

~~Power Factor~~

18/ Eng 04/060

Electrical / Electronics Engineering

EE 326: Electrical machines

Test ...

①

$V = 415 \text{ V}$, 3- ϕ , 4-wire, $f = 50 \text{ Hz}$, $P = 74.6$
 $\text{P.f} = 0.7$, % eff = 85%

②

i) Unity = 1.

$$C = \frac{\text{KVAR}}{2\pi f V^2}$$

$$\rightarrow \text{KVAR} = P \times (\tan \text{ actual p.f} - \tan \text{ target p.f})$$

$$\text{actual p.f} \Rightarrow \cos \theta = 0.7$$

$$\theta = \cos^{-1} 0.7$$

$$= 45.57$$

$$\tan(45.57) = 1.0201$$

$$\text{target p.f} \Rightarrow \cos \theta = 1$$

$$\theta = \cos^{-1} 1 = 0$$

$$\tan 0 = 0$$

$$\text{KVAR} = 74.6 \times (1.0201 - 0)$$

$$= 76.0995$$

$$\approx 76.10$$

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$$C = \frac{74.10}{2\pi \times 50 \times 415^2}$$
$$= \frac{0.00058}{0.000014}$$
$$\approx \frac{5.8 \times 10^{-4}}{1.4 \times 10^{-6}} \mu\text{F} \approx 1.4 \times 10^{-6} \mu\text{F}$$

ii) 0.9 lagging.

$$\text{actual p.f.} = 1.0201$$

$$\text{target p.f.} = \cos \theta = -0.9$$
$$\theta = \cos^{-1}(-0.9)$$
$$= 154.16^\circ$$

$$\tan \theta = -0.48$$

$$\text{KVAR} = 74.6 \times (1.0201 - (-0.48))$$
$$= 111.90$$
$$\approx 112$$

$$C = \frac{\text{KVAR}}{2\pi f V}$$

$$= \frac{112}{2\pi \times 50 \times 415^2}$$
$$= \frac{0.00006}{0.0000207}$$
$$\approx \frac{8.6 \times 10^{-4}}{20.7 \times 10^{-6}} \mu\text{F}$$
$$= 20.7 \times 10^{-6} \mu\text{F}$$

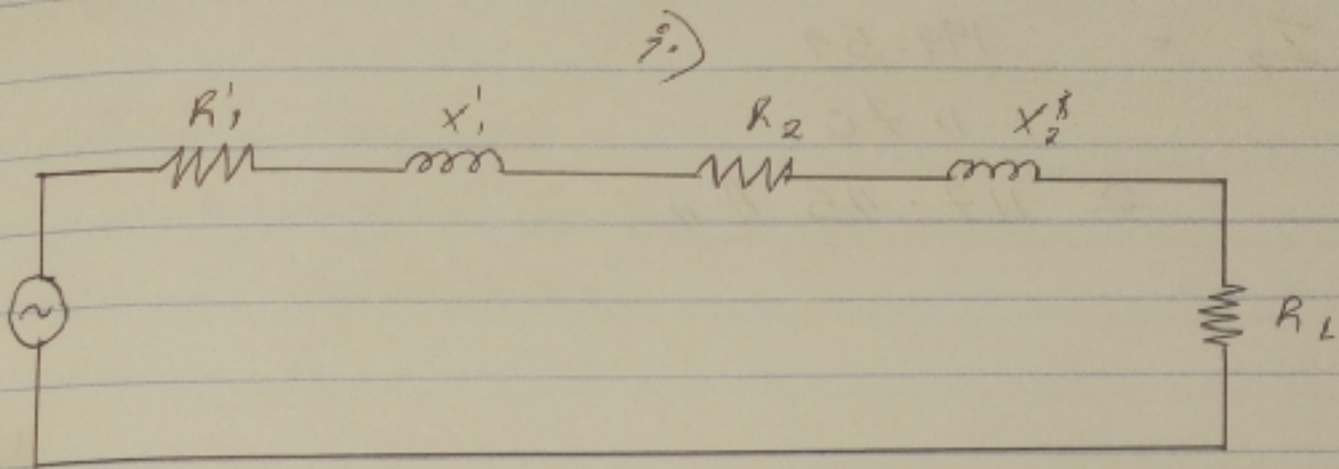
No 2.

$$k_p = 25, \quad V_{LL} = 415, \quad 6\text{-pole}, \quad f = 50 \text{ Hz.}$$

$$Y-Y, \quad 3-\phi, \quad k/V_p \text{ ratio} = \frac{6}{5} \left(\frac{5}{6} \right) \approx 0.833$$

$$Z_s = (0.25 + j0.75) \Omega, \quad Z_r = (1.173 + j0.52)$$

approx circ Ver 2. to rotor.



$$V_{LL} = 415.$$

$$V_p \approx \frac{415}{\sqrt{3}} = 239.66 \text{ V.}$$

$$\begin{aligned} R_2^* &= (R_2 + k^2 R_1) \\ &= (1.173 + 0.833^2 \times 0.25) \\ &= \text{N/A/B/A/n/a/n.} \quad 1.35 \Omega. \end{aligned}$$

$$\begin{aligned} X_2^* &= (X_2 + k^2 X_1) \\ &= (0.52 + 0.833^2 \times 0.75) \\ &= j1.04 \Omega. \end{aligned}$$

$$\begin{aligned} Z_s^* &= R_2^* + X_2^* \\ &= 1.35 + j1.04 \\ &\approx 1.70 \angle 37.61^\circ \Omega \end{aligned}$$

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$$\text{rotor current, } \bar{I}_2 = \frac{E_2}{Z_{e2}}$$

$$E_2 = K V_f$$

$$= 0.833 \times 239.60$$

$$= 199.59 \quad = 199.59$$

$$\bar{I}_2 = \frac{199.59}{1.70}$$

$$= 117.45$$

$$\approx 117.45 \text{ A}$$

NO 3

$f = 50 \text{ Hz}$, $\frac{1}{4} \text{ hp}$, $N_s = 2000 \text{ rpm}$, $I = 0.7 \text{ A}$,
 $V = 220 \text{ V}$, $r = 15 \Omega$, $L \text{ or } X = 0.25 \text{ H}$.

Determine when A.C; $V = 220$, $f = 50 \text{ Hz}$, $I = 0.7 \text{ A}$.

Soln.

Eq.

$$E_{dc} = V - IR \\ = 220 - (0.7 \times 15) \\ E_1 = 209.5 \text{ V}$$

$$E_{ac} = \sqrt{V^2 - (IX_L)^2} - IR \\ = \sqrt{220^2 - (IX_L)^2} - 10.5$$

$$* X_L = 2\pi fL \\ = 2 \times \pi \times 50 \times 0.25 \\ = 78.54$$

$$E_{ac} = \sqrt{(220)^2 - (0.7 \times 78.54)^2} - 10.5 \\ E_2 = 202.52 \text{ V}$$

i) Speed of the motor.

$$\frac{E_2}{E_1} = \frac{N_2}{N_1}$$

$$N_2 = \frac{N_1 \times E_2}{E_1} \\ = \frac{2000 \times 202.52}{209.5}$$

$$N_2 = 1933.37 \text{ rpm} //$$

ii) Power factor of motor.

$$P.f = \frac{E_2 + IA}{V}$$

$$= \frac{202.52 + 10.5}{220}$$

$$= 0.97 //$$

iii) Torque developed by motor.

$$T = \frac{E_2 \cdot I}{2\pi N_2 / 60}$$

$$= \frac{202.52 \times 0.7}{(2\pi \times 1933.37) / 60}$$

$$= 0.700$$

$$\approx 0.7 \text{ Nm} //$$

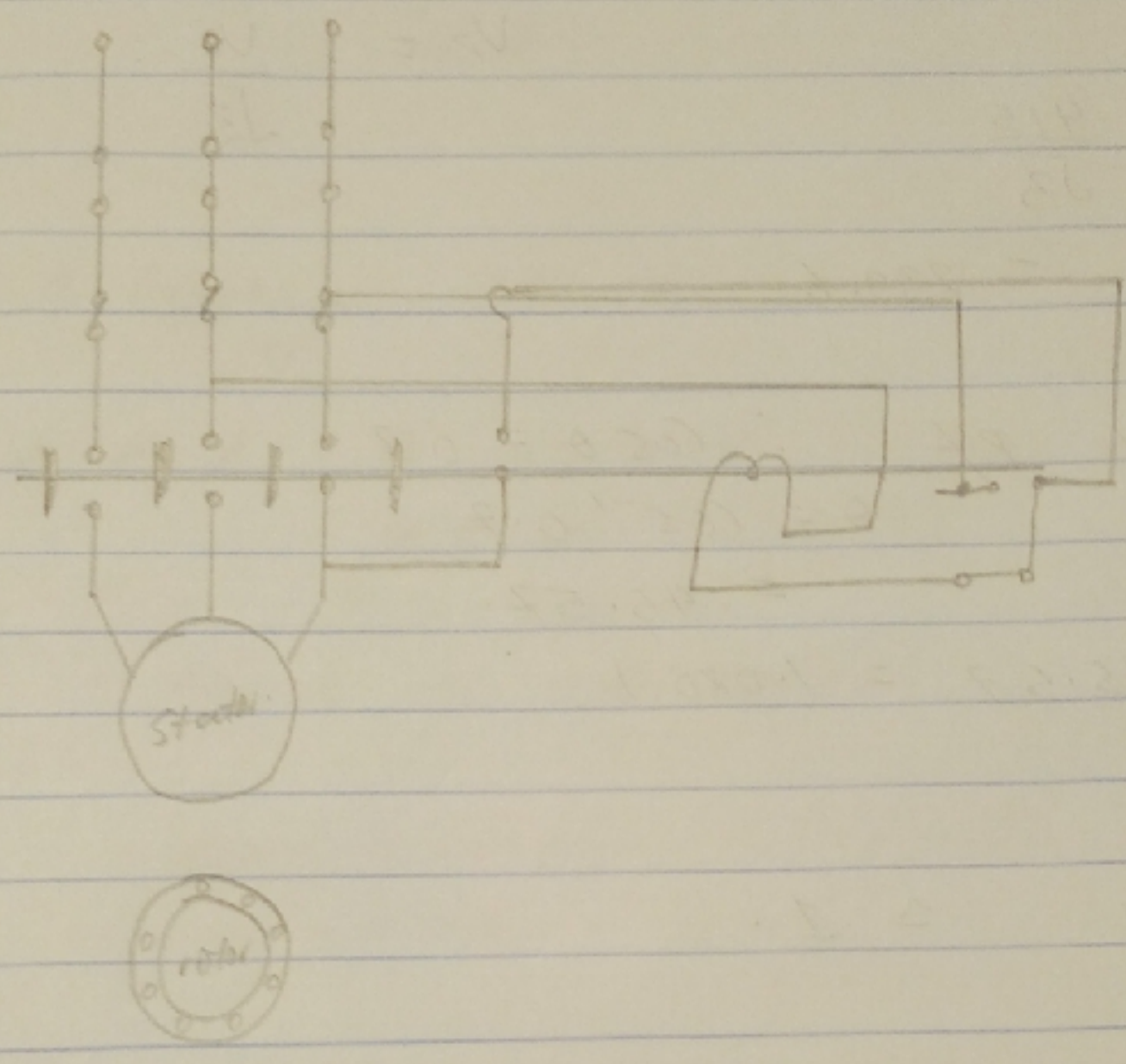
iv) This is a universal motor.

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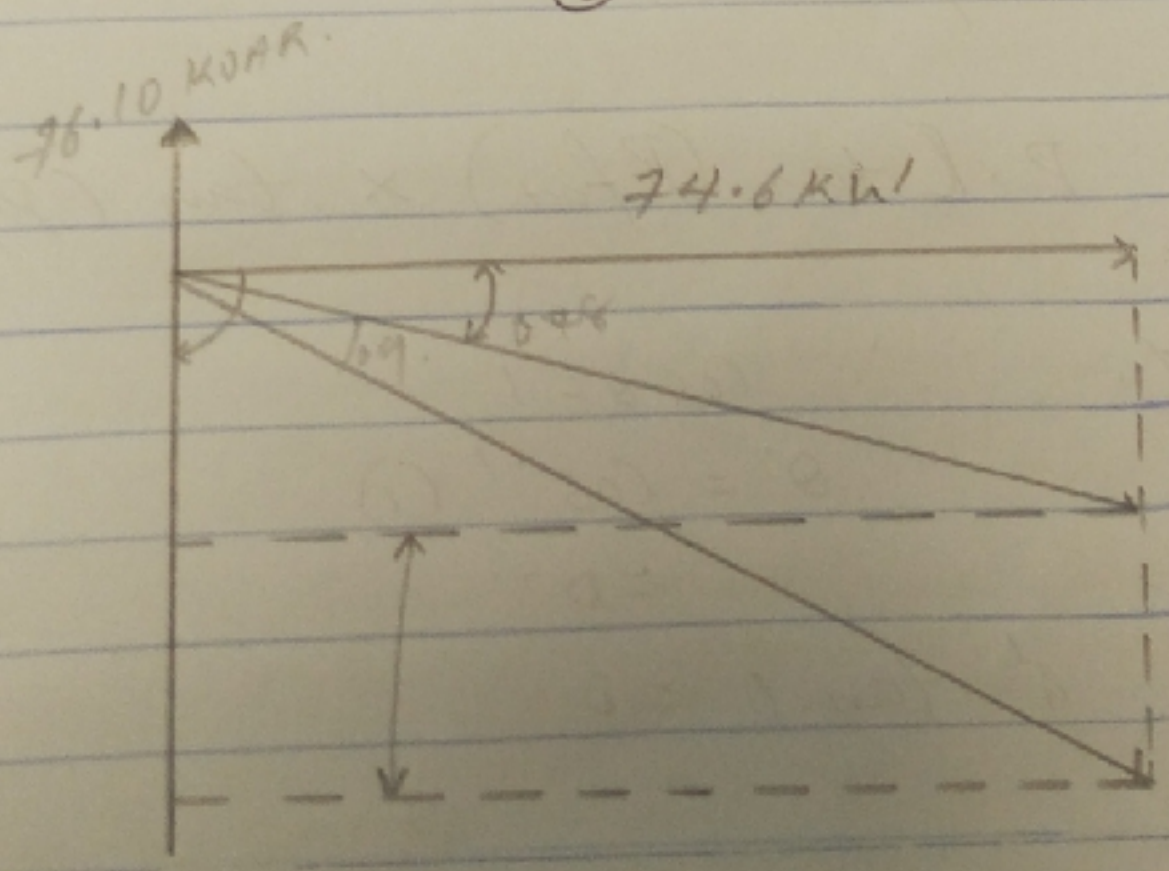
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no 1.

The drive motor type is a three-phase induction motor or 3- ϕ synchronous motor.



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NO 1

$V_L = 415 \text{ V}$, 3- ϕ , 4-wire, $f = 50 \text{ Hz}$, $P = 746$

P.f = 0.7, % efficiency = 85%

4-wire \approx Δ -connected.

$$\therefore V_L = 415$$

$\frac{1}{4}$

$$V_L = \sqrt{3} V_P$$

$$V_P = \frac{V_L}{\sqrt{3}}$$

$$V_P = \frac{415}{\sqrt{3}}$$

$$= 239.6$$

i) \rightarrow actual P.f $\therefore \cos \theta = 0.7$

$$\theta = \cos^{-1} 0.7$$

$$= 45.57$$

$$\tan 45.57 = 1.0201$$

$\frac{1}{4}$

ii) unity ≈ 1 .

$$C = \frac{\text{KVAR}}{2\pi f V^2}$$

$$\rightarrow \text{KVAR} = P \times [\tan(\text{P.f. fact}) \times \tan(\text{P.f. target})]$$

target P.f:

$\Rightarrow 1$

$$\therefore \cos \theta = 1$$

$$\theta = \cos^{-1}(1)$$

$$= 0$$

$$\frac{1}{4} \tan 0 = 0$$

(9)

$$\therefore \Rightarrow \text{KVAR} = 74.6 [1.0201 - 0] \\ = 76.10$$

$$\therefore C = \frac{76.10}{2 \times \pi \times 50 \times 239.6^2} \\ = 0.00000422 \\ \approx \cancel{4.22 \times 10^{-6}} \text{ C}_H \dots \\ \approx 4.2 \times 10^{-6} \text{ C}_H \dots$$

$$I_C = \sqrt{2\pi f C} \\ = 239.6^2 \times 2 \times \pi \\ \times 50 \times 4.2 \times 10^{-6} \\ = 75.75 \text{ A}_H$$

$$\text{ii)} \quad 0.9 \text{ lagging} \approx -0.9$$

$$\text{target p.f} \approx \cos \theta = -0.9$$

$$\theta = \cos^{-1}(-0.9)$$

$$\theta = 154.16$$

$$\tan \theta = -0.48$$

$$\text{KVAR} = 74.6 \times (1.0201 - (-0.48)) \\ = 111.90 \approx 112$$

$$C = \frac{\text{KVAR}}{2\pi f V^2} \\ = \frac{112}{2\pi \times 50 \times 239.6^2} \\ = 0.0000062 \\ \approx 6.2 \times 10^{-6} \text{ C}_H \dots$$

$$I_C = \sqrt{2\pi f C} \\ = 239.6^2 \times 2 \times \pi \times 50 \times 6.2 \times 10^{-6} \\ = 111.82 \text{ A}_H \dots$$