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Transfer Function

- Block Diagram & Signal Flow Diagram

By

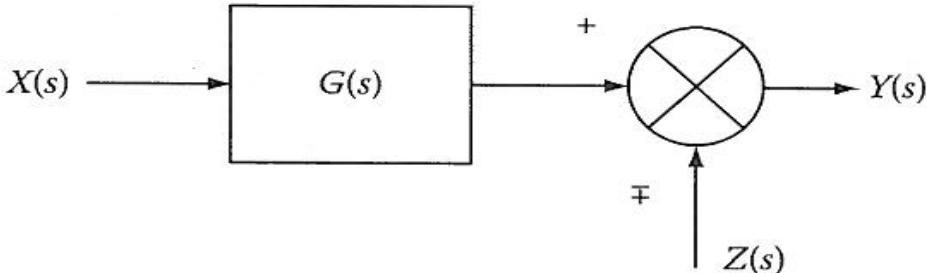
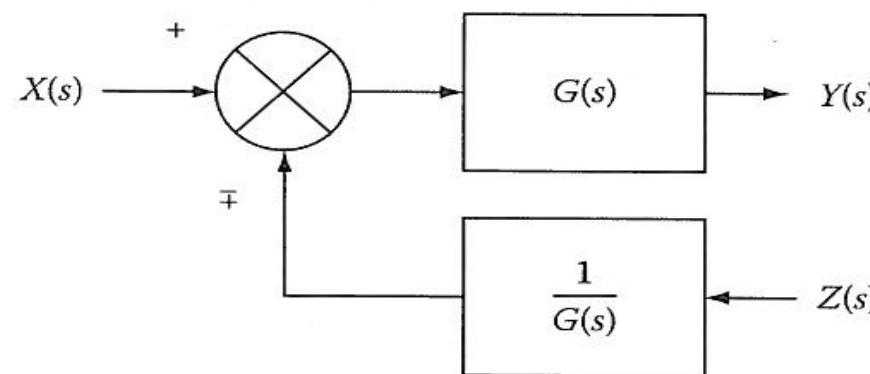
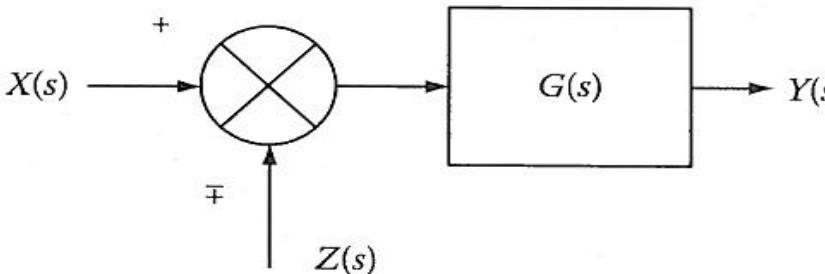
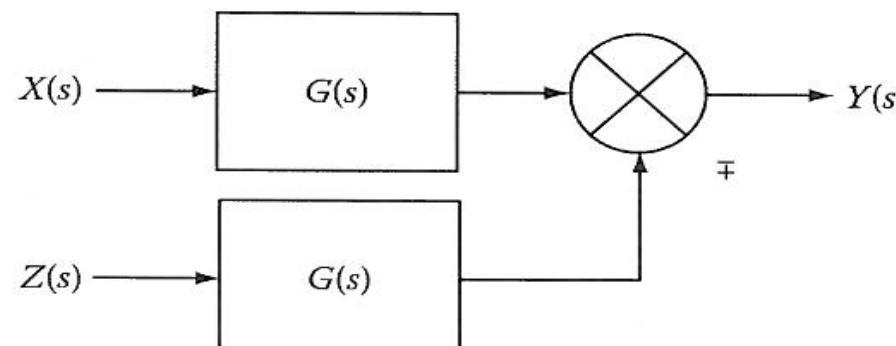
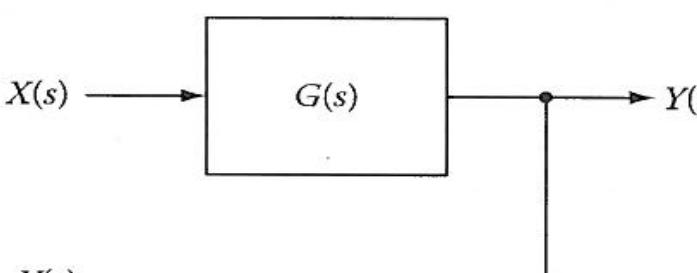
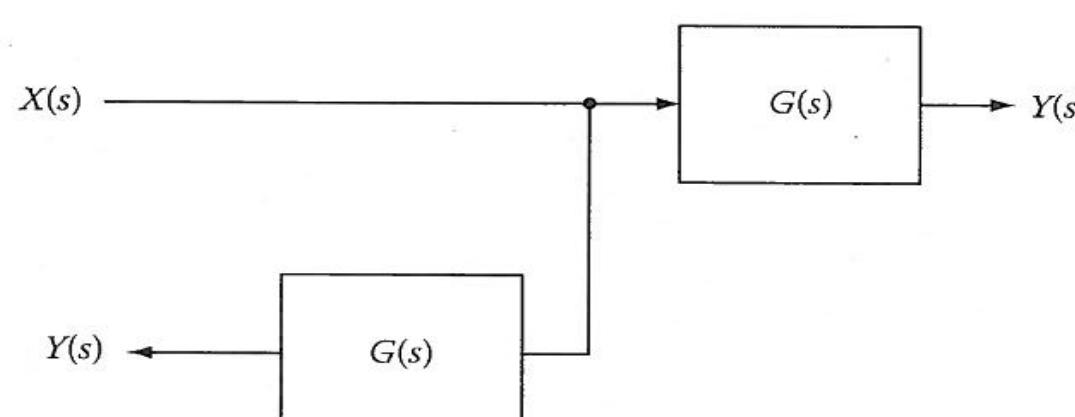
Dr. Femi Onibonoje

Block Diagram (Cont'd)

Block Diagram Transformations

| S/N | Initial Diagram | Equivalent Diagram |
|-----|---|---|
| 1. | <p>Initial Diagram:</p> <pre> graph LR X1[X(s)] --> G1[G1(s)] G1 --> G2[G2(s)] G2 --> ...[] ... --> Gn[Gn(s)] Gn --> Y1[Y(s)] </pre> | <p>Equivalent Diagram:</p> <pre> graph LR X2[X(s)] --> G3[G1(s)G2(s)G3(s)...Gn(s)] G3 --> Y2[Y(s)] </pre> |
| 2. | <p>Initial Diagram:</p> <pre> graph LR X3[X(s)] --> G1[G1(s)] G1 --> Sum(()) G2[G2(s)] --> NegIn(()) NegIn --> Sum Sum --> Y3[Y(s)] </pre> | <p>Equivalent Diagram:</p> <pre> graph LR X4[X(s)] --> G4[G1(s) ± G2(s)] G4 --> Y4[Y(s)] </pre> |
| 3. | <p>Initial Diagram:</p> <pre> graph LR X5[X(s)] --> Sum2(()) Sum2 --> G5[G(s)] G5 --> Y5[Y(s)] H[H(s)] --> NegIn2(()) NegIn2 --> Sum2 </pre> | <p>Equivalent Diagram:</p> <pre> graph LR X6[X(s)] --> G6["G(s) / 1 ± G(s)H(s)"] G6 --> Y6[Y(s)] </pre> |

Block Diagram Transformations

| S/N | Initial Diagram | Equivalent Diagram |
|-----|--|--|
| 4. |  |  |
| 5. |  |  |
| 6. |  |  |

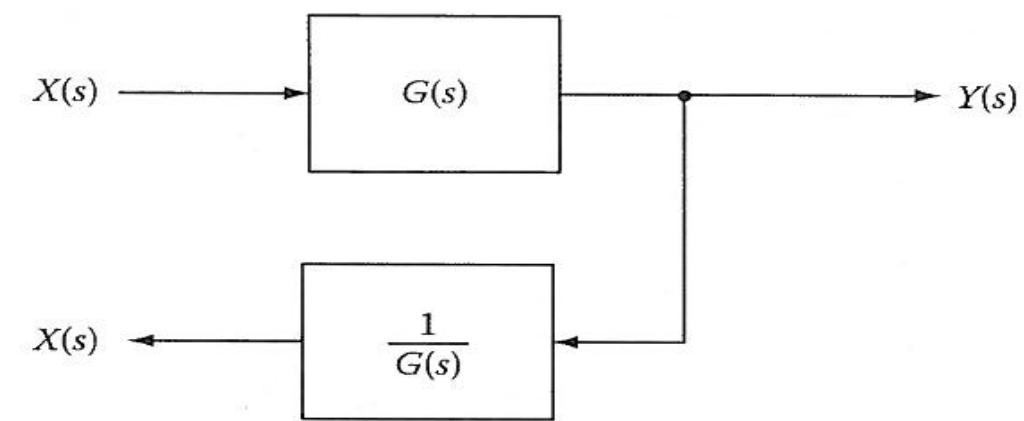
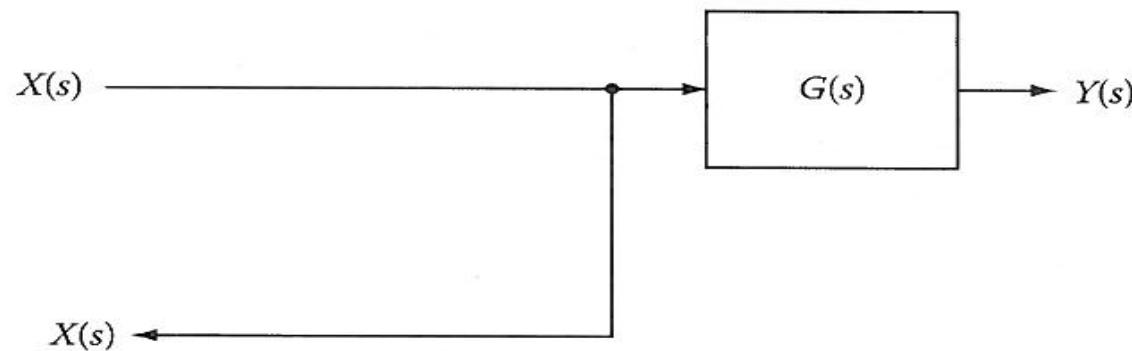
Block Diagram Transformations

S/N

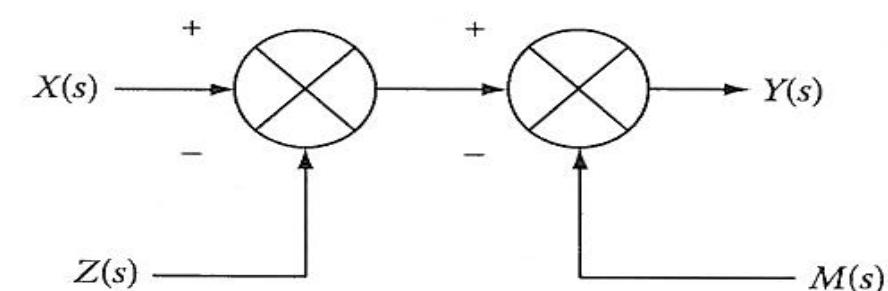
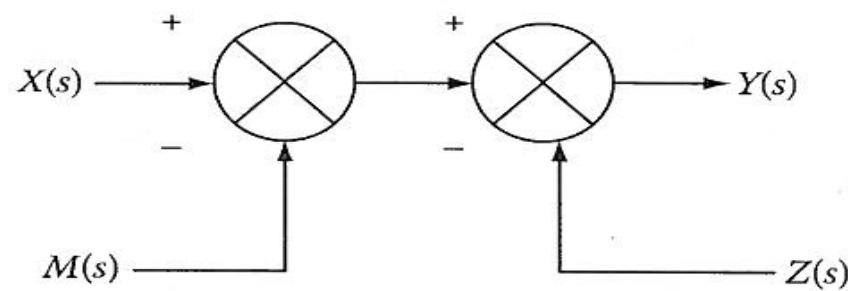
Initial Diagram

Equivalent Diagram

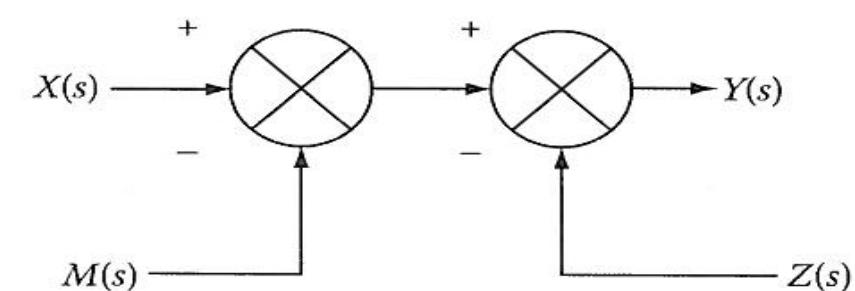
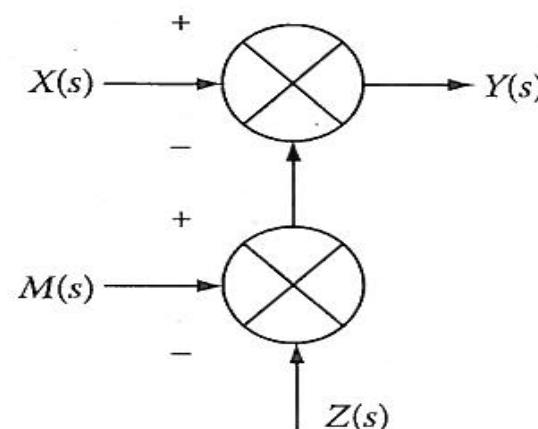
7.



8.



9.

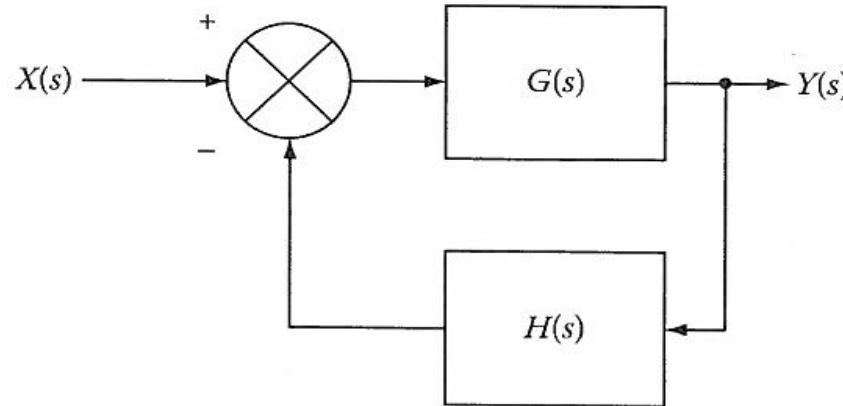


Block Diagram Transformations

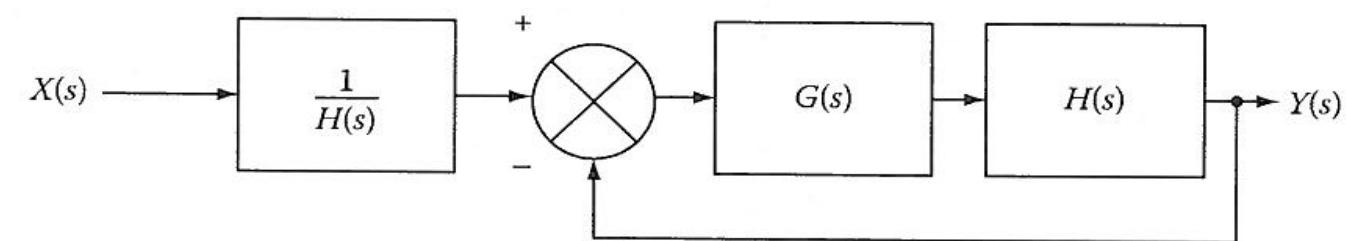
S/N

Initial Diagram

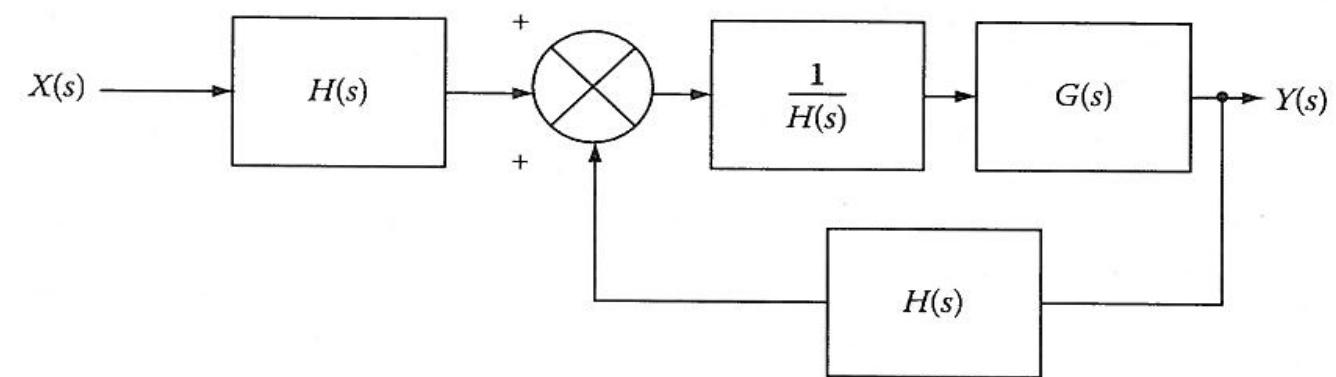
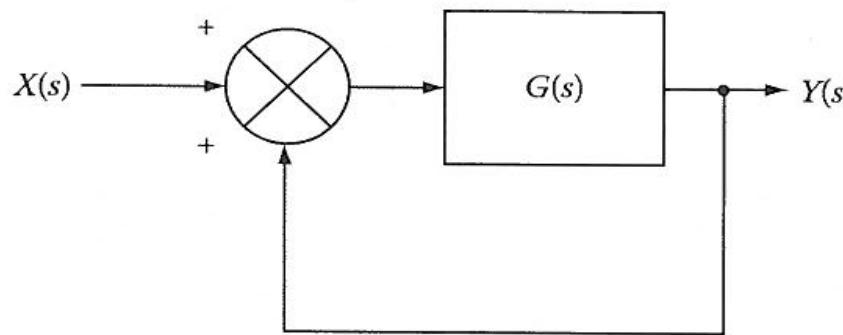
10.



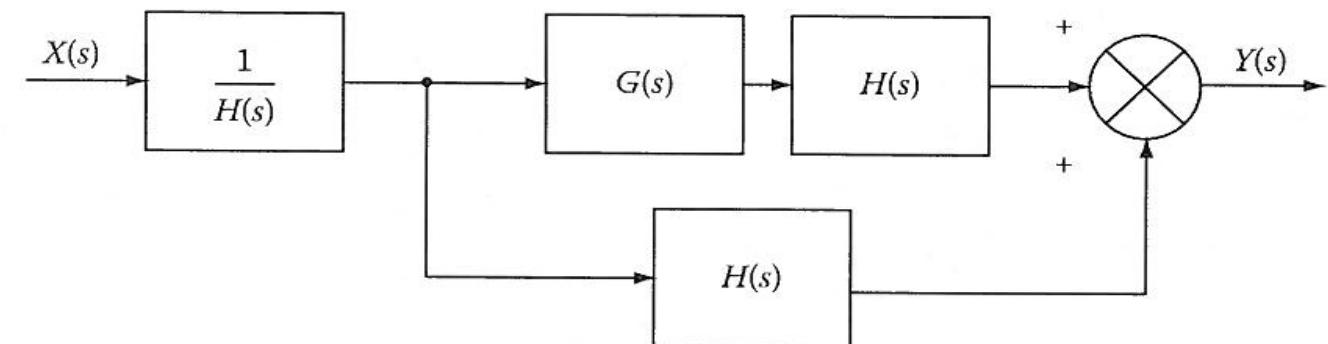
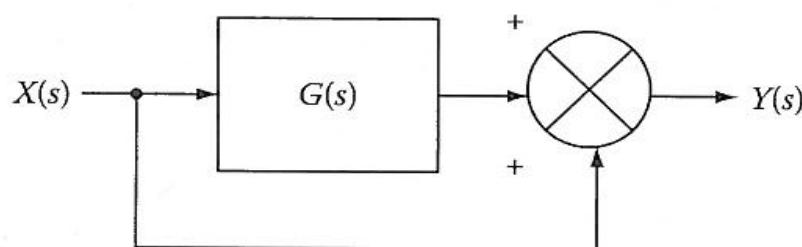
Equivalent Diagram



11.



12.



Signal Flow Diagram/Graph (SFG)

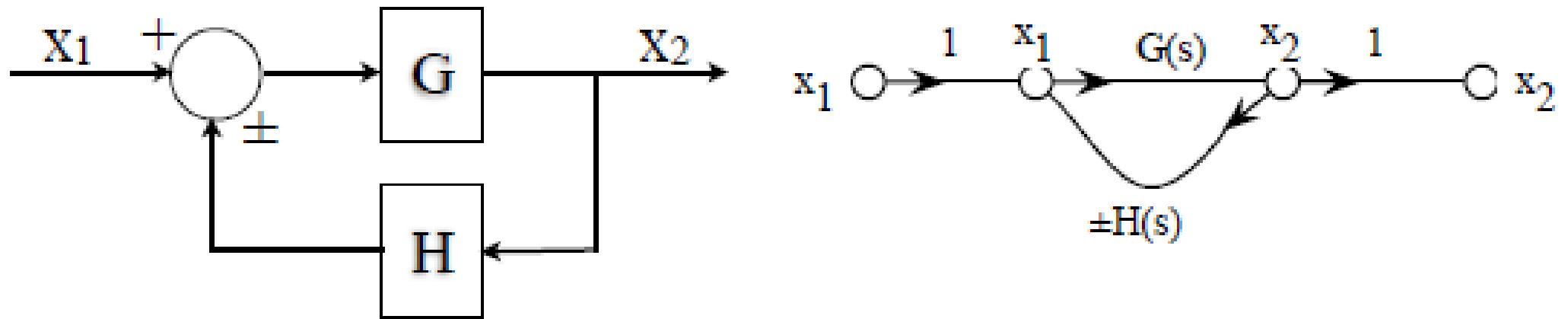
Signal Flow Graphs

- Alternative to block diagrams
- Do not require iterative reduction to find transfer functions (using Mason's gain rule)
- Can be used to find the transfer function between any two variables (not just the input and output).

Definitions

- **Input:** (source) has only outgoing branches
- **Output:** (sink) has only incoming branches
- **Path:** (from node i to node j) has no loops.
- **Forward-path:** path connecting a source to a sink
- **Loop:** A simple graph cycle.
- **Path Gain:** Product of gains on path edges
- **Loop Gain:** Product of gains on loop
- **Non-touching Loops:** Loops that have no vertex in common (and, therefore, no edge.)

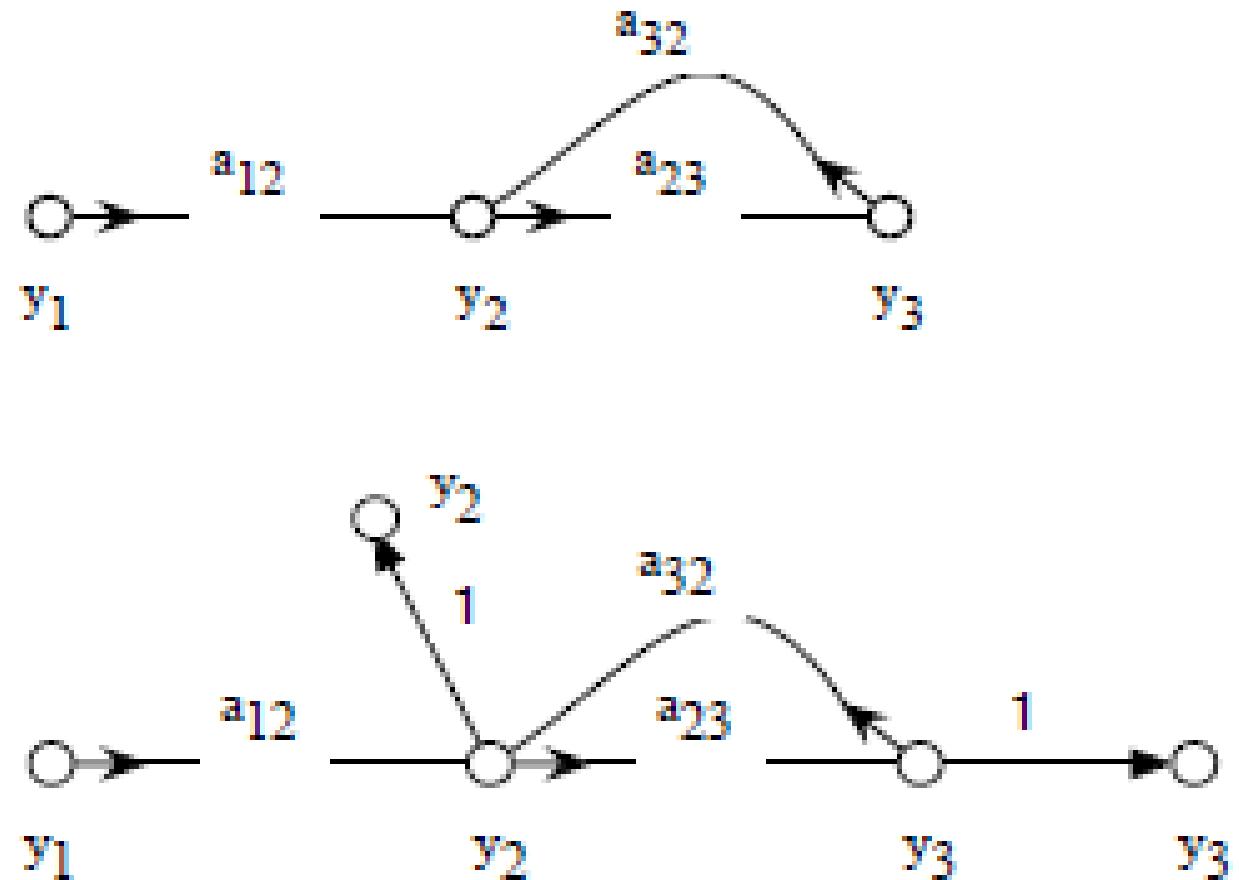
Block Diagram Vs. SFG



- Blocks \Rightarrow Edges (aka branches)
(representing transfer functions)
- Edges + junctions \Rightarrow Vertices (aka nodes)
(representing variables)

Input/Output

- Input (source) has only outgoing edges
- Output (sink) has only incoming edges
- any variable can be made into an output by adding a sink with “1” edge



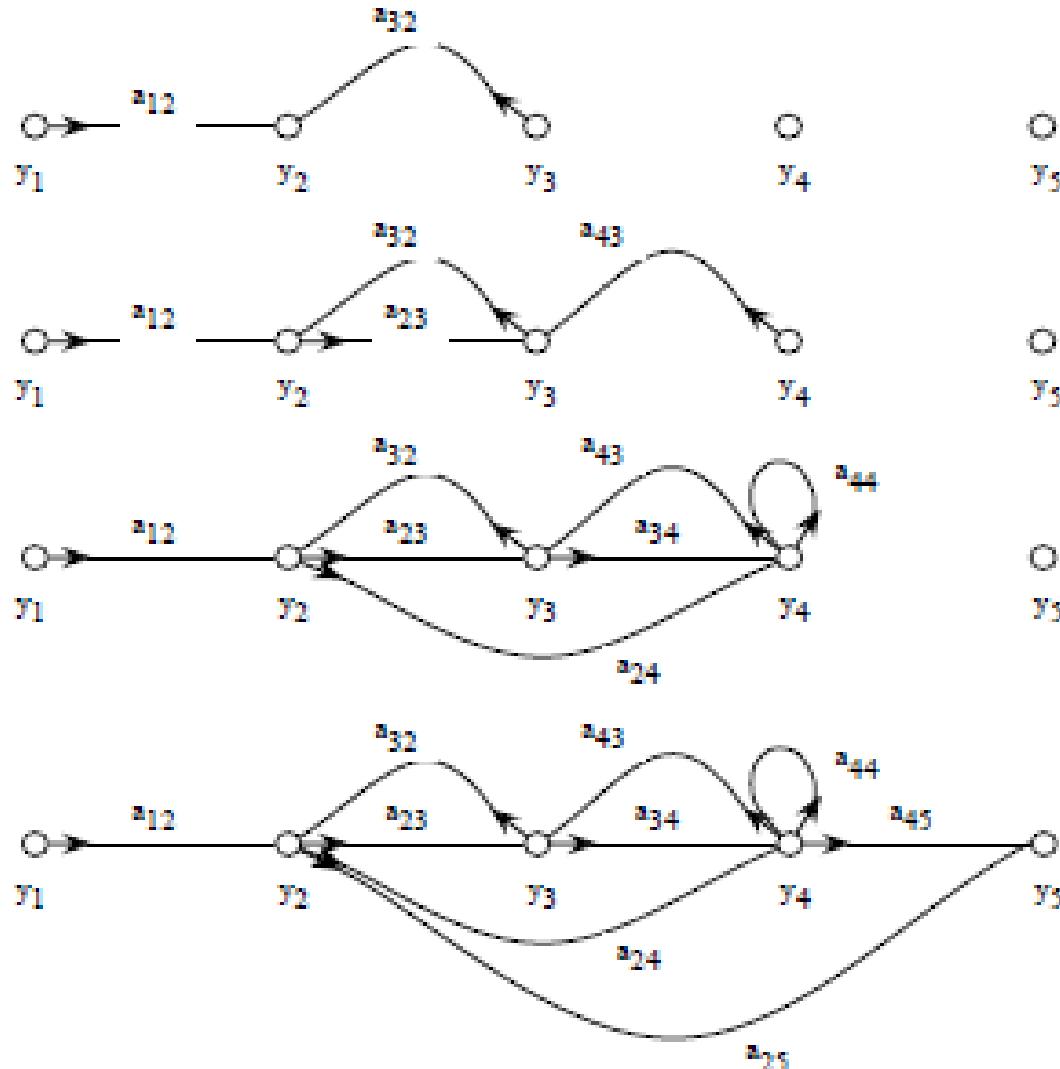
Example 1

$$y_2 = a_{12}y_1 + a_{32}y_3$$

$$y_3 = a_{23}y_2 + a_{43}y_4$$

$$y_4 = a_{24}y_2 + a_{34}y_3 + a_{44}y_4$$

$$y_5 = a_{25}y_2 + a_{45}y_4$$



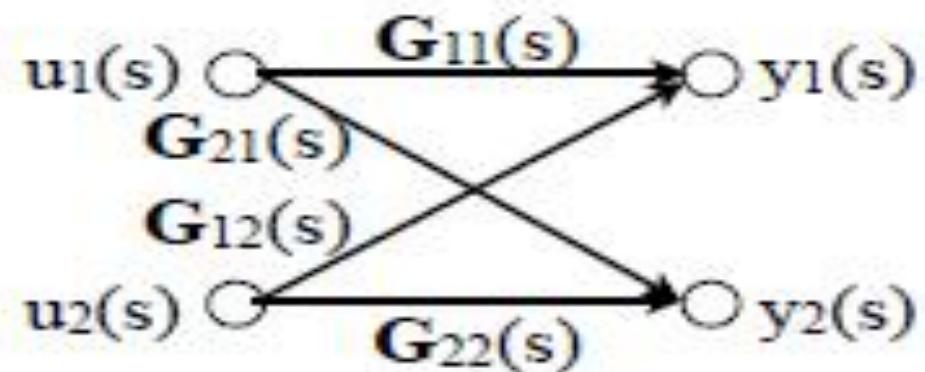
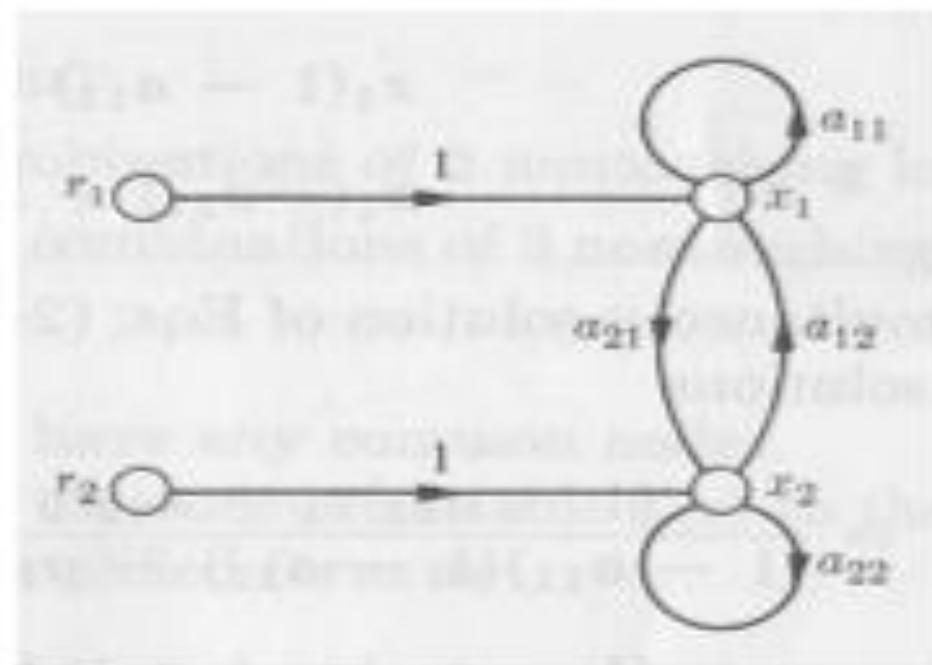
Example 2

- $\mathbf{x} = \mathbf{Ax} + \mathbf{r}$

$$x_1 = a_{11}x_1 + a_{12}x_2 + r_1$$

$$x_2 = a_{21}x_1 + a_{22}x_2 + r_2$$

- $\mathbf{y}(s) = \mathbf{G}(s)\mathbf{u}(s)$



Mason's Gain Formula

Given an SFG, a source and a sink, N forward paths between them and K loops, the gain (transfer function) between the source-sink pair is

$$T_{ij} = \frac{\sum P_k \Delta_k}{\Delta}$$

P_k is the gain of path k, Δ is the “graph determinant”:

$$\Delta = 1 - \sum(\text{all loop gains})$$

$$+ \sum(\text{products of non-touching-loop gain pairs})$$

$$- \sum(\text{products of non-touching-loop gain triplets})$$

$$+ \dots$$

$\Delta_k = \Delta$ of the SFG after removal of the k^{th} forward path

Mason's Rule for Simple Feedback loop

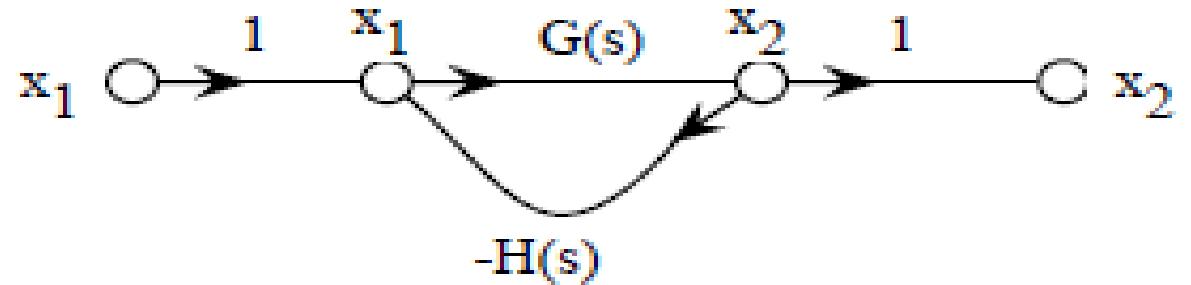
$$P_1 = G(s)$$

$$L_1 = -G(s)H(s)$$

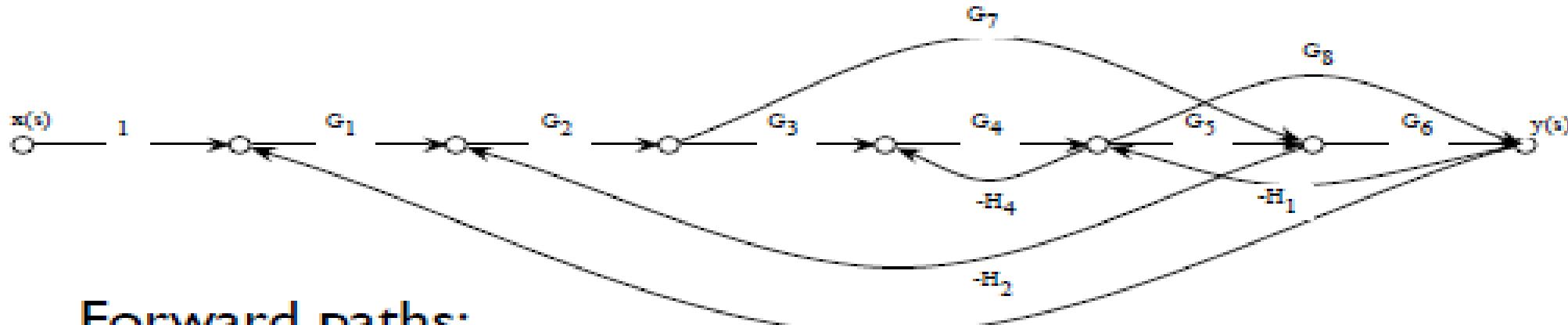
$$\Delta = 1 - (-G(s)H(s))$$

$$\Delta_1 = 1$$

$$T(s) = \frac{P_1 \Delta_1}{\Delta} = \frac{G(s)}{\Delta} = \frac{G(s)}{1+G(s)H(s)}$$



Example 3



Forward paths:

$$P_1 = G_1 G_2 G_3 G_4 G_5 G_6 \quad P_2 = G_1 G_2 G_7 G_6 \quad P_3 = G_1 G_2 G_3 G_4 G_8$$

Feedback loops:

$$L_1 = -G_2 G_3 G_4 G_5 H_2 \quad L_2 = -G_5 G_6 H_1 \quad L_3 = -G_8 H_1$$

$$L_4 = -G_7 H_2 G_2 \quad L_5 = -G_4 H_4 \quad L_6 = -G_1 G_2 G_3 G_4 G_5 G_6 H_3$$

$$L_7 = -G_1 G_2 G_7 G_6 H_3 \quad L_8 = -G_1 G_2 G_3 G_4 G_8 H_3$$

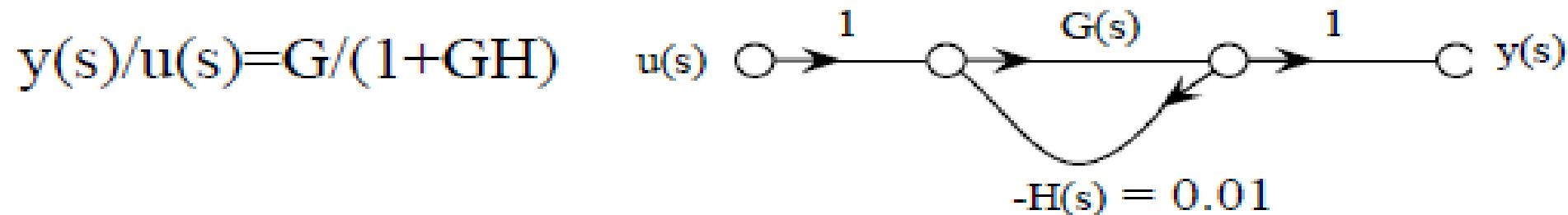
Loops $\{3,4\}$, $\{4,5\}$ and $\{5,7\}$ don't touch

$$\Delta = 1 - (L_1 + L_2 + L_3 + L_4 + L_5 + L_6 + L_7 + L_8) + (L_3 L_4 + L_4 L_5 + L_5 L_7)$$

$$\Delta_1 = \Delta_3 = 1 \quad , \quad \Delta_2 = 1 - L_5 = 1 - G_4 H_4$$

$$T(s) = \frac{y(s)}{x(s)} = \frac{P_1 + P_2 \Delta_2 + P_3}{\Delta}$$

A Feedback Loop Reduces Sensitivity To Plant Variations



$$G=10000$$

$$y(s)/u(s)=10000/(1+10000*0.01)=99.01$$

$$G=20000$$

$$y(s)/u(s)=20000/(1+20000*0.01)=99.50$$