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ELECTRICAL AND ELECTRONICS ENGINEERING

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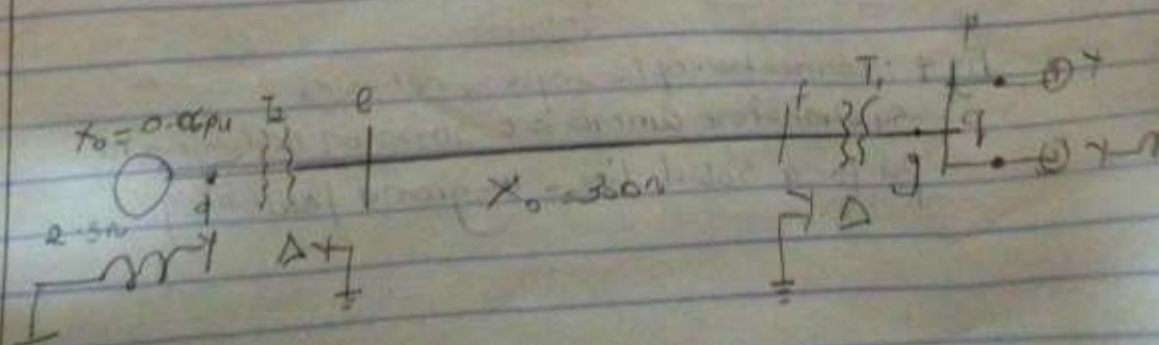
Assignment:

A 35MVA, 11KV three phase generator has a subtransient reactance of 20%. The generator supplies two motors over a transmission line with transformers at both ends as shown in one-line diagram. The motors have rated inputs of 15 and 7.5 MVA, both 11KV with 25% subtransient reactance. The three-phase transformers are both rated 30MVA, 10.5/11KV connection $\Delta-Y$ with leakage of 6% each. The series reactance of the line is 100 Ohms.

(a) Draw the positive, negative and the zero sequence networks of the system with reactances marked in per unit.

(b) If the motors are loaded to draw 15 and 7.5 MW at 10KV, 0.8 leading power factor before the occurrence of a solid LG fault at bus 2 and the pre-fault current is neglected, calculate the fault current and subtransient current in all parts of the system.

(c) Assume that the negative sequence reactance of each machine is equal to the subtransient reactance. Omit resistances, select generator rating as base in the generator circuit.



Solution

A base of 25 MVA, 11 kV in the generator circuit requires 25 MVA base in all other circuits and the following voltage bases.

$$\text{Transmission line voltage base} = \frac{11 \times 121}{10.8} = \underline{123.24 \text{ kV}}$$

$$\text{Motor voltage base} = \frac{123.2 \times 10.8}{121} = \text{11 kV} = \underline{11 \text{ kV}}$$

The reactances for transformers, transmission line and motors converted to pu values with their bases respectively

$$\text{Transformer reactance} = \frac{0.1 \times 25}{30} \times \left(\frac{10.8}{11}\right)^2 = \underline{j0.0805 \text{ pu}}$$

$$\text{Transmission line reactance} = \frac{100 \times 0.5}{(123.2)^2} = \underline{j0.164 \text{ pu}}$$

$$\text{Reactance of motor 1} = \frac{0.25 \times 25}{15} \times \left(\frac{10}{11}\right)^2 = \underline{j0.343 \text{ pu}}$$

$$\text{Reactance of motor 2} = \frac{0.25 \times 25}{7.5} \times \left(\frac{10}{11}\right)^2 = \underline{j0.69 \text{ pu}}$$

The positive sequence network is shown below

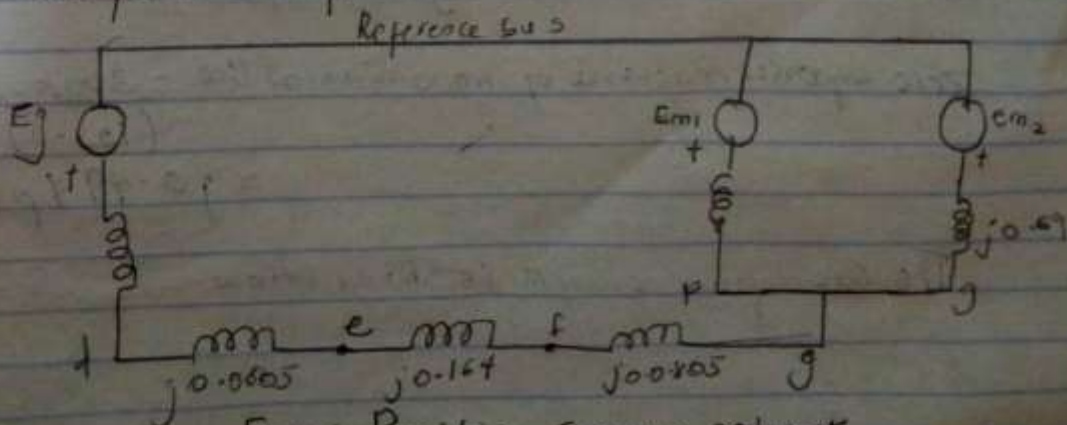


Fig 1: Positive sequence network

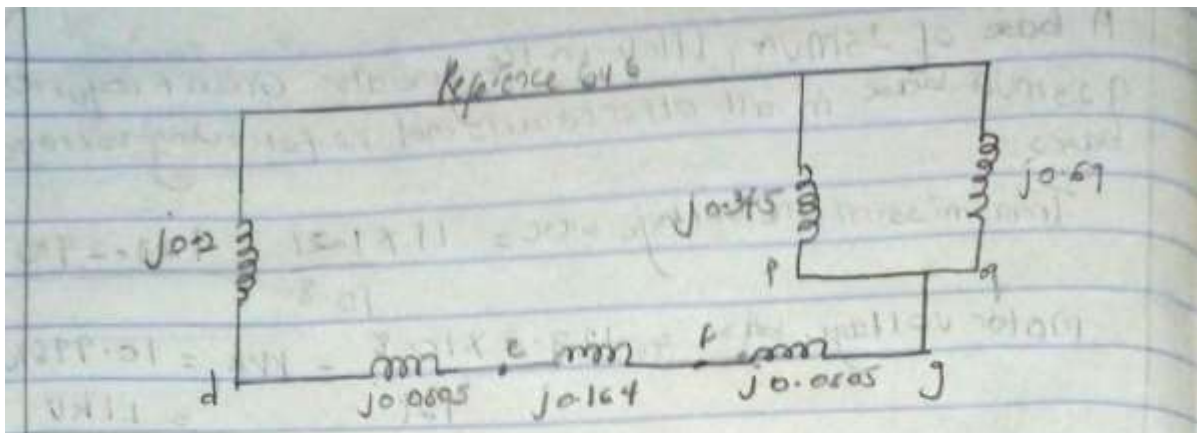


Figure 2: Negative sequence network

Since all the negative sequence reactances of the system are equal to the positive sequence reactances, the negative sequence network is identical to the positive sequence network.

$$\text{Zero sequence reactance of motor 2} = 0.06 \times \frac{25}{7.5} \times \left(\frac{10}{11} \right)^2$$

$$\text{Reactance of current limiting reactor} = \frac{2.5 \times 25}{(11)^2} = j0.516 \text{ pu}$$

$$\text{Reactance of current limiting reactor included in zero sequence network} = 3 \times 0.516 = j1.548 \text{ pu}$$

$$\text{Zero sequence reactance of transmission line} = \frac{300 \times 25}{(123.2)^2} = j0.494 \text{ pu}$$

The zero sequence network is shown below

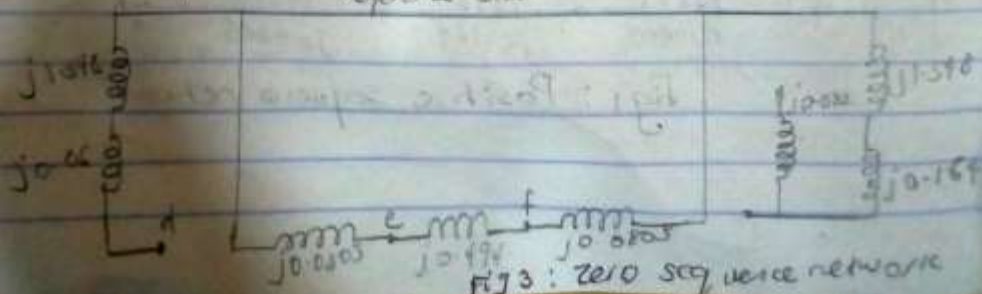


Fig 3: Zero sequence network

fault at bus g

Solution - The sequence networks are connected below to give a solid LLr
 If pre-fault currents are neglected
 $E_g'' = E_{m1}'' = E_{m2}'' = V_f^0$ (pre-fault voltage at g)

$$\frac{10}{11} = 0.909 \text{ pu}$$

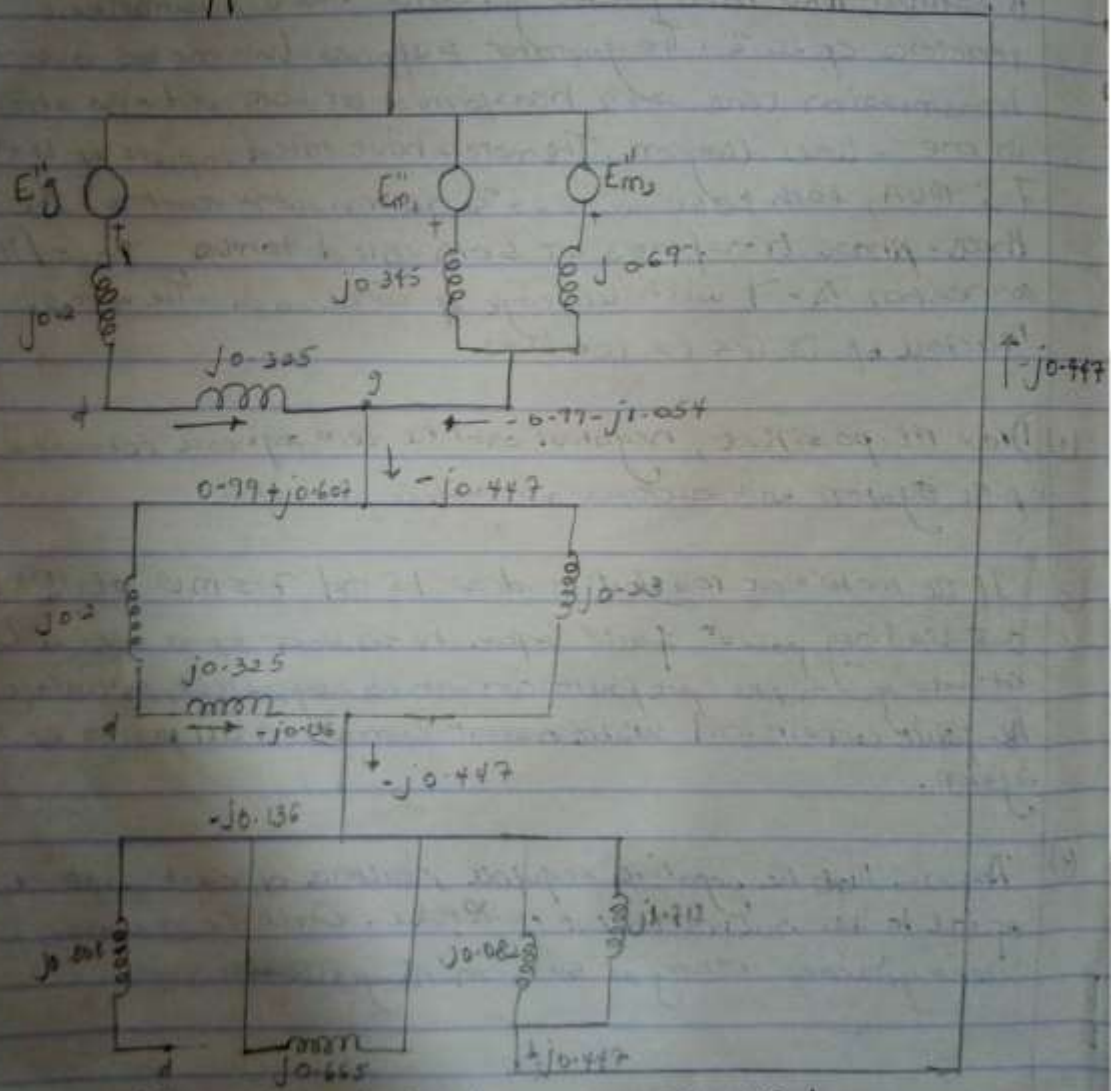
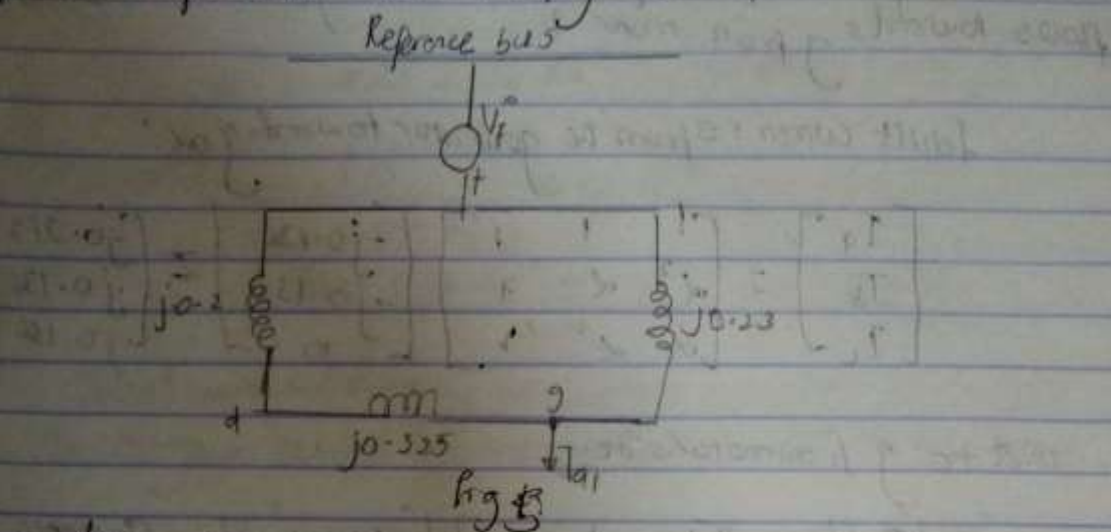


Fig 4: Connection of the sequence networks.
 Subtransient currents are shown on the diagram in pu for a solid line-to-ground fault at g.

The positive sequence network can be easily replaced by its Thevenin equivalent shown in fig 5



Now calculating Z_1

$$Z_1 = \frac{j0.525 \times j0.23}{j0.755} = j0.16 \text{ pu}$$

$$Z_2 = Z_1 = j0.16 \text{ pu}$$

From the sequence network connection

$$I_{a1} = \frac{V_f^0}{Z_1 + Z_2 + Z_0}$$

$$\frac{0.709}{j2.032} = -j0.447 \text{ pu}$$

$$I_{a0} = I_{a2} = I_{a1} = -j0.447 \text{ pu}$$

$$\text{Fault current} = 3I_{a0} = 3 \times (-j0.447) = -j1.341 \text{ pu}$$

The component of I_{a1} flowing towards g from the generator side

$$-j0.447 \times \frac{j0.23}{j0.755} = -j0.136 \text{ pu}$$

and its component flowing towards g from the motor side is

$$I_{a1} - j0.136 = -j0.447 + j0.136 = -j0.311 \text{ pu}$$

Similarly the component I_{a2} from the generator side is $-j0.136 \text{ pu}$ and its component from the motor side is $-j0.311$. All of I_{a3} flows towards g from motor 2.

Fault current I_s from the generator towards g is:

$$\begin{bmatrix} I_a \\ I_b \\ I_c \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ \alpha^2 & \alpha & 1 \\ \alpha & \alpha^2 & 1 \end{bmatrix} \begin{bmatrix} -j0.136 \\ -j0.136 \\ 0 \end{bmatrix} = \begin{bmatrix} j0.272 \\ j0.136 \\ j0.136 \end{bmatrix} \text{ pu}$$

and to g from motor 2 is:

$$\begin{bmatrix} I_a \\ I_b \\ I_c \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ \alpha^2 & \alpha & 1 \\ \alpha & \alpha^2 & 1 \end{bmatrix} \begin{bmatrix} -j0.311 \\ -j0.311 \\ -j0.447 \end{bmatrix} = \begin{bmatrix} -j1.069 \\ -j0.136 \\ -j0.136 \end{bmatrix} \text{ pu}$$

The positive and negative sequence components of the transmission currents are shifted -90° and $+90^\circ$ respectively, from the corresponding components on the generator side of T_2 , i.e.

$$\text{Positive sequence current} = -j(-j0.136) = -0.136 \text{ pu}$$

$$\text{Negative sequence current} = j(-j0.136) = 0.136 \text{ pu}$$

$$\text{Zero sequence current} = 0$$

\therefore There are no zero sequence currents on the transmission line from figure 3

Line a current on the transmission line

$$I_a = -0.136 + 0.136 + 0 = 0$$

I_b and I_c can be similarly calculated

Calculating the voltages behind subtransient reactances to be used if the load currents are assumed to be zero.

The per unit motor currents are:

$$\text{Motor 1: } \frac{15}{25 \times 0.909 \times 0.8} \angle 36.86^\circ$$

$$= 0.825 \angle 36.86^\circ = 0.66 + j0.495 \text{ pu}$$

$$\text{Motor 2: } \frac{7.5}{25 \times 0.909 \times 0.8} \angle 36.86^\circ$$

$$= 0.4125 \angle 36.86^\circ = 0.33 + j0.34 \text{ pu}$$

Total current drawn by both motors = $0.99 + j0.843 \text{ pu}$
The voltages behind subtransient reactances are calculated:

$$\begin{aligned} \text{Motor 1: } E''_{m1} &= 0.909 - j0.345 \times 0.825 \angle 36.86^\circ \\ &= 1.08 - j0.228 = 1.104 \angle -11.92^\circ \text{ pu} \end{aligned}$$

$$\begin{aligned} \text{Motor 2: } E''_{m2} &= 0.909 - j0.69 \times 0.4125 \angle 36.86^\circ \\ &= 1.08 - j0.228 \\ &= 1.104 \angle -11.92^\circ \text{ pu} \end{aligned}$$

$$\begin{aligned} \text{Generator: } E''_g &= 0.909 + j0.525 \times 1.2375 \angle 36.86^\circ \\ &= 0.52 + j0.52 = 0.735 \angle 45^\circ \text{ pu} \end{aligned}$$

It may be noted with the voltages behind subtransient reactances, the Thevenin circuit will still be the same as that of Fig 5.
 \therefore In calculating fault currents taking no account of fault loading condition, there's no need to calculate E''_{m1} , E''_{m2} and E''_g . Using Thevenin equivalent approach, there's a need to calculate currents caused by fault to which the load can be added.

Thus, the actual value of positive sequence current from the generator towards fault is:

$$\begin{aligned} &0.99 + j0.743 - j0.136 \\ &= 0.99 + j0.607 \end{aligned}$$

and the actual value of positive sequence current from the motors to the fault is

$$-0.99 - j0.743 - j0.311 = -0.99 - j1.054$$

Since the zero sequence reactance is large, load current is comparable with the fault current. In actual situations, this will be the case, so that it is normal practice to neglect load current without causing an appreciable error.