

From eq \*\*

$$\left[ V_a = -\frac{R_1}{R_2} V_{out1} \right]$$

rearranging eq \*

$$\frac{V_e - V_a}{R_3} + C \frac{d}{dt} (V_e - V_a) - \frac{V_a}{R_1} = 0$$

taking Laplace transform

$$\frac{V_e(s) - V_a(s)}{R_3} + sC (V_e(s) - V_a(s)) - \frac{V_a(s)}{R_1} = 0$$

Initial conditions going to zero

$$V_e(s) \left( \frac{1}{R_3} + sC \right) = V_a(s) \left( \frac{1}{R_1} + \frac{1}{R_2} + sC \right)$$

Recall,  $V_a = -\frac{R_1}{R_2} V_{out1}$

$$V_e(s) \left( \frac{1}{R_3} + sC \right) = -\frac{R_1}{R_2} V_{out1} \left( \frac{1}{R_1} + \frac{1}{R_2} + sC \right)$$

taking Lcm

$$\frac{V_e}{R_1} + \frac{V_b}{R_2} = 0 \quad \text{--- (1)}$$

$$C \frac{d}{dt} (V_{out1} - V_b) - \frac{V_b}{R_2} = 0 \quad \text{--- (2)}$$

from eq (1)

$$\frac{V_b}{R_2} = -\frac{V_e}{R_1}$$

$$V_b = -\frac{R_2 V_e}{R_1}$$

taking laplace transform of eq (2)

$$sC (V_{out1}(s) - V_b(s)) - \frac{V_b(s)}{R_2} = 0$$

$$sC V_{out1}(s) = \frac{V_b(s)}{R_2} + \frac{V_b(s)}{R_2}$$

$$sC V_{out1}(s) = V_b(s) \left( sC + \frac{1}{R_2} \right)$$

recall:  $V_b = -\frac{R_2}{R_1} V_e$

$$sC V_{out1}(s) = -\frac{R_2}{R_1} V_e(s) \left( sC + \frac{1}{R_2} \right)$$

From the Inverting circuit

$$V_{out} \underline{1} - V_{out} + V_0$$

$$\therefore -(-V_{out}cs + V_0) = V_e \frac{(R_2 + sCR_2R_3)}{R_1 + R_3}$$

$$V_{out}(cs) - V_0 = \frac{V_e cs R_2}{R_1 + R_3} + \frac{sCR_2R_3 V_e cs}{R_1 + R_3}$$

$$V_{out}(s) = \frac{R_2}{R_1 + R_3} V_e(s) + \frac{R_2}{R_1 + R_3} R_3 (s V_e(s) + V_0)$$

taking Inverse Laplace

$$V_{out} = \frac{R_2}{R_1 + R_3} V_e + \frac{R_2}{R_1 + R_3} R_3 c \frac{dV_e}{dt} + V_0$$

$$\left[ V_{out} = G_p V_e + G_p G_D \frac{dV_e}{dt} + V_0 \right]$$

$$\text{where } G_p = \frac{R_2}{R_1 + R_3}$$

$$G_D = R_3 c$$

Urosen Edwin

16/ENG04/060

ELECT/ELECT

## QUESTION 1

PI Controller

$$V_a = 0$$

$$I_1 + I_2 = 0 \quad \text{--- (1)}$$

$$I_3 - I_2 = 0 \quad \text{--- (2)}$$

Current through the capacitor

$$I_c = \frac{C \, dV_c}{dt}$$

$$I_1 = \frac{V_c - V_a}{R_1} \quad (V_a = 0)$$

$$I_2 = \frac{V_0 - V_a}{R_2} \quad (V_a = 0)$$

$$I_3 = \frac{V_b}{R_2} = V_b / R_2$$

$$I_3 = C \frac{d}{dt} (V_{out} - V_b)$$

Sub into eq (1) & eq (2)

## QUESTION 2

PD Controller

$$I_1 + I_2 = I_3 \quad \text{--- (1)}$$

$$I_3 + I_4 = \quad \text{--- (2)}$$

$$I_1 = \frac{V_e - V_a}{R_3}$$

$$I_2 = C \frac{d}{dt} (V_e - V_a)$$

$$I_3 = \frac{V_a - V_b}{R_1} \quad (V_b = 0) = \frac{V_a}{R_1}$$

$$I_4 = \frac{V_{out1} - V_b}{R_2} \quad (V_b = 0) = \frac{V_{out1}}{R_2}$$

$$R = \frac{R_1 R_3}{R_1 + R_3} \quad \text{--- effective resistance}$$

Sub into eq(1) & eq(2)

$$\frac{V_e - V_a}{R_3} + C \frac{d}{dt} (V_e - V_a) = \frac{V_a}{R} \quad \text{--- *}$$

$$\frac{V_b}{R_1} + \frac{V_{out1}}{R_2} = 0 \quad \text{--- **}$$