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 Mechatronics Engineering

$$C_d \frac{d[V_{out} - V_b]}{dt} - \frac{V_b}{R_2} = 0 \quad \text{--- PI}$$

$$\frac{V_e - V_a}{R_3} + C_d \frac{d[V_b - V_a]}{dt} - \frac{V_a}{R_1} = 0$$

$$\frac{V_{out}}{R_2} + \frac{V_b}{R_1} = 0$$

PI

$$C_d \frac{d[V_{out} - V_b]}{dt} - \frac{V_b}{R_2} = 0$$

$$C_d \frac{d[V_{out} - V_b]}{dt} = \frac{V_b}{R_2}$$

$$\frac{d[V_{out} - V_b]}{dt} = \frac{V_b}{R_2 C_d}$$

Recall

$$\frac{V_e}{R_1} + \frac{V_b}{R_2} = 0$$

$$\frac{V_b}{R_2} = -\frac{V_e}{R_1}$$

$$V_b = -\frac{R_2 V_e}{R_1}$$

$$\int d[V_{out} - V_b] = \int \frac{V_b}{R_2 C} dt$$

$$V_{out} - V_b = \int \frac{V_b}{R_2 C} dt$$

$$V_{out} = \int_0^t \frac{V_b}{R_2 C} dt + V_b$$

$$= \frac{1}{R_2 C} \int_0^t -\frac{R_2}{R_1} V_e dt + \left[-\frac{R_2 V_e}{R_1} \right]$$

$$= \frac{1}{R_2 C} \frac{R}{R_1} \int_0^t V_e dt - \frac{R_2}{R_1} V_e$$

$$= - \left[\frac{R_2}{R_1} V_e + \frac{R_2}{R_1} \frac{1}{R_2 C} \int_0^t [V_e dt] + V_{co} \right]$$

After inserting

$$V_{out} = \frac{R_2}{R_1} V_e + \frac{R_2}{R_1} \frac{1}{R_2 C} \int_0^t V_e dt + V_{co}$$

$$V_{out} = G_P V_e + G_P G_I \int_0^t V_e dt + V_{co}$$

where

$$G_P = \frac{R_2}{R_1} \rightarrow \text{Proportional Gain}$$

$$G_I = \frac{1}{R_2 C} \rightarrow \text{Integral gain}$$

$$\frac{V_e - V_b}{R_2} + C \frac{d}{dt} [V_e - V_b] - \frac{V_a}{R_1} = 0 \quad \text{---} *$$

$$\frac{V_{out}}{R_2} + \frac{V_a}{R_1} = 0 \quad \text{---} **$$

From **

$$V_0 = -\frac{R_1}{R_2} V_{out}$$

Substituting into eqn *

$$\frac{V_e}{R_3} - \left[-\frac{R_1}{R_2} V_{out} \right] \frac{1}{R_3} + C \frac{dV_e}{dt} - C \frac{d}{dt} \left[-\frac{R_1}{R_2} V_{out} \right] - \left[-\frac{R_1}{R_2} V_{out} \right] \frac{1}{R_2} = 0$$

$$\frac{V_e}{R_3} + \frac{R_1}{R_2 R_3} V_{out} + C \frac{dV_e}{dt} + \frac{R_1}{R_2} C \frac{dV_{out}}{dt} + \frac{1}{R_2} V_{out} = 0$$

Multiply all through by R_3

$$V_e + \frac{R_1}{R_2} V_{out} + R_3 C \frac{dV_e}{dt} + \frac{R_1 R_3}{R_2} C \frac{dV_{out}}{dt} + \frac{R_3}{R_2} V_{out} = 0$$

$$\frac{R_1}{R_2} V_{out} + \frac{R_1 R_3}{R_2} C \frac{dV_{out}}{dt} + \frac{R_3}{R_2} V_{out} = -V_e - R_3 C \frac{dV_e}{dt}$$

$$\frac{R_1 V_{out} + R_3 V_{out}}{R_2} + \frac{R_1 R_3}{R_2} C \frac{dV_{out}}{dt} + \frac{R_3 V_{out}}{R_2} = -V_e - \frac{R_3 C dV_e}{dt}$$

$$\frac{R_1 V_{out} + R_3 V_{out}}{R_2} + \frac{R_1 R_3}{R_2} C \frac{dV_{out}}{dt} = -V_e - R_3 C \frac{dV_e}{dt}$$

$$\left[\frac{R_1 + R_3}{R_2} \right] V_{out} + \frac{R_1 R_3}{R_2} C \frac{dV_{out}}{dt} = -V_e - R_3 C \frac{dV_e}{dt}$$

Multiply all through by $\frac{R_2}{R_1 + R_3}$

$$V_{out} + \left[\frac{R_3}{R_1 + R_3} \right] R_3 C \frac{dV_{out}}{dt} = - \left[\frac{R_2}{R_1 + R_3} \right] V_e - \left[\frac{R_2}{R_1 + R_3} \right] R_3 C \frac{dV_e}{dt}$$

After inverting

$$V_{out} + \left[\frac{R_1}{R_2 + R_3} \right] R_3 C \frac{dV_{out}}{dt} = \left(\frac{R_2}{R_1 + R_3} \right) V_c + \left(\frac{R_2}{R_1 + R_3} \right) R_3 C \frac{dV_c}{dt}$$

$$V_{out} = \left(\frac{R_2}{R_1 + R_3} \right) V_c + \left(\frac{R_2}{R_1 + R_3} \right) R_3 C \frac{dV_c}{dt} + V_{cc}$$

$$V_{out} = Q_p V_c + Q_p G_D \frac{dV_c}{dt} + V_0$$

where

$$Q_p = \frac{R_2}{R_1 + R_3} \longrightarrow \text{Proportional Gain}$$

$$G_D = R_3 C \longrightarrow \text{Derivative gain.}$$