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17/ENIG06/085

Mechanical Engineering

Question 1!

b)

415V

3-phase

4-wire

50Hz

0.7 lagging

85%

i) Unity = F

$$C = \frac{\text{KVAR}}{2\pi f V^2}$$

$$\rightarrow \text{KVAR} = P \times (\tan \text{ actual P.f} \times \tan \text{ target P.f})$$

$$\text{actual P.f} = \cos \theta = 0.7$$

$$\theta = \cos^{-1} 0.7$$

$$= 45.57$$

$$\tan(45.57) = 1.0201$$

$$\text{target P.f} \Rightarrow \cos \theta = 1$$

$$\theta = \cos^{-1} 1 = 0$$

$$\tan \theta = 0$$

$$\text{KVAR} = 74.6 \times (1.0201 - 0)$$

$$= 76.0995$$

$$\approx 76.10 //$$

$$Q = \frac{76.10}{2 \times \pi \times 50 \times \left(\frac{415}{\sqrt{3}}\right)^2} = 0.000014 \approx 1.4 \times 10^{-6} //$$

ii) 0.9 lagging

$$\text{actual } P_f = 10201$$

$$\text{target } P_f = \cos \theta = 0.9$$

$$\theta = \cos^{-1}(0.9)$$

$$= 26.16$$

$$\tan \theta = 0.48$$

$$KVAR = 74.6 \times (10201 - 0.48)$$

$$= 111.90$$

$$\approx 112 //$$

$$= \frac{KVAR}{2\pi f V^2}$$

$$= \frac{112}{2 \times \pi \times 50 \times \frac{415^2}{\sqrt{3}}}$$

$$= 2.068 \times 10^{-6} C //$$

QUESTION 2

$$V = 415V$$

$$\text{No. of Pole} = 6$$

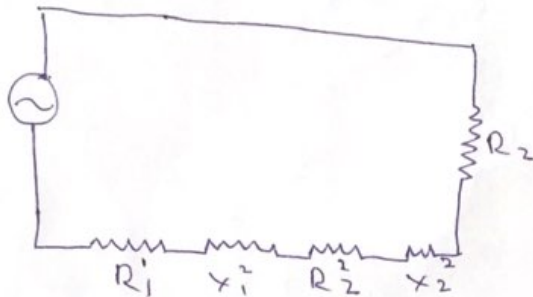
$$f = 50\text{Hz}$$

$$k = \frac{5}{6} = 0.83$$

$$Z_1 = 0.25 + j0.75 \dots \text{stator}$$

$$Z_2 = 1.173 + j0.52 \dots \text{rotor}$$

i)



supply voltage per phase

$$V = \frac{415}{\sqrt{3}} = 239.60V$$

Referring to rotor

$$R_{02} = (R_2 + k^2 R_1)$$

$$= (1.173 + (\frac{5}{6})^2 \times 0.25)$$

$$R_{02} = 1.347\Omega$$

$$X_{02} = (X_2 + k^2 X_1)$$

$$= j(0.52 + (\frac{5}{6})^2 \times 0.75)$$

$$= 1.041$$

$$Z_{02} = R_{02} + X_{02}$$

$$= 1.347 + j1.041$$

$$Z_{02} = \sqrt{1.347^2 + 1.041^2} = 1.7\Omega$$

To find rotor current

$$I_2 = \frac{E_2}{Z_{02}}$$

Recall that $E_2 = kV_1$

$$= 239.6 \times 0.85 = 199.67V$$

$$I_2 = \frac{199.67}{1.7} = 117.45A$$

Question 2

Recall speed constant equation

$$\frac{N_2}{N_1} = \frac{E_{b2}}{E_{b1}}$$

making N_{ac} subject of the formulae

$$N_{ac} = \frac{N_{dc} \times E_{bac}}{E_{bdc}}$$

$$2000 \times \frac{202.52V}{209.5V}$$

$$N_{ac} = \underline{\underline{1933.37 \text{ rpm}}}$$

$$\text{Power factor, } \cos \phi = \frac{E_{bac} + IR}{V}$$

$$= \frac{202.52 + 10}{220}$$

$$= 0.968 \text{ Lagging}$$

$$\text{Torque developed } T_w = E_{bac} \times I$$

$$I_{ac} = \frac{E_{bac} \times I}{\omega}$$

where ω is speed in rad/s

$$\omega = 2\pi n, \text{ where } n \text{ is rev/min}$$

$$I_{ac} = \frac{E_{bac} \times I_c}{2\pi \times \frac{N_{ac}}{60}}$$

$$\frac{202.52 \times 0.7 \times 60}{2\pi \times 1933.37}$$

$$= 0.706 \text{ A}$$

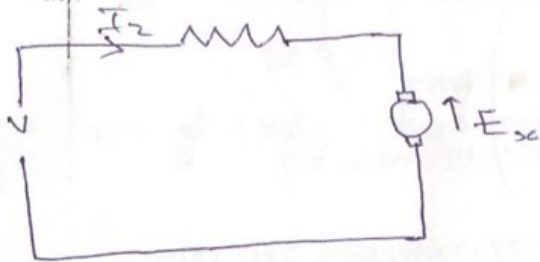
$$0.706 \text{ A} //$$

Question 3

$$f = 50 \text{ Hz}, V = 220 \text{ V} \quad 15 \Omega \text{ and } 0.25 \text{ H}$$

On DC supply

Supply voltage = 220V
current draws, $I = 0.7 \text{ A}$



$$V = E_b + I_2 R = I_2 R + E_b$$

$$V - [I_2 R] = E_b$$

$$E_b = 220 - [0.7 \times 15]$$

$$= \underline{209.5 \text{ V}}$$

Speed on DC

$$N_{dc} = 2000 \text{ rpm}$$

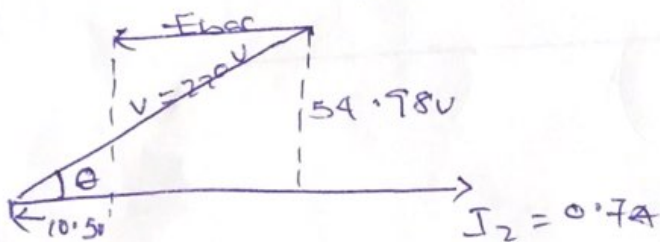
$$\text{Resistance drop} = I_1 R = 0.7 \times 15 = 10.5 \text{ V}$$

$$\text{Reactance voltage drop} = I_2 X_L = 0.7 \times 2\pi f L$$

$$\text{where } X_L = j\omega L = 2\pi f L$$

$$= 0.7 \times 2\pi \times 50 \times 0.25$$

$$= 54.98 \text{ V} //$$



$$E_{bac} = \sqrt{V^2 - (I_1 R)^2} - I_2 R$$

$$= \sqrt{(220)^2 - (10.5)^2} - 10.5$$

$$= 202.52 \text{ V} //$$