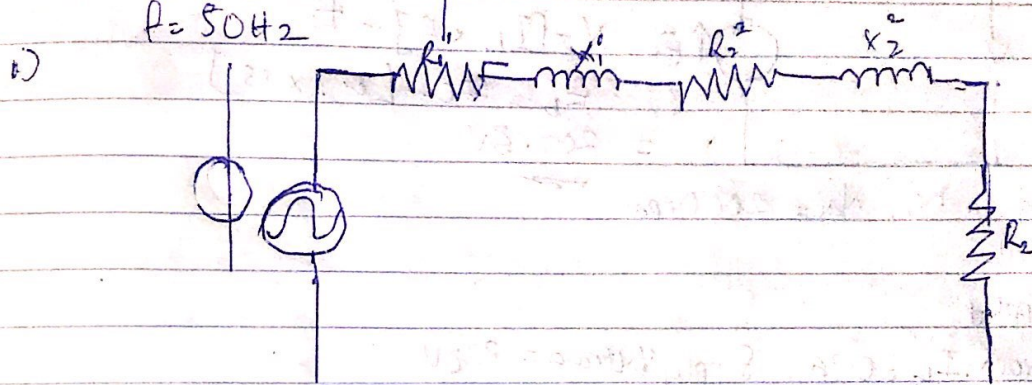
Number of poles = 6

$$k = \frac{5}{6} = 0.83$$

$$f = 50 \text{ Hz}$$

$$Z_1 = 0.25 + j0.75 \text{ (Stator)}$$

$$Z_2 = 1.173 + j0.52 \text{ (rotor)}$$



$$\text{Supply Voltage / phase} = V = \frac{415}{\sqrt{3}} = 239.60 \text{ V}$$

$$R_{01} = (R_2 + k^2 R_1)$$
$$= (1.173 + (0.83)^2 \times 0.25)$$
$$R_{01} = 1.347 \Omega$$

$$X_{02} = (X_2 + k^2 X_1)$$
$$= j(0.52 + (0.83)^2 \times 0.75)$$
$$= 1.041$$

$$Z_{01} = R_{01} + X_{02}$$

$$= 1.347 + j1.041$$
$$Z_{01} = \sqrt{1.347^2 + 1.041^2}$$
$$= 1.7 \Omega$$

ii) Rotor secondary current I_2

$$I_2 = \frac{E_2}{Z_{02}}$$

$$R_2 \text{ Recall } E_2 = KVL$$
$$= 239.6 \times 0.83$$
$$= 199.67 \text{ V}$$

$$\therefore I_2 = \frac{199.67}{1.7} = 117.45 \text{ A}$$

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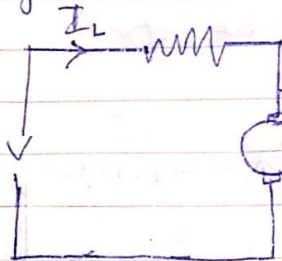
EEE 3 26 T6ST

Question 3

$N = 2000 \text{ rpm}$, $f = 50 \text{ Hz}$, $V = 220 \text{ V}$

On DC Supply

Supply Voltage = 220 V , Current $I = 0.7 \text{ A}$



$$V - E_b = I_L \times R$$

$$V - [I_L \times R] = E_b$$

$$E_b = 220 - [0.7 \times 15]$$

$$= 209.5 \text{ V}$$

Speed on DC, $N_{dc} = 2000 \text{ rpm}$

On AC Supply

Current drawn = $I_L = 0.7 \text{ A}$, Supply Voltage = 220 V

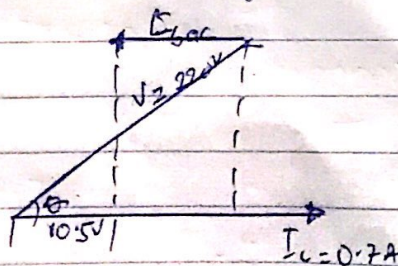
Resistance drop = $I_L \times R = 0.7 \times 15 = 10.5 \text{ V}$

Reactance voltage drop = $I_L \times X_L = 0.7 \times 2\pi fL$

where, $X_L = j\omega L = 2\pi fL$

$$= 0.7 \times 2\pi \times 50 \times 0.25$$

$$= 54.98 \text{ V}$$



$$E_{bac} = \sqrt{V^2 - [I_L R]^2} - I_L X_L$$

$$= \sqrt{(220)^2 - (10.5)^2} - 54.98$$

$$= 202.52 \text{ V}$$

1) Real Speed

Speed of the motor =

$$\text{Real speed} = \frac{N_2}{N_1} = \frac{E_{b2}}{E_{b1}} \quad \therefore \frac{E_{bac}}{E_{bdc}} = \frac{\omega_{ac}}{N_{dc}}$$

$$\text{Making } N_{ac} \text{ SOF} = N_{ac} = N_{dc} \times \frac{E_{bac}}{E_{bdc}}$$

$$= \frac{2000 \times 202.52 \text{ V}}{209.5 \text{ V}} = 1933.37 \text{ rpm}$$

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i) The power factor of the motor

$$\text{Power factor, } \cos \phi = \frac{E_{\text{back}} I_f}{V}$$

$$= \frac{202.52 + 10}{220} = 0.968 \text{ (lagging)}$$

ii) Torque developed by the motor

$$= T_w = E_{\text{back}} \times I_f$$

$$T_{\text{ac}} = \frac{E_{\text{back}} \times I_f}{\omega}$$

$$\omega = 2\pi n \quad n \text{ (speed in rev)}$$

$$T_{\text{ac}} = \frac{E_{\text{back}} \times I_f}{2\pi \times \frac{N_{\text{ac}}}{60}} = \frac{202.52 \times 0.7 \times 60}{2\pi \times 933.57} = 0.700 \text{ Nm}$$

iii) Universal motor should be used for this application

11/ENG/CA/064

Elect

ECE 326 TEST

Question 1

$V_L = 415\text{ V}$, 3 phase 4 wire $f = 50\text{ Hz}$, $P = 74.6$

Efficiency = 85% 4-wire \Rightarrow Y connected

$$V_L = 415$$

$$I_p = \frac{415}{\sqrt{3}}$$

$$= 239.6$$

$$V_L = \sqrt{3} V_p$$

$$V_p = \frac{V_L}{\sqrt{3}}$$

$$\Rightarrow \text{actual P.f.} = \cos \theta = 0.7$$

$$\theta = \cos^{-1} 0.7$$

$$= 45.57^\circ$$

$$\tan 45.57^\circ = 1.0201$$

i) Unity = 1

$$C = \frac{kVAR}{2\pi fV^2}$$

$$2\pi fV^2$$

$$\Rightarrow kVAR = P \times [\tan(\theta \text{ factor}) \times \tan(\theta \text{ target})]$$

target P.f.:

$$\Rightarrow 1 \therefore \cos \theta = 1$$

$$\theta = \cos^{-1}(1)$$

$$= 0$$

and $\tan 0 = 0$

$$\Rightarrow kVAR = 74.6 [1.0201 - 0]$$

$$= 76.10$$

$$C = \frac{76.10}{2 \times \pi \times 50 \times 239.6^2}$$

$$= 0.00000422 \approx 42.2 \times 10^{-6} \text{ F}$$

ii) 0.9 lagging

target P.f. $\cos \theta = 0.9$

$$\theta = \cos^{-1}(0.9)$$

$$\theta = 26.1^\circ$$

$$\tan \theta = 0.48$$

$$kVAR = 74.6 \times (1.0201 - 0.48)$$

$$= 111.70 \approx 112$$

$$C = \frac{kVAR}{2\pi fV^2}$$

$$2\pi fV^2$$

$$= 112$$

$$2\pi \times 50 \times 239.6^2$$

$$= 0.0000062$$

$$\approx 6.2 \times 10^{-6} \text{ F}$$