

17/Eng041041  
EEE 326

Electrical/Electronics  
300L

### Question 2

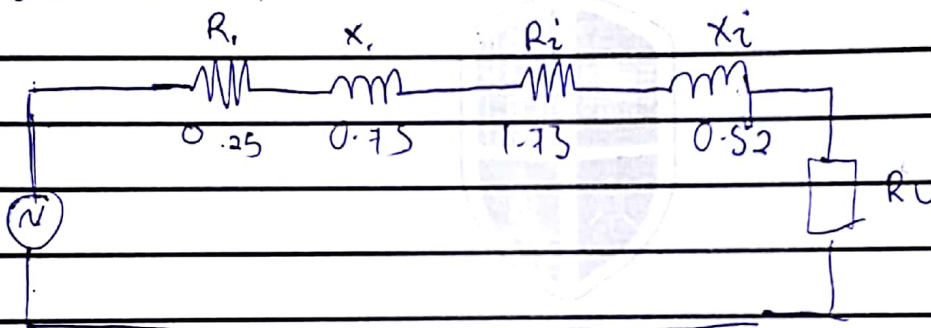
25 hp, 415V (line-line),  $G = \text{pole} = 1.6$

$f = 50 \text{ Hz}$        $k = 5/6$

$$Z_1 = 0.25 + j0.75 \quad Z_2 = 1.73 + j0.52$$

↓  
Stator

↓  
Rotor



$$\text{Supply Voltage } V = \frac{415}{\sqrt{3}} = 239.6$$

$$\Rightarrow 240 \text{ V}$$

relating to rotor

$$R_{oc} = (R_2 + k^2 R_1)$$

$$= (1.73 + (5/6)^2 \times 0.25) \Rightarrow 1.73 + 0.17361$$

$$= 1.3466 \Omega$$

$$R_{oc} \approx 1.347 \Omega$$

$$X_{oc} = (X_2 + k^2 X_1)$$

$$= 0.52 + (5/6)^2 \times 0.75 \Rightarrow 0.52 + 0.521$$

$$X_{oc} = 1.0408$$

$$\approx j1.041 \Omega$$

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$$Z_{02} = R_{02} + jX_{02}$$

300L

$$= 1.347 + j1.041$$

$$Z_{02} = 1.347 + j1.041$$

$$\text{angle} = \tan^{-1}(1.041/1.347)$$

$$= \sqrt{1.347^2 + 1.041^2}$$

$$\text{angle} = \tan^{-1}(0.7726)$$

$$= \sqrt{1.814409 + 1.083681}$$

$$= 37.69$$

$$= \sqrt{2.89809}$$

$$= 1.7023$$

$$Z_{02} = 1.7023 \angle 37.69$$

Rotor Current =

$$I_2 = \frac{E_2}{Z_{02}}$$

$$E_2 = kV_1$$

$$= \cancel{239} 240 \times 0.833$$

$$E_2 = 199.92V$$

$$I_2 = \frac{199.92}{1.7023} = 117.44A$$

Question 2



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$f = 50\text{Hz}$   $\frac{1}{4}$  p motor  $N = 2000\text{rpm}$

$V = 220\text{V DC source}$

$R = 15\Omega$

$I = 0.7\text{A}$

On DC supply

$V = 220\text{V}$

$I = 0.7\text{A}$

$$V - E_b = I_a \times R$$

$$V - (I_a \times R) = E_b$$

$$E_b = 220 - [0.7 \times 15]$$

$$= 220 - 10.5$$

$$= 209.5\text{V}$$

Speed on DC

$N = 2000\text{rpm}$

On AC supply

$$X_c = 2\pi f L$$

Supply  $V = 220\text{V}$

$I = 0.7\text{A}$

$$\text{Reactance drop} = I_c \times R = 0.7 \times 15 = 10.5\text{V}$$

$$\text{Reactance Voltage drop} = I_c \times X_c = 0.7 \times 2\pi f L$$

$$X_c = 2 \times 3.142 \times 50 \times 0.25$$

$$= 78.55$$

$$\Rightarrow I \times 78 = 0.7 \times 78.55 = 54.985\text{V}$$

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$$\begin{aligned}
 E_{bac} &= \sqrt{V^2 - [X_c I]^2} - I R \\
 &= \sqrt{(220)^2 - (54.96)^2} - 10.5 \\
 &= \sqrt{45377.1996} - 10.5 \\
 &= 213.01 - 10.5 \\
 &= 202.519 \text{ V}
 \end{aligned}$$

Speed relation

$$\frac{N_2}{N_1} = \frac{E_{s2}}{E_{s1}}$$

$$\frac{N_2}{N_1} = \frac{E_{s2}}{E_{s1}}$$

$$E_{sac} = \frac{N_{oc}}{N_{ac}}$$

make speed of AC just see

$$N_{ac} = \frac{E_{sac} \times N_{oc}}{E_{sdc}}$$

$$= \frac{202.519 \times 2000}{209.5}$$

$$= 0.966678 \times 2000$$

$$1) = 1933.36 \text{ rpm}$$

Power factor  $\Rightarrow$ 

$$11) \text{ Power factor} = \cos \theta = \frac{E_{sac} + I R}{V}$$

$$= \frac{202.52 + 0.7 \times 19}{220}$$

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Q3

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$$\text{(i)} \quad \frac{202.52 + 10.5}{220} \\ = \frac{213.02}{220}$$

$$\cos \phi = 0.968 = \text{Power factor}$$

(ii) Torque developed

$$T = \frac{E_{bav} \times I_c}{2\pi \times N_{av}} \\ \text{GO}$$

$$= \frac{202.52 \times 0.7 \times 3}{2 \times 3.142 \times 1933.33}$$

$$= \frac{41.764}{262.488}$$

$$\text{Torque} = 0.1591 \text{ Nm}$$

(iv) The type of motor is Universal motor

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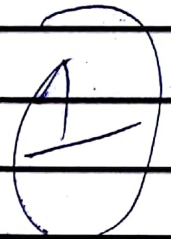
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Question 1

$V = 415 \text{ V}$ , 3- $\phi$  4 wire  $f = 50 \text{ Hz}$

$P = 74.6 \text{ kW}$   $\text{p.f.} = 0.7$   $\text{eff} = 85\%$



$C = \text{kVAR}$

$2\pi fV$

$\text{kVAR} = P \times$

actual  $\text{p.f.} = \cos \theta = 0.7$

$\theta = \cos^{-1} 0.7$

$\theta = 45.57$

$\tan^{-1}(45.57) = 1.0201$

Target  $\text{p.f.} = \cos \theta = 1$

$\theta = \cos^{-1}(1) = 0$

$\tan \theta = 0$

$\text{kVAR} = 74.6 \times (1.0201 - 0)$

$= 76.099$

$= 76.1$

$C = 76.10$

$= 1.4 \times 10^0 \text{ e}$

$2\pi \times 50 \times 415^2$

ii) 0.9 lagging

actual  $\text{p.f.} = 1.0201$

target  $\text{p.f.} = \cos \theta = \cos^{-1}(0.9)$

$\theta = 154.16$

$\tan \theta = \tan(154.16)$

$= -0.48$

$\text{kVAR} = 74.6 \times (1.0201 - 0.48)$

$= 111.90$

$\text{kVAR} \approx 112$



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C = KVAR

is Question 1

274V

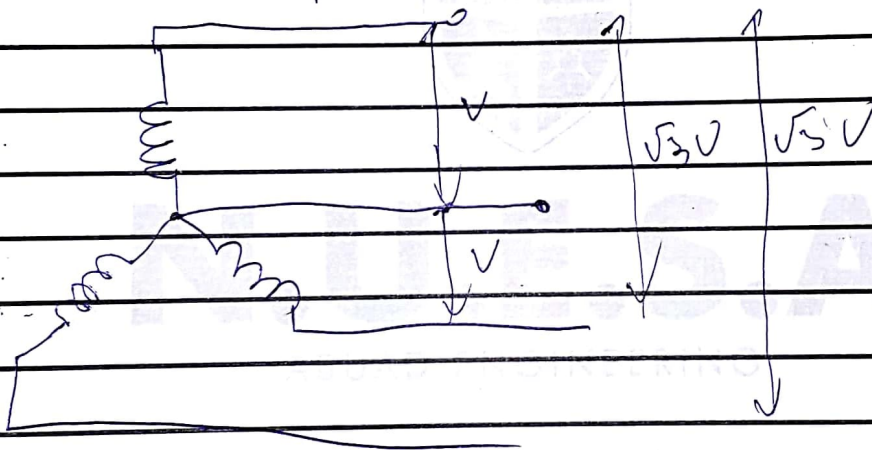
= 111.9

$$2 \times 3.142 \times 50 \times \frac{415}{\sqrt{3}}$$

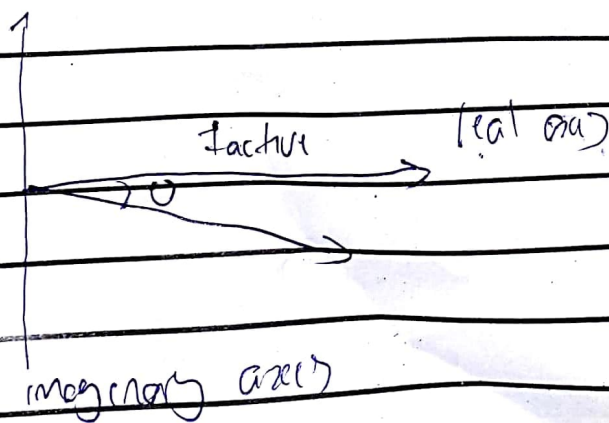
$$= 1.462 \times 10^{-6} C$$

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1) It is a Three phase induction motor



Phasor diagram



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