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①

$$V = 400V, \text{ 3-}\phi,$$

4-wire

$$f = 50\text{Hz}$$

$$P = 74.6$$

$$\text{P.f} = 0.7$$

$$\% \text{eff} = 85\%$$

3- $\phi$

②

$$I \text{ unity} = I$$

$$C = \frac{\text{KVAR}}{2\pi f V^2}$$

$$\rightarrow \text{KVAR} = P \times (\tan \text{actual P.f} - \tan \text{target P.f})$$

$$\text{actual P.f} \Rightarrow \cos \theta = 0.7$$

$$\theta = \cos^{-1} 0.7$$

$$= 45.57$$

$$\tan(45.57) = 1.0201$$

$$\text{Target P.f} \Rightarrow \cos \theta = 1$$

$$\theta = \cos^{-1} 1 = 0$$

$$\tan 0 = 0$$

$$\text{KVAR} = 74.6 \times (1.0201 - 0)$$

$$= 76.0995 \approx 76.10$$

$$C = \frac{76.10}{2\pi \times 50 \times 400^2}$$

$$= \frac{76.10}{251327400} = 3.028 \times 10^{-7} \text{ F}$$

$$= 302.8 \text{ nF}$$

$$\approx 42.2 \times 10^{-6} \text{ F}$$

⑤ 0.9 Lagging

$$\text{actual P.f} = 1.020$$

$$\text{target P.f} = \cos \theta = 0.9$$

$$\theta = \cos^{-1}(0.9)$$

$$= 26.74^\circ$$

$$\tan \theta = 0.48$$

$$\text{KVAR} = 74.6 \times (1.020 - 0.9)$$

$$= 111.90 \approx 112$$

$$C = \frac{\text{KVAR}}{2\pi fV}$$

$$= \frac{112}{2 \times \pi \times 50}$$

$$= 112$$

$$2 \times \pi \times 50 \times 112 = 239.6^2$$

$$= \frac{239.6^2}{2 \times \pi \times 50} = 0.0000062$$

$$= 6.2 \times 10^{-6} \text{ F}$$

Question 2.

$$V_{out} = 415V$$

$$\text{No. of Poles} = p = 6$$

$$f = 50 \text{ Hz}$$

$$K = 5/6 = 0.83$$

$$R \times Z_1 = 0.25 + j0.75 - \text{stator}$$

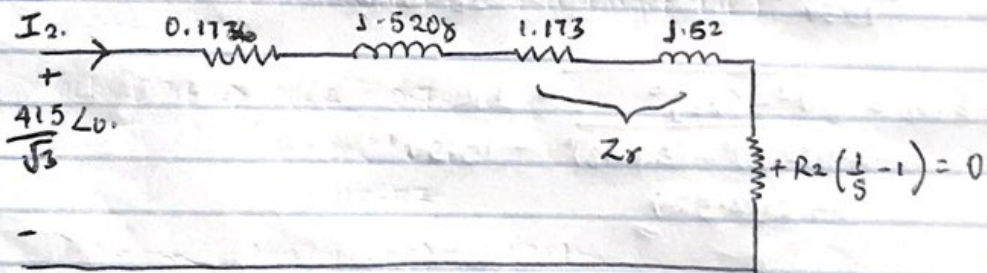
$$Z_2 = 1.173 + j0.52 - \text{rotor.}$$



$Z'_3$  = stator impedance refers to rotor side

$$Z'_3 = (0.25 + j0.75) \times (5/6)^2$$

$$Z'_3 = (0.1736 + j0.5208) \Omega$$



$$\therefore \frac{R_2}{s} \left( \frac{1}{s} - 1 \right) = 0$$

↳ mechanical load

$$\text{as @ at } s = 1, R_2 \left( \frac{1}{s} - 1 \right) = 0$$

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(b) From the approximate circuit of Part (a)

$$I_2 = \frac{4/5\sqrt{3}}$$

$$(0.1736 + 1.173) + j(0.3208 + 0.52)$$

$$I_2 = 140.780 \angle -37.70^\circ \text{ A}$$

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Question 3

$$F = 50 \text{ Hz},$$

$$1/4 \text{ HP}$$

$$N = 2000 \text{ rpm}$$

$$V = 220 \text{ V}$$

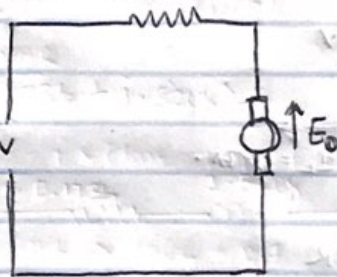
$$15 \Omega$$

$$0.25 \text{ H}$$

On DC Supply:

$$\text{Supply Voltage} = 220 \text{ V}$$

$$\text{Current draws, } I = 0.7 \text{ A}$$



$$V - E_b = I_2 * R$$

$$V - [I_2 * R] = E_b$$

$$E_b = 220 - [0.7 * 15]$$

$$= 209.5 \text{ V}$$

Speed on DC;

$$n_{10} = 2000 \text{ rpm}$$

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On AC Supply

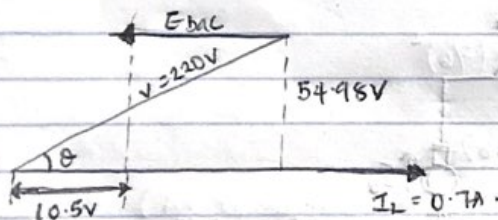
$$\text{Supply voltage} = 220\text{V}$$

$$\text{Current drawn, } I_L = 0.7\text{A}$$

$$\begin{aligned} \text{Reactance drop} &= I_L \times R = 0.7 \times 15 \\ &= 10.5\text{V} \end{aligned}$$

$$\begin{aligned} \text{Reactance voltage drop} &= I_L \times X_L \\ &= 0.7 \times 2\pi fL \end{aligned}$$

$$\begin{aligned} \text{where } X_L &= j\omega L = 2\pi fL \\ &= 0.7 \times 2\pi \times 30 \times 0.25 \\ &= 54.95\text{V} \end{aligned}$$



$$\begin{aligned} E_{bac} &= \sqrt{V^2 - (X_L)^2} - IR \\ &= \sqrt{(220)^2 - (54.95)^2} - 10.5\text{V} \\ &= 202.52\text{V} \end{aligned}$$

Real speed - constant its equation

$$\frac{N_2}{N_1} = \frac{E_{b2}}{E_{b1}}$$

$$\text{So } \frac{E_{bac}}{E_{bac}} = \frac{N_{ac}}{N_{ac}}$$

making  $N_{ac}$  subject of the formula

$$N_{ac} = \frac{N_{dc} \times E_{bac}}{E_{bdc}}$$

$$= 2000 \times \frac{202.52\text{V}}{209.5\text{V}}$$

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$$N_{ac} = 1933.31 \text{ rpm}$$

$$\begin{aligned} \text{Power Factor, } \cos \phi &= \frac{E_{bac} + IR}{V} \\ &= \frac{202.52 + 10.5}{220} \\ &= 0.968 \text{ Lagging} \end{aligned}$$

$$\text{Torque developed } T_w = E_{bac} \times I$$

$$T_{ac} = \frac{E_{bac} \times I}{\omega}$$

where  $\omega$  is in speed in rad/s

$$\omega = 2\pi n, \text{ where } n \text{ is in rpm}$$

$$\begin{aligned} T_{ac} &= \frac{E_{bac} \times I}{2\pi \times \frac{N_{ac}}{60}} \\ &= \frac{202.52 \times 0.7 \times 60}{2\pi \times 1933.31} \\ &= 0.700 \text{ Nm} \end{aligned}$$